

ON A STAGE OF A NUMERICAL ALGORITHM FOR A
 TIMOSHENKO TYPE NONLINEAR EQUATION

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ABSTRACT. An initial boundary value problem for a differential equation describing the beam oscillation is considered. As a result of application of the variational method and a difference scheme, a nonlinear system of equations is obtained, which is solved by iteration. The convergence conditions and the error estimate of the iteration method are obtained.

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1. STATEMENT OF THE PROBLEM

Let us consider the initial boundary value problem

$$u_{tt}(x, t) + \delta u_t(x, t) + \gamma u_{xxxxt}(x, t) + \alpha u_{xxxx}(x, t) -$$

$$- \left(\beta + \rho \int_0^L u_x^2(x, t) dx \right) u_{xx}(x, t) -$$

$$- \sigma \left(\int_0^L u_x(x, t) u_{xt}(x, t) dx \right) u_{xx}(x, t) = 0, \quad 0 < x < L, \quad 0 < t \leq T, \quad (1)$$

$$u(x, 0) = u^0(x), \quad u_t(x, 0) = u^1(x), \quad (2)$$

$$u(0, t) = u(L, t) = 0, \quad u_{xx}(0, t) = u_{xx}(L, t) = 0,$$

where $\alpha, \gamma, \rho, \sigma, \beta$ and δ are the given constants, among which the first four are positive numbers, while $u^0(x) \in W_2^2(0, L)$ and $u^1(x) \in L_2(0, L)$ are given functions such that $u_0(0) = u_1(0) = u_0(L) = u_1(L) = 0$. In the sequel it is assumed that the inequality $|\delta| < \gamma(\frac{\pi}{L})^4$ is fulfilled when $\delta < 0$, and $\alpha(\frac{\pi}{L})^2 > |\beta|$ holds when $\beta < 0$. It will be assumed that there exists a solution $u(x, t) \in W_2^2((0, L) \times (0, T))$ of problem (1), (2).

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Equation (1) obtained by J. Ball [1] using the Timoshenko theory describes the vibration of the beam. Moreover, in [1], the existence of a global solution for (1) is shown. The problem of construction of an approximate solution for this equation is investigated in [2], [3], [4].

Here we consider a numerical solution algorithm for problem (1), (2).

2. ALGORITHM

a. *Galerkin method.* A solution of the problem (1), (2) will be sought in the form of a finite sum

$$u_n(x, t) = \sum_{i=1}^n u_{ni}(t) \sin \frac{i\pi x}{L}, \quad (3)$$

where the coefficients $u_{ni}(t)$ are defined by the Galerkin method from the system of ordinary differential equations

$$\begin{aligned} u''_{ni}(t) + \left(\delta + \gamma \left(\frac{i\pi}{L} \right)^4 \right) u'_{ni}(t) + \left[\alpha \left(\frac{i\pi}{L} \right)^4 + \right. \\ \left. + \left(\frac{i\pi}{L} \right)^2 \left(\beta + \rho \frac{L}{2} \sum_{j=1}^n \left(\frac{j\pi}{L} \right)^2 u_{nj}^2(t) + \right. \right. \\ \left. \left. + \sigma \frac{L}{2} \sum_{j=1}^n \left(\frac{j\pi}{L} \right)^2 u_{nj}(t) u'_{nj}(t) \right) \right] u_{ni}(t) = 0, \quad i = 1, 2, \dots, n, \quad (4) \end{aligned}$$

with the initial conditions

$$u_{ni}(0) = a_i^0, \quad u'_{ni}(0) = a_i^1, \quad i = 1, 2, \dots, n, \quad (5)$$

where

$$a_i^p = \frac{2}{L} \int_0^L u^p(x) \sin \frac{i\pi x}{L} dx, \quad p = 0, 1, \quad i = 1, 2, \dots, n.$$

The convergence of the Galerkin method for equation (1) and an equation with similar nonlinearity is studied in [6] and [7].

