Memoirs on Differential Equations and Mathematical Physics
Volume 92, 2024, 129-140

Billal Lekdim, Mohammed Aili, Ammar Khemmoudj

GENERAL DECAY OF A SINGULAR VISCOELASTIC
WAVE EQUATION WITH DISTRIBUTED DELAY
AND INTEGRAL CONDITION


#### Abstract

In this paper, we consider a singular viscoelastic wave equation with a distributed delay and an integral condition. By introducing a suitable Lyapunov functional, under appropriate assumptions on the relaxation function and the delay weight, we establish a general decay result in which the exponential and polynomial decay are only special cases.


## 2020 Mathematics Subject Classification. 35L05, 35B35, 74D05.

Key words and phrases. Wave equation, integral condition, general decay, distributed delay.






## 1 Introduction

In the mathematical modeling of phenomena with partial differential equations (PDEs) and a set of boundary conditions, sometimes it is not possible to directly measure the boundary data such as the moment, mean, total energy or total mass, so one resorts to the integral condition

$$
\int_{0}^{l} f(x) u(x, t) d x=g(t)
$$

This kind of condition is called nonlocal, however, it has been adopted by many researchers, especially with regard to stability problems of nonlocal single systems.

The motivation for our work is based on some previous findings published in the following research papers.

In [13], Mesloub studied the solvability of the viscoelastic wave equation with frictional damping

$$
u_{t t}-\frac{1}{x}\left(x u_{x}\right)_{x}+\int_{0}^{t} h(t-s) \frac{1}{x}\left(x u_{x}(s)\right)_{x} d s+a u_{t}=f\left(x, t, u, u_{x}\right), \quad(x, t) \in(0, l) \times(0, \infty)
$$

with the combination of Dirichlet and integral boundary conditions, and for some properties of the relaxation function $h$. A similar problem, but with localized frictional damping, is considered in [3], where the authors proved the existence and general decay of a global solution. While in [18], Piskin et al. investigated the blow-up of the nonlocal singular viscoelastic system with strong damping.In the absence of the frictional dissipation, the blow-up of solutions has been proven in [19].

Moreover, in [9], the authors only care about the linear nonlocal singular viscoelastic wave equation

$$
u_{t t}-\frac{1}{x}\left(x u_{x}\right)_{x}+\int_{0}^{t} h(t-s) \frac{1}{x}\left(x u_{x}(s)\right)_{x} d s=0, \quad(x, t) \in(0, l) \times(0, \infty)
$$

under certain conditions on the function $h$, and prove the existence of strong solutions. But the result of general stability has been demonstrated in [2]. For a more viscoelastic problem, see [4, 5, 7, 15-17].

In this paper, we investigate a singular viscoelastic problem with internal damping and distributed delay:

$$
\begin{cases}u_{t t}(x, t)-\frac{1}{x}\left(x u_{x}(x, t)\right)_{x}+\int_{0}^{t} h(t-s) \frac{1}{x}\left(x u_{x}(x, s)\right)_{x} d s &  \tag{1.1}\\ & +a u_{t}(x, t)+\int_{\tau_{1}}^{\tau_{2}} b(s) u_{t}(x, t-s) d s=0, \\ u(l, t)=0, \quad \int_{0}^{l} x u(x, t) d x=0, & \\ & \\ u(x, 0)=u_{1}(x), \quad u_{t}(x, 0)=u_{2}(x), \quad u_{t}(x,-t)=u_{3}(x, t), & x \in(0, l) \times(0, \infty) \\ u(0, t \in] 0, \tau_{2}[ \end{cases}
$$

where $0<l<\infty, h$ is a positive decreasing function and $u_{1}, u_{2}, u_{3}$ are given data. The term

$$
\int_{\tau_{1}}^{\tau_{2}} b(s) u_{t}(x, t-s) d s
$$

represents the distributed delay. Its appearance in the equation causes some disturbances.
Inspired by the previous studies, more precisely by [2], the aim of this paper is to study a general decay of solution of problem (1.1). To our knowledge, there are no works related to this issue yet.

The rest is organized as follows. In Section 2, we give some preliminaries, hypotheses and theorem on the existence and uniqueness to justify the calculations in the next section. In Section 3, we establish our general decay result.

## 2 Preliminary results

Let $L_{\rho}^{2}(Q)(Q=(0, l) \times(0, T))$ be the Hilbert space equipped with inner product

$$
(u, v)_{L_{\rho}^{2}(Q)}=\int_{Q} x u v d x d t
$$

and associated norms

$$
\|u\|_{L_{\rho}^{2}(Q)}=\int_{Q} x|u|^{2} d x d t
$$

Also, denote by $H_{\rho}^{1,0}(Q)$ and $H_{\rho}^{1,1}(Q)$ the Hilbert spaces with inner products

$$
(u, v)_{H_{\rho}^{1,0}(Q)}=(u, v)_{L_{\rho}^{2}(Q)}+\left(u_{x}, v_{x}\right)_{L_{\rho}^{2}(Q)}
$$

and

$$
(u, v)_{H_{\rho}^{1,1}(Q)}=(u, v)_{L_{\rho}^{2}(Q)}+\left(u_{x}, v_{x}\right)_{L_{\rho}^{2}(Q)}+\left(u_{t}, v_{t}\right)_{L_{\rho}^{2}(Q)}
$$

respectively.
As in [8], for the function $h$, we assume:
(H1) Let $h \in \mathcal{C}^{1}\left(\mathbb{R}_{+}, \mathbb{R}_{+}\right)$be a decreasing function satisfying

$$
h(0)>0, \quad \int_{0}^{\infty} h(s) d s=\bar{h}<1 .
$$

(H2) There exists a nonincreasing differentiable function $\zeta: \mathbb{R}_{+} \rightarrow \mathbb{R}_{+}$satisfying

$$
h^{\prime}(t) \leq-\zeta(t) h(t), \quad t \geq 0
$$

For the delay weight $b$, following $[1,6]$, we assume:
(H3) Let $b \in L^{\infty}\left(\tau_{1}, \tau_{2}\right)$ and $b \geq 0$ almost everywhere such that

$$
\int_{\tau_{1}}^{\tau_{1}} b(s) d s<a
$$

which implies that there exists a positive constant $c_{0}$ such that

$$
\begin{equation*}
\bar{b}=a-\int_{\tau_{1}}^{\tau_{1}}\left(b(s)+\frac{c_{0}}{2}\right) d s \geq 0 \tag{2.1}
\end{equation*}
$$

Remark. Inequality (2.1) is necessary to establish the exponential stability results.
Problem (1.1) can be written in the operational form

$$
\mathcal{L} u=F,
$$

where $\mathcal{L} u=\left(L_{\rho} u, L_{1} u, L_{2} u, L_{3} u\right)$ and $F=\left(0, u_{1}, u_{2}, u_{3}\right)$ with

$$
\begin{gathered}
L_{\rho} u=u_{t t}(x, t)-\frac{1}{x}\left(x u_{x}(x, t)\right)_{x}+\int_{0}^{t} h(t-s) \frac{1}{x}\left(x u_{x}(x, s)\right)_{x} d s \\
+a u_{t}(x, t)+\int_{\tau_{1}}^{\tau_{2}} b(s) u_{t}(x, t-s) d s, \quad(x, t) \in(0, l) \times(0, \infty) \\
u(l, t)=0, \quad \int_{0}^{l} x u(x, t) d x=0, \quad t \in(0, \infty) \\
L_{1} u=u(x, 0)=u_{1}(x), \quad L_{2} u=u_{t}(x, 0)=u_{2}(x), \quad x \in(0, l) \\
\left.L_{3} u=u_{t}(x,-t)=u_{3}(x), \quad x \in(0, l), \quad t \in\right] 0, \tau_{2}[, \\
D(\mathcal{L})=\left\{u \in L_{\rho}^{2}(Q), u_{t}, u_{t t}, u_{x}, u_{x x}, u_{t x} \in L_{\rho}^{2}(Q), \quad u(l, t)=0, \quad \int_{0}^{l} x u(x, t) d x=0\right\}
\end{gathered}
$$

Now, we state without proof the theorem of the existence and uniqueness, which can be proven by performing the same steps as in [9-14].