b. *Difference scheme.* Let us introduce the notation

$$y_{ni}(t) = u'_{ni}(t), \quad z_{ni}(t) = \frac{i\pi}{L} u_{ni}(t), \quad i = 1, 2, \dots, n, \quad (6)$$

and rewrite system (4), (5) in the new notation as follows

$$y'_{ni}(t) + \left(\delta + \gamma \left(\frac{i\pi}{L} \right)^4 \right) y_{ni}(t) + \left[\alpha \left(\frac{i\pi}{L} \right)^3 + \frac{i\pi}{L} \left(\beta + \rho \frac{L}{2} \sum_{j=1}^n z_{nj}^2(t) + \right. \right. \\ \left. \left. + \sigma \frac{L}{2} \sum_{j=1}^n \frac{j\pi}{L} y_{nj}(t) z_{nj}(t) \right) \right] z_{ni}(t) = 0, \quad (7)$$

$$z'_{ni}(t) = \frac{i\pi}{L} y_{ni}(t), \quad i = 1, 2, \dots, n, \quad (8)$$

$$y_{ni}(0) = a_i^1, \quad z_{ni}(0) = \frac{i\pi}{L} a_i^0, \quad i = 1, 2, \dots, n.$$

Problem (7), (8) will be solved using the difference method. On the time interval $[0, T]$ we introduce a net with step $\tau = \frac{T}{M}$ and nodes $t_m = m\tau$, $m = 0, 1, \dots, M$.

On the m -th layer, i.e. for $t = t_m$, the approximate values of $y_{ni}(t)$ and $z_{ni}(t)$ are denoted by y_{ni}^m and z_{ni}^m .

We use a Crank-Nicolson type scheme

$$\frac{y_{ni}^m - y_{ni}^{m-1}}{\tau} + \left(\delta + \gamma \left(\frac{i\pi}{L} \right)^4 \right) \frac{y_{ni}^m + y_{ni}^{m-1}}{2} + \\ + \left[\alpha \left(\frac{i\pi}{L} \right)^3 + \frac{i\pi}{L} \left(\beta + \rho \frac{L}{2} \sum_{j=1}^n \frac{(z_{nj}^m)^2 + (z_{nj}^{m-1})^2}{2} + \right. \right. \\ \left. \left. + \sigma \frac{L}{2} \sum_{j=1}^n \frac{j\pi}{L} \frac{(y_{nj}^m + y_{nj}^{m-1})(z_{nj}^m + z_{nj}^{m-1})}{4} \right) \right] \frac{z_{ni}^m + z_{ni}^{m-1}}{2} = 0, \quad (9)$$

$$\frac{z_{ni}^m - z_{ni}^{m-1}}{\tau} = \frac{i\pi}{L} \frac{y_{ni}^m + y_{ni}^{m-1}}{2}, \\ m = 1, 2, \dots, M, \quad i = 1, 2, \dots, n,$$

with the conditions

$$y_{ni}^0 = a_i^1, \quad z_{ni}^0 = \frac{i\pi}{L} a_i^0, \quad i = 1, 2, \dots, n. \quad (10)$$

c. *Iteration method.* System (9), (10) will be solved layer-by-layer. Assuming that the solution has already been obtained on the $(m-1)$ -th layer, to find it on the m -th layer we use the Jacobi iteration method. For the sake of simplicity, the error of the final approximation iteration approximation on the $(m-1)$ -th layer will be neglected. This means that for fixed m the

counting will be carried out by the formulas

$$\begin{aligned}
& \frac{y_{ni,k+1}^m - y_{ni}^{m-1}}{\tau} + \left(\delta + \gamma \left(\frac{i\pi}{L} \right)^4 \right) \frac{y_{ni,k+1}^m + y_{ni}^{m-1}}{2} + \\
& + \left[\alpha \left(\frac{i\pi}{L} \right)^3 + \frac{i\pi}{L} \left(\beta + \rho \frac{L}{2} \frac{(z_{ni,k+1}^m)^2 + (z_{ni}^{m-1})^2}{2} + \right. \right. \\
& \quad \left. \left. + \rho \frac{L}{2} \sum_{\substack{j=1 \\ j \neq i}}^n \frac{(z_{nj,k}^m)^2 + (z_{nj}^{m-1})^2}{2} + \right. \right. \\
& \quad \left. \left. + \sigma \frac{L}{2} \frac{i\pi}{L} \frac{(y_{ni,k+1}^m + y_{ni}^{m-1})(z_{ni,k+1}^m + z_{ni}^{m-1})}{4} + \right. \right. \\
& \quad \left. \left. + \sigma \frac{L}{2} \sum_{\substack{j=1 \\ j \neq i}}^n \frac{j\pi}{L} \frac{(y_{nj,k}^m + y_{nj}^{m-1})(z_{nj,k}^m + z_{nj}^{m-1})}{4} \right) \right] \frac{z_{ni,k+1}^m + z_{ni}^{m-1}}{2} = 0, \quad (11)
\end{aligned}$$