Theorem 2.1. Let $u_{1} \in H_{\rho}^{1,0}(0, l), u_{2} \in L_{\rho}^{2}(0, l)$ and $u_{3} \in L_{\rho}^{2}(Q)$. Then problem (1.1) has a unique solution

$$
u \in C\left(0, T ; H_{\rho}^{1,0}(0, l)\right) \cap C^{1}\left(0, T ; L_{\rho}^{2}(0, l)\right) \text { for some } T>0
$$

We define the energy of problem (1.1) by

$$
\begin{align*}
E(t)=\frac{1}{2} \int_{0}^{l} x u_{t}^{2} d x+\frac{1}{2}(1 & \left.-\int_{0}^{t} h(s) d s\right) \int_{0}^{l} x u_{x}^{2} d x \\
& +\frac{1}{2}\left(h \circ u_{x}\right)+\frac{1}{2} \int_{0}^{l} \int_{\tau_{1}}^{\tau_{2}} s\left[b(s)+c_{0}\right] \int_{0}^{1} x u_{t}^{2}(t-p s) d p d s d x \tag{2.2}
\end{align*}
$$

where

$$
\left(h \circ u_{x}\right)(t)=\int_{0}^{l} \int_{0}^{t} x h(t-s)\left|u_{x}(x, t)-u_{x}(x, s)\right|^{2} d x
$$

Lemma 2.1. Let $u$ be the solution of system (1.1). Then for all $t \geq 0$, we have

$$
E^{\prime}(t)=\frac{1}{2}\left(h^{\prime} \circ u_{x}\right)(t)-\frac{h(t)}{2} \int_{0}^{l} x u_{x}^{2} d x-\bar{b} \int_{0}^{l} x u_{t}^{2} d x-\frac{c_{0}}{2} \int_{0}^{l} \int_{\tau_{1}}^{\tau_{2}} x u_{t}^{2}(t-s) d s d x
$$

Proof. Multiplying the first equation in (1.1) by $x u_{t}$, integrating by parts over $(0, l)$ and using the same technique as in [4] for the memory term, we have

$$
\begin{align*}
E^{\prime}(t)= & -\frac{h(t)}{2} \int_{0}^{l} x u_{x}^{2} d x+\frac{1}{2}\left(h^{\prime} \circ u_{x}\right)-\int_{0}^{l} x u_{t} \int_{\tau_{1}}^{\tau_{2}} b(s) u_{t}^{2}(t-s) d s d x \\
& -a \int_{0}^{l} x u_{t}^{2} d x+\int_{0}^{l} \int_{\tau_{1}}^{\tau_{2}} s\left[b(s)+c_{0}\right] \int_{0}^{1} x u_{t t} u_{t}(t-p s) d p d s d x \tag{2.3}
\end{align*}
$$

It is clear that for all $t \geq 0$,

$$
\begin{equation*}
u_{t t}(t-p s)=-\frac{1}{s} u_{t p}(t-p s), \quad(p, s) \in(0,1) \times\left(\tau_{1}, \tau_{2}\right) \tag{2.4}
\end{equation*}
$$

Therefore,

$$
\int_{0}^{1} u_{t}(t-p s) u_{t t}(t-p s) d p=-\frac{1}{2 s}\left(u_{t}^{2}(t-s)-u_{t}^{2}(t)\right)
$$

Using Cauchy-Schwarz and Young's inequalities, we get

$$
\int_{0}^{l} x u_{t} \int_{\tau_{1}}^{\tau_{1}} b(s) u_{t}(t-s) d s d x \leq \frac{1}{2}\left(\int_{\tau_{1}}^{\tau_{1}} b(s) d s\right) \int_{0}^{l} x u_{t}^{2} d x+\frac{1}{2} \int_{0}^{l} \int_{\tau_{1}}^{\tau_{1}} b(s) x u_{t}^{2}(t-s) d s d x
$$

Then relationship (2.3) becomes

$$
E^{\prime}(t)=\frac{1}{2}\left(h^{\prime} \circ u_{x}\right)(t)-\frac{h(t)}{2} \int_{0}^{l} x u_{x}^{2} d x-\bar{b} \int_{0}^{l} x u_{t}^{2} d x-\frac{c_{0}}{2} \int_{0}^{l} \int_{\tau_{1}}^{\tau_{2}} x u_{t}^{2}(t-s) d s d x
$$

where

$$
\bar{b}=\left(a-\left(\int_{\tau_{1}}^{\tau_{1}}\left(b(s)+\frac{c_{0}}{2}\right) d s\right)\right)
$$