$$\frac{z_{ni,k+1}^m - z_{ni}^{m-1}}{\tau} = \frac{i\pi}{L} \frac{y_{ni,k+1}^m + y_{ni}^{m-1}}{2}, \quad (12)$$

$$m = 1, 2, \dots, M, \quad k = 0, 1, \dots, \quad i = 1, 2, \dots, n,$$

where $y_{ni,k+p}^m$ and $z_{ni,k+p}^m$ denote the $(k+p)$ -th iteration approximation for y_{ni}^m and z_{ni}^m , $i = 1, 2, \dots, n$, $p = 0, 1$, y_{ni}^{m-1} and z_{ni}^{m-1} are the known values, $i = 1, 2, \dots, n$, and

$$y_{ni}^0 = a_i^1, \quad z_{ni}^0 = \frac{i\pi}{L} a_i^0, \quad i = 1, 2, \dots, n.$$

On expressing $y_{ni,k+1}^m$ in (12) through y_{ni}^{m-1} , z_{ni}^{m-1} and $z_{ni,k+1}^m$,

$$y_{ni,k+1}^m = -y_{ni}^{m-1} + 2 \frac{L}{i\pi} \frac{z_{ni,k+1}^m - z_{ni}^{m-1}}{\tau}, \quad (13)$$

and substituting (13) into (11), we come to the expression

$$\begin{aligned}
& \frac{1}{\tau} \left(-y_{ni}^{m-1} + 2 \frac{L}{i\pi} \frac{z_{ni,k+1}^m - z_{ni}^{m-1}}{\tau} \right) - \frac{y_{ni}^{m-1}}{\tau} + \\
& + \left(\delta + \gamma \left(\frac{i\pi}{L} \right)^4 \right) \frac{L}{i\pi} \frac{z_{ni,k+1}^m - z_{ni}^{m-1}}{\tau} + \\
& + \left\{ \alpha \left(\frac{i\pi}{L} \right)^3 + \frac{i\pi}{L} \left[\beta + \rho \frac{L}{2} \frac{(z_{ni,k+1}^m)^2 + (z_{ni}^{m-1})^2}{2} + \right. \right. \\
& \quad \left. \left. + \rho \frac{L}{2} \sum_{\substack{j=1 \\ j \neq i}}^n \frac{(z_{nj,k}^m)^2 + (z_{nj}^{m-1})^2}{2} + \right. \right.
\end{aligned}$$

$$\begin{aligned}
& + \sigma \frac{L}{4} \frac{z_{ni,k+1}^m - z_{ni}^{m-1}}{\tau} (z_{ni,k+1}^m + z_{ni}^{m-1}) + \\
& + \sigma \frac{L}{4} \sum_{\substack{j=1 \\ j \neq i}}^n \frac{z_{nj,k}^m - z_{nj}^{m-1}}{\tau} (z_{nj,k}^m + z_{nj}^{m-1}) \left. \right\} \frac{z_{ni,k+1}^m + z_{ni}^{m-1}}{2} = 0. \quad (14)
\end{aligned}$$

Hence it follows that for each k the iteration process means the realization of only one formula (14). On obtaining the final iteration approximation $z_{ni,k+1}^m$, we substitute this value into (13) to find an approximation for y_{ni}^m , $i = 1, 2, \dots, n$.

From expression (14) it follows that we have to solve a cubic equation with respect to $z_{ni,k+1}^m$ at the $(k+1)$ -th iteration step for each i .

Applying Cardano's formula we get

$$\begin{aligned}
z_{ni,k+1}^m &= -\frac{z_{ni}^{m-1}}{3} + \sum_{p=1}^2 (-1)^{p+1} \sigma_{i,p}, \quad (15) \\
k &= 0, 1, \dots, \quad i = 1, 2, \dots, n,
\end{aligned}$$

where

$$\sigma_{i,p} = \left[(-1)^p \frac{s_i}{2} + \left(\frac{s_i^2}{4} + \frac{r_i^3}{27} \right)^{\frac{1}{2}} \right]^{\frac{1}{3}}, \quad (16)$$

and

$$\begin{aligned}
r_i &= \frac{8}{L(\rho + \frac{\sigma}{\tau})} \left[2 \left(\frac{L}{i\pi} \right)^2 \frac{1}{\tau^2} + \left(\delta + \gamma \left(\frac{i\pi}{L} \right)^4 \right) \left(\frac{L}{i\pi} \right)^2 \frac{1}{\tau} + \frac{1}{2} \alpha \left(\frac{i\pi}{L} \right)^2 + \right. \\
& \left. + \frac{1}{2} \beta \right] + \sum_{\substack{j=1 \\ j \neq i}}^n (z_{nj,k}^m)^2 - \frac{1}{3} (z_{ni}^{m-1})^2 + \frac{\rho - \frac{\sigma}{\tau}}{\rho + \frac{\sigma}{\tau}} \sum_{j=1}^n (z_{nj}^{m-1})^2, \quad (17)
\end{aligned}$$

$$\begin{aligned}
s_i &= \frac{2(z_{ni}^{m-1})^3}{27} - \frac{16y_{ni}^{m-1}}{i\pi(\sigma + \tau\rho)} + \frac{8z_{ni}^{m-1}}{3L(\rho + \frac{\sigma}{\tau})} \left[-8 \left(\frac{L}{i\pi} \right)^2 \frac{1}{\tau^2} - \right. \\
& \left. - 4 \left(\delta + \gamma \left(\frac{i\pi}{L} \right)^4 \right) \left(\frac{L}{i\pi} \right)^2 \frac{1}{\tau} + \alpha \left(\frac{i\pi}{L} \right)^2 + \beta \right] + \\
& + \frac{2}{3} z_{ni}^{m-1} \left(\sum_{\substack{j=1 \\ j \neq i}}^n (z_{nj,k}^m)^2 + \frac{\rho - \frac{\sigma}{\tau}}{\rho + \frac{\sigma}{\tau}} \sum_{j=1}^n (z_{nj}^{m-1})^2 \right). \quad (18)
\end{aligned}$$

The considered algorithm of solution of problem (1), (2) should be understood as counting by formula (15). Using $z_{ni,k}^m$ and taking (6) and (3) into consideration, we construct the approximate value of the function $u(x, t)$

for $t = t_m$ as the sum

$$u_{n,k}^m(x) = \sum_{i=1}^n \frac{L}{i\pi} z_{ni,k}^m \sin \frac{i\pi x}{L}. \quad (19)$$

3. ESTIMATE OF THE ITERATION METHOD ERROR

Our aim consists in finding convergence conditions and estimating the accuracy of the iteration method (15).

Let us estimate the sums $\sum_{i=1}^n (y_{ni}^m)^2$ and $\sum_{i=1}^n \left(\frac{i\pi}{L}\right)^{2p} (z_{ni}^m)^2$, $p = 0, 1$. For this, we multiply the first equation in (9) by $\frac{1}{2}(y_{ni}^m + y_{ni}^{m-1})$, sum the obtained relation over $i = 1, 2, \dots, n$ and take into consideration the second equality in (9). We obtain

$$\begin{aligned} & \frac{1}{2\tau} \sum_{i=1}^n ((y_{ni}^m)^2 - (y_{ni}^{m-1})^2) + \frac{1}{4} \sum_{i=1}^n \left(\delta + \gamma \left(\frac{i\pi}{L} \right)^4 \right) (y_{ni}^m + y_{ni}^{m-1})^2 + \\ & + \alpha \frac{1}{2\tau} \sum_{i=1}^n \left(\frac{i\pi}{L} \right)^2 ((z_{ni}^m)^2 - (z_{ni}^{m-1})^2) + \beta \frac{1}{2\tau} \sum_{i=1}^n ((z_{ni}^m)^2 - (z_{ni}^{m-1})^2) + \\ & + \rho L \frac{1}{8\tau} \sum_{i=1}^n ((z_{ni}^m)^2 + (z_{ni}^{m-1})^2) \sum_{i=1}^n ((z_{ni}^m)^2 - (z_{ni}^{m-1})^2) + \\ & + \sigma \frac{L}{32} \left(\sum_{i=1}^n \frac{i\pi}{L} (y_{ni}^m + y_{ni}^{m-1}) (z_{ni}^m + z_{ni}^{m-1}) \right)^2 = 0, \end{aligned}$$