Lemma 2.2 ([15], (Poincare-type inequality)). Let $u$ be a function on $H^{1}(0, l)$ and $u(l)=0$. Then the following inequality holds:

$$
\int_{0}^{l} x u^{2} d x \leq 2 l^{2} \int_{0}^{l} x u_{x}^{2} d x, \quad \forall t \geq 0
$$

## 3 Asymptotic Stability

In order to prove the decay of energy, we define the Lyapunov candidate function by

$$
L(t)=E(t)+\beta_{1} V_{1}(t)+\beta_{2} V_{2}(t)+\beta_{3} V_{3}(t)
$$

where $\beta_{1}, \beta_{2}$ and $\beta_{3}$ are positive constants, $E(t)$ is the energy given by (2.2) and

$$
\begin{align*}
V_{1}(t) & =\int_{0}^{l} x u_{t} u d x \\
V_{2}(t) & =-\int_{0}^{l} x u_{t} \int_{0}^{t} h(t-s)(u(t)-u(s)) d s d x  \tag{3.1}\\
V_{3}(t) & =\int_{0}^{L} \int_{\tau_{1}}^{\tau_{2}} \int_{0}^{1} s e^{-2 p s}\left[b(s)+c_{0}\right] x u_{t}^{2}(t-p s) d p d s d x
\end{align*}
$$

Proposition. There exist $\alpha_{1}$ and $\alpha_{2}$ such that

$$
\begin{equation*}
\alpha_{1} E(t) \leq L(t) \leq \alpha_{2} E(t), \quad \forall t \geq 0 \tag{3.2}
\end{equation*}
$$

Proof. Using the Young and Poincaré inequalities, we obtain (3.2).

Lemma 3.1. The derivative of $V_{1}(t)$ yields

$$
\begin{align*}
V_{1}^{\prime}(t) \leq & \left(1+\frac{a^{2}}{\delta_{1}}\right) \int_{0}^{l} x u_{t}^{2} d x-\left(1-\delta_{1} l^{2}-\bar{h}+\frac{\delta \bar{h}}{4}\right) \int_{0}^{l} x u_{x}^{2} d x \\
& +\frac{1}{\delta}\left(h \circ u_{x}\right)+\frac{1}{\delta_{1}}\left(\int_{\tau_{1}}^{\tau_{2}} b(s) d s\right) \int_{0}^{l} \int_{\tau_{1}}^{\tau_{2}} b(s) x u_{t}^{2}(t-s) d s d x \tag{3.3}
\end{align*}
$$

where $\delta$ and $\delta_{1}$ are positive constants.
Proof. The derivative of $V_{1}(t)$, the system (1.1) and the integration by parts yield

$$
\begin{align*}
V_{1}^{\prime}(t)= & \int_{0}^{l} x u_{t}^{2} d x-\int_{0}^{l} x u_{x}^{2} d x+\int_{0}^{l} \int_{0}^{t} h(t-s) x u_{x}(s) u_{x}(t) d s d x \\
& -a \int_{0}^{l} x u u_{t} d x-\int_{0}^{l} \int_{\tau_{1}}^{\tau_{2}} b(s) x u u_{t}(t-s) d s d x \tag{3.4}
\end{align*}
$$

By the Young and Poincaré-type inequalities, we estimate

$$
\begin{align*}
\int_{0}^{l} \int_{0}^{t} h(t-s) x u_{x}(s) u_{x}(t) d s d x & \leq \frac{1}{\delta}\left(h \circ u_{x}\right)+\left(\bar{h}+\frac{\delta \bar{h}}{4}\right) \int_{0}^{l} x u_{x}^{2} d x  \tag{3.5}\\
a \int_{0}^{l} x u u_{t} d x & \leq \frac{a^{2}}{\delta_{1}} \int_{0}^{l} x u_{t}^{2} d x+\frac{\delta_{1} l^{2}}{2} \int_{0}^{l} x u_{x}^{2} d x \tag{3.6}
\end{align*}
$$