whence we have

$$\begin{aligned} & \sum_{i=1}^n (y_{ni}^m)^2 + \alpha \sum_{i=1}^n \left(\frac{i\pi}{L} \right)^2 (z_{ni}^m)^2 + \beta \sum_{i=1}^n (z_{ni}^m)^2 + \rho \frac{L}{4} \left(\sum_{i=1}^n (z_{ni}^m)^2 \right)^2 \leq \\ & \leq \sum_{i=1}^n (y_{ni}^{m-1})^2 + \alpha \sum_{i=1}^n \left(\frac{i\pi}{L} \right)^2 (z_{ni}^{m-1})^2 + \\ & + \beta \sum_{i=1}^n (z_{ni}^{m-1})^2 + \rho \frac{L}{4} \left(\sum_{i=1}^n (z_{ni}^{m-1})^2 \right)^2. \end{aligned}$$

From this inequality and relations (10) and (5) follow the estimates

$$\sum_{i=1}^n (y_{ni}^m)^2 \leq \theta_0, \quad \sum_{i=1}^n \left(\frac{i\pi}{L} \right)^{2p} (z_{ni}^m)^2 \leq \left(\frac{1}{\alpha} \right)^p \theta_{1-p}, \quad p = 0, 1, \quad (20)$$

where

$$\begin{aligned}\theta_0 &= \frac{2}{L} \int_0^L [(u^1(x))^2 + \alpha(u^{0''}(x))^2 + \beta(u^{0'}(x))^2] dx + \\ &\quad + \frac{\rho}{L} \left(\int_0^L (u^{0'}(x))^2 dx \right)^2, \\ \theta_1 &= \frac{1}{2\theta_2} (-\theta_3 + (\theta_3^2 + 4\theta_0\theta_2)^{\frac{1}{2}}), \quad \theta_2 = \rho \frac{L}{4}, \quad \theta_3 = \beta + \alpha \left(\frac{\pi}{L} \right)^2.\end{aligned}$$

We will need these estimates later.

Note that under the conditions imposed on the coefficients of equation (1) and functions $u^0(x)$ and $u^1(x)$ the inequality $\theta_0 \geq 0$ holds.

Under the iteration method error we understand the difference between (19) and the sum

$$u_n^m(x) = \sum_{i=1}^n \frac{L}{i\pi} z_{ni}^m \sin \frac{i\pi x}{L},$$

which would give an approximate value of the function $u(x, t)$ for $t = t_m$ if the difference system (9), (10) were solved exactly. So, we mean here the relation

$$u_{n,k}^m(x) - u_n^m(x) = \sum_{i=1}^n \frac{L}{i\pi} (z_{ni,k}^m - z_{ni}^m) \sin \frac{i\pi x}{L}. \quad (21)$$

To estimate (21), we represent system (15) as

$$z_{ni,k+1}^m = \varphi_i(z_{n1,k}^m, z_{n2,k}^m, \dots, z_{nn,k}^m) \quad (22)$$

and consider the Jacobi matrix

$$J = \left(\frac{\partial \varphi_i}{\partial z_{nj,k}^m} \right)_{i,j=1}^n. \quad (23)$$

By virtue of (15)–(18) and (22) the diagonal elements of the matrix J are equal to zero, while for the nondiagonal elements we have

$$\begin{aligned}\frac{\partial \varphi_i}{\partial z_{nj,k}^m} &= -\frac{z_{nj,k}^m}{9} \sum_{p=1}^2 \frac{1}{\sigma_{i,p}^2} \left[2z_{ni}^{m-1} + \right. \\ &\quad \left. + (-1)^p \left(s_i z_{ni}^{m-1} + \frac{1}{3} r_i^2 \right) \left(\frac{s_i^2}{4} + \frac{r_i^3}{27} \right)^{-\frac{1}{2}} \right].\end{aligned} \quad (24)$$

By (16)

$$\sigma_{i,1}\sigma_{i,2} = \frac{r_i}{3}, \quad \sigma_{i,2}^3 - \sigma_{i,1}^3 = s_i, \quad \left(\frac{s_i^2}{4} + \frac{r_i^3}{27} \right)^{\frac{1}{2}} = \frac{\sigma_{i,1}^3 + \sigma_{i,2}^3}{2}. \quad (25)$$

Formulas (24) are obtained under the condition that $\sigma_{i,p} \neq 0$, $p = 1, 2$, for the fulfilment of which it suffices to assume that $|r_i| > 0$. As will be shown below, this condition will be observed.

From (24) and (25) follows

$$\begin{aligned} \frac{\partial \varphi_i}{\partial z_{nj,k}^m} = & -\frac{4}{9} z_{nj,k}^m z_{ni}^{m-1} \left(\sigma_{i,1}^2 - \frac{r_i}{3} + \sigma_{i,2}^2 \right)^{-1} + \\ & + \frac{2}{3} z_{nj,k}^m s_i \left(\sigma_{i,1}^4 + \frac{r_i^2}{9} + \sigma_{i,2}^4 \right)^{-1}, \quad i \neq j. \end{aligned} \quad (26)$$

Now to the obvious inequality $\sigma_{i,1}^{2p} + \sigma_{i,2}^{2p} \geq 2(\sigma_{i,1}\sigma_{i,2})^p$, $p = 1, 2$, we apply the first relation in (25). We have

$$\sigma_{i,1}^{2p} + \sigma_{i,2}^{2p} \geq 2 \left(\frac{r_i}{3} \right)^p.$$

By virtue of this inequality, from (26) follows

$$\left| \frac{\partial \varphi_i}{\partial z_{nj,k}^m} \right| \leq \left(\frac{4}{3|r_i|} |z_{ni}^{m-1}| + \frac{2}{r_i^2} |s_i| \right) |z_{nj,k}^m|. \quad (27)$$

Let us estimate $|r_i|$ from below. From (17) and (20) we conclude that

$$|r_i| \geq \mu_i + \sum_{\substack{j=1 \\ j \neq i}}^n (z_{nj,k}^m)^2 - \mu \theta_1,$$

where

$$\begin{aligned} \mu_i = & \frac{8}{L(\rho + \frac{\sigma}{\tau})} \left[2 \left(\frac{L}{i\pi} \right)^2 \frac{1}{\tau^2} + \left(\delta + \gamma \left(\frac{i\pi}{L} \right)^4 \right) \left(\frac{L}{i\pi} \right)^2 \frac{1}{\tau} + \right. \\ & \left. + \frac{1}{2} \alpha \left(\frac{i\pi}{L} \right)^2 + \frac{1}{2} \beta \right], \quad (28) \\ \mu = & \max \left(0, \frac{1}{3} - \frac{\rho - \frac{\sigma}{\tau}}{\rho + \frac{\sigma}{\tau}} \right). \end{aligned}$$

Let us choose an arbitrary number ε from the interval $(0, 1)$ and require that the inequality

$$|r_i| \geq (1 - \varepsilon) \left(\mu_i + \sum_{\substack{j=1 \\ j \neq i}}^n (z_{nj,k}^m)^2 + \frac{5}{9} \theta_1 \right) \quad (29)$$

be fulfilled. For this it suffices to assume that the step τ is so small that the inequality $\mu_i > \frac{1}{\varepsilon} \theta_1 (\mu + \frac{5}{9} (1 - \varepsilon))$ is fulfilled. On replacing in the latter inequality μ_i by $\frac{8}{L(\sigma + \tau\rho)} [\omega + 2(\frac{L}{n\pi})^2 \frac{1}{\tau} + \frac{1}{2} \tau (\alpha(\frac{\pi}{L})^2 + \beta)]$, where $\omega = 2\sqrt{\delta}\gamma$ for $\delta > 0$ and $\omega = (\delta + \gamma(\frac{\pi}{L})^4)(\frac{L}{n\pi})^2$ for $\delta < 0$, we obtain a simpler but more rigid condition of the fulfillment of relation (29).