and

$$
\begin{equation*}
\int_{0}^{l} \int_{\tau_{1}}^{\tau_{2}} b(s) x u u_{t}(t-s) d s d x \leq \frac{\delta_{1} l^{2}}{2} \int_{0}^{l} x u_{x}^{2} d x+\frac{1}{\delta_{1}}\left(\int_{\tau_{1}}^{\tau_{2}} b(s) d s\right) \int_{0}^{l} \int_{\tau_{1}}^{\tau_{1}} b(s) x u_{t}^{2}(t-s) d s d x \tag{3.7}
\end{equation*}
$$

Combining (3.4)-(3.7), we obtain (3.3).
Lemma 3.2. The time derivative of $V_{2}(t)$ yields

$$
\begin{align*}
V_{2}^{\prime}(t)= & -\left[\left(\int_{0}^{t} h(s) d s\right)-\frac{\delta_{3} \bar{h} a^{2}}{2}\right] \int_{0}^{l} x u_{t}^{2} d x-\left(h^{\prime} \circ u_{x}\right)+\frac{\delta_{2} \bar{h}}{2} \int_{0}^{l} x u_{x}^{2} \\
& +\left[\bar{h}+\frac{\bar{h}+1}{\delta_{2}}+\frac{(\bar{h}+1) l^{2}}{\delta_{3}}\right]\left(h \circ u_{x}\right)+\frac{\delta_{3}}{2}\left(\int_{\tau_{1}}^{\tau_{2}} b(s) d s\right) \int_{0}^{l} \int_{\tau_{1}}^{\tau_{2}} b(s) x u_{t}^{2}(t-s) d s d x \tag{3.8}
\end{align*}
$$

where $\delta_{2}$ and $\delta_{3}$ are positive constants.
Proof. Differentiation of (3.1), system (1.1) and integration by parts give

$$
\begin{aligned}
V_{2}^{\prime}(t)= & -\int_{0}^{t} h(s) d s \int_{0}^{l} x u_{t}^{2} d x-\left(h^{\prime} \circ u_{x}\right)-\int_{0}^{l} x u_{x} \int_{0}^{t} h(t-s)\left(u_{x}(t)-u_{x}(s)\right) d s d x \\
& +\int_{0}^{l} \int_{0}^{t} h(t-s) x u_{x}(s) d s \int_{0}^{t} h(t-s)\left(u_{x}(t)-u_{x}(s)\right) d s d x
\end{aligned}
$$

$$
\begin{align*}
& +a \int_{0}^{l} x u_{t} \int_{0}^{t} h(t-s)(u(t)-u(s)) d s d x \\
& +\int_{0}^{l} \int_{\tau_{1}}^{\tau_{2}} b(s) x u_{t}(t-s) d s \int_{0}^{t} h(t-s)(u(t)-u(s)) d s d x \tag{3.9}
\end{align*}
$$

Using the Young and Poincare-type inequalities, we obtain

$$
\begin{gather*}
\int_{0}^{l} x u_{x} \int_{0}^{t} h(t-s)\left(u_{x}(t)-u_{x}(s)\right) d s d x \leq \frac{1}{\delta_{2}}\left(h \circ u_{x}\right)+\frac{\delta_{2} \bar{h}}{4} \int_{0}^{l} x u_{x}^{2} d x  \tag{3.10}\\
\int_{0}^{l} \int_{0}^{t} h(t-s) x u_{x}(s) d s \int_{0}^{t} h(t-s)\left(u_{x}(t)-u_{x}(s)\right) d s d x \leq\left(\bar{h}+\frac{\bar{h}}{\delta_{2}}\right)\left(h \circ u_{x}\right)+\frac{\delta_{2} \bar{h}}{4} \int_{0}^{l} x u_{x}^{2} d x  \tag{3.11}\\
a \int_{0}^{l} x u_{t} \int_{0}^{t} h(t-s) x(u(t)-u(s)) d s d x \leq \frac{l^{2}}{\delta_{3}}\left(h \circ u_{x}\right)+\frac{\delta_{3} \bar{h} a^{2}}{2} \int_{0}^{l} x u_{t}^{2} d x \tag{3.12}
\end{gather*}
$$

and

$$
\begin{align*}
\int_{0}^{l} \int_{\tau_{1}}^{\tau_{2}} b(s) x u_{t}(t-s) d s & \int_{0}^{t} h(t-s)(u(t)-u(s)) d s d x \\
& \leq \frac{\bar{h} l^{2}}{\delta_{3}}\left(h \circ u_{x}\right)+\frac{\delta_{3}}{2}\left(\int_{\tau_{1}}^{\tau_{2}} b(s) d s\right) \int_{0}^{l} \int_{\tau_{1}}^{\tau_{2}} b(s) x u_{t}^{2}(t-s) d s d x \tag{3.13}
\end{align*}
$$

Substituting (3.10)-(3.13) into (3.9), we get (3.8).
Lemma 3.3. The time derivative of $V_{3}(t)$ yields

$$
\begin{align*}
V_{3}^{\prime}(t)= & -e^{-2 \tau_{2}} \int_{0}^{L} \int_{\tau_{1}}^{\tau_{2}}\left[b(s)+c_{0}\right] x u_{t}^{2}(t-s) d s d x+\int_{\tau_{1}}^{\tau_{2}}\left[b(s)+c_{0}\right] d s \int_{0}^{L} x u_{t}^{2} d x \\
& -2 \int_{0}^{L} \int_{\tau_{1}}^{\tau_{2}} \int_{0}^{1} s e^{-2 p s}\left[b(s)+c_{0}\right] x u_{t}^{2}(t-p s) d p d s d x \tag{3.14}
\end{align*}
$$

Proof. By deriving $V_{3}(t)$, using identity (2.4) and integrating by parts, we have

$$
\begin{aligned}
& V_{3}^{\prime}(t)=2 \int_{0}^{L} \int_{\tau_{1}}^{\tau_{2}} \int_{0}^{1} s e^{-2 p s}\left[b(s)+c_{0}\right] x u_{t} u_{t t}(t-p s) d p d s d x \\
&=-\int_{0}^{L} x \int_{\tau_{1}}^{\tau_{2}}\left[b(s)+c_{0}\right] \int_{0}^{1} e^{-2 p s}\left(u_{t}^{2}\right)_{p}(t-p s) d p d s d x \\
&=-\int_{0}^{L} \int_{\tau_{1}}^{\tau_{2}} e^{-2 s}\left[b(s)+c_{0}\right] x u_{t}^{2}(t-s) d s d x+\int_{\tau_{1}}^{\tau_{2}}\left[b(s)+c_{0}\right] d s \int_{0}^{L} x u_{t}^{2} d x \\
&-2 \int_{0}^{L} \int_{\tau_{1}}^{\tau_{2}} \int_{0}^{1} s e^{-2 p s}\left[b(s)+c_{0}\right] x u_{t}^{2}(t-p s) d p d s d x
\end{aligned}
$$

Using the decay property of $e^{-2 s}$, we obtain (3.14).

Theorem 3.1. Assume that (H1) and (H2) hold. Then there exist two positive constants $\alpha$ and $C$ such that

$$
\begin{equation*}
E(t) \leq C e^{-\alpha \int_{0}^{t} \zeta(s) d s}, \quad t \geq 0 \tag{3.15}
\end{equation*}
$$

Proof. Taking into account Lemmas 2.1, 3.1, 3.2 and 3.3, the derivative of $L(t)$ for all $t \geq t_{0}>0$, we obtain