Further, (18) and (20) imply

$$\begin{aligned} |s_i| \leq & \frac{16|y_{ni}^{m-1}|}{i\pi(\sigma + \tau\rho)} + \frac{8|z_{ni}^{m-1}|}{3L(\rho + \frac{\sigma}{\tau})} \left[8\left(\frac{L}{i\pi}\right)^2 \frac{1}{\tau^2} + \right. \\ & + 4\left(\delta + \gamma\left(\frac{i\pi}{L}\right)^4\right) \left(\frac{L}{i\pi}\right)^2 \frac{1}{\tau} + \alpha\left(\frac{i\pi}{L}\right)^2 + \beta \Big] + \\ & + \left(\frac{2}{3} \sum_{\substack{j=1 \\ j \neq i}}^n (z_{nj,k}^m)^2 + \frac{20}{27} \theta_1\right) |z_{ni}^{m-1}|. \end{aligned} \quad (30)$$

Using (27)–(30), we obtain

$$\begin{aligned} \left| \frac{\partial \varphi_i}{\partial z_{nj,k}^m} \right| \leq & \frac{1}{1-\varepsilon} \tau(\sigma + \tau\rho) \left(\frac{i\pi}{L}\right)^2 L \left\{ \frac{1}{12} |z_{ni}^{m-1}| + \right. \\ & \left. + \frac{1}{8(1-\varepsilon)} \left[\tau \frac{i\pi}{L} |y_{ni}^{m-1}| + \frac{4}{3} |z_{ni}^{m-1}| \right] \right\} |z_{nj,k}^m|. \end{aligned} \quad (31)$$

We need the vector norm equal to $\|v\| = \sum_{i=1}^n |v_i|$ and the corresponding norm for the matrix $\|K\| = \max_{1 \leq j \leq n} \sum_{i=1}^n |k_{ij}|$, where $v = (v_i)_{i=1}^n$ and $K = (k_{ij})_{i,j=1}^n$. By (23), (31) and (20) we get

$$\|J\| \leq (a\tau^3 + b\tau^2 + c\tau) \max_{1 \leq j \leq n} |z_{nj,k}^m|, \quad (32)$$

where the following notation is used

$$\begin{aligned} a &= \frac{\rho L}{8(1-\varepsilon)^2} \left(\frac{\pi}{L}\right)^3 \left(\sum_{i=1}^n i^6\right)^{\frac{1}{2}} \sqrt{\theta_0}, \quad b = a \frac{\sigma}{\rho} + c \frac{\rho}{\sigma}, \\ c &= \frac{1}{6(1-\varepsilon)} \sigma L \left(\frac{1}{2} + \frac{1}{1-\varepsilon}\right) \frac{\pi}{L} \left(\sum_{i=1}^n i^2\right)^{\frac{1}{2}} \sqrt{\frac{\theta_0}{\alpha}}. \end{aligned}$$

By virtue of Banach's construction principle [5], it can be assumed that the condition $\|J\| \leq q$ is fulfilled for $0 < q < 1$ and $z_{n,k}^m = (z_{ni,k}^m)_{i=1}^n$, $k = 0, 1, \dots$, belongs to the domain

$$\left\{ w \in R^n : \|w - z_{n,0}^m\| \leq \frac{1}{1-q} \|z_{n,1}^m - z_{n,0}^m\| \right\}. \quad (33)$$

According to (32), for this it suffices that the restriction

$$a\tau^3 + b\tau^2 + c\tau \leq q \left(\|z_{n,0}^m\| + \frac{1}{1-q} \|z_{n,1}^m - z_{n,0}^m\| \right)^{-1} \quad (34)$$

be fulfilled for the step τ .

If this restriction is fulfilled, then system (9), (10) has a unique solution $y_{ni}^m, z_{ni}^m, i = 1, 2, \dots, n$, in (33), the iteration process (15) converges, $\lim_{k \rightarrow \infty} z_{ni,k}^m = z_{ni}^m, i = 1, 2, \dots, n$, and the convergence rate is determined by the vector inequality

$$\|z_{n,k}^m - z_n^m\| \leq \frac{q^k}{1-q} \|z_{n,1}^m - z_{n,0}^m\|,$$

where $z_n^m = (z_{ni}^m)_{i=1}^n$.

Applying this relation to (21), we come to a conclusion that if condition (34) is fulfilled, then the estimate

$$\left\| \frac{d^p}{dx^p} (u_{n,k}^m(x) - u_n^m(x)) \right\|_{L^2(0,L)} \leq \left(\frac{L}{\pi} \right)^{1-p} \sqrt{\frac{L}{2}} \frac{q^k}{1-q} \|z_{n,1}^m - z_{n,0}^m\|,$$

$$p = 0, 1, \quad m = 1, 2, \dots, M, \quad k = 1, 2, \dots,$$

holds for the $L^2(0, L)$ -norm of the iteration method error.

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