$$
\begin{align*}
L^{\prime}(t)= & -\left[\bar{b}+h_{0} \beta_{2}-\frac{\delta_{3} \bar{h} a^{2}}{2} \beta_{2}-\left(1+\frac{a^{2}}{\delta_{1}}\right) \beta_{1}-\int_{\tau_{1}}^{\tau_{2}}\left[b(s)+c_{0}\right] d s \beta_{3}\right] \int_{0}^{l} x u_{t}^{2} d x \\
& -\frac{1+2 e^{-2 \tau_{2}} \beta_{3}}{2} c_{0} \int_{0}^{l} \int_{\tau_{1}}^{\tau_{2}} x u_{t}^{2}(t-s) d s d x \\
& -\left[e^{-2 \tau_{2}} \beta_{3}-\left(\frac{\beta_{1}}{\delta_{1}}+\frac{\delta_{3} \beta_{2}}{2}\right)\left(\int_{\tau_{1}}^{\tau_{2}} b(s) d s\right)\right] \int_{\tau_{1}}^{\tau_{2}} b(s) x u_{t}^{2}(t-s) d s \\
& -\left[\left(1-\delta_{1} l^{2}-\bar{h}+\frac{\delta \bar{h}}{4}\right) \beta_{1}-\frac{\delta_{2} \bar{h}}{2} \beta_{2}\right] \int_{0}^{l} x u_{x}^{2} \\
& -2 \beta_{3} \int_{0}^{L} \int_{\tau_{1}}^{\tau_{2}} \int_{0}^{1} s e^{-2 p s}\left[b(s)+c_{0}\right] x u_{t}^{2}(t-p s) d p d s d x \\
& +\left[\frac{\beta_{1}}{\delta}+\left(\bar{h}+\frac{\bar{h}+1}{\delta_{2}}+\frac{(\bar{h}+1) l^{2}}{\delta_{3}}\right) \beta_{2}\right]\left(h \circ u_{x}\right)+\left(\frac{1}{2}-\beta_{2}\right)\left(h^{\prime} \circ u_{x}\right) \tag{3.16}
\end{align*}
$$

where

$$
h_{0}=\int_{0}^{t_{0}} h(s) d s
$$

Now, it's time to set the parameters $\beta_{i}$ and $\delta_{i}, i=1,2,3$, so that all coefficients in (3.16) are strictly negative. Then there exist two positive constants $c_{1}$ and $c_{2}$ such that

$$
\begin{equation*}
L^{\prime}(t) \leq-c_{1} E(t)+\frac{c_{2}}{2}\left(h \circ w_{x x}\right), \quad \forall t \geq t_{0} \tag{3.17}
\end{equation*}
$$

Multiplying (3.17) by $\zeta(t)$ and taking into account assumption (H2) and Lemma 2.1, we have

$$
\zeta(t) L^{\prime}(t) \leq-c_{1} \zeta(t) E(t)+\frac{c_{2}}{2} \zeta(t)\left(h \circ w_{x x}\right) \leq-c_{1} \zeta(t) E(t)-c_{2} E^{\prime}(t), \quad \forall t \geq t_{0}
$$

which implies that for all $t \geq t_{0}$,

$$
\left\{\zeta(t) L(t)+c_{2} E(t)\right\}^{\prime} \leq-c_{1} \zeta(t) E(t)+\zeta^{\prime}(t) L(t)
$$

Having $\mathcal{L}(t)=\zeta(t) L(t)+c_{2} E(t)$, we find that

$$
d_{1} E(t) \leq \mathcal{L}(t) \leq d_{1} E(t), \quad d_{1}, d_{2}>0
$$

and exploiting the nonincreasing property of $\zeta(t)$ and (3.2), we get

$$
\begin{equation*}
\mathcal{L}^{\prime}(t) \leq-\alpha \mathcal{L}(t), \quad \forall t \geq t_{0} \tag{3.18}
\end{equation*}
$$

where $\alpha$ is a positive constant.
Integrating the differential inequality (3.18) over $\left(t_{0}, t\right)$ and considering the fact that $\mathcal{L}(t) \sim E(t)$, we get

$$
E(t) \leq \frac{\mathcal{L}\left(t_{0}\right)}{d_{1}} e^{-\alpha \int_{t_{0}}^{t} \zeta(s) d s}, \quad \forall t \geq t_{0}
$$

It remains to estimate $E(t)$ on $[0, t]$. To do this, we take the decay property of the functions $E(t)$, $\mathcal{L}(t), \zeta(t)$ and $e^{-t}$, and find that

$$
E(t) \leq \begin{cases}\frac{\mathcal{L}\left(t_{0}\right)}{d_{1}} e^{-\alpha t_{0}} e^{-\alpha \int_{0}^{t} \zeta(s) d s}, & \forall t \geq t_{0} \\ E(0) e^{-\alpha t_{0}} e^{-\alpha \int_{0}^{t} \zeta(s) d s}, & \forall t<t_{0}\end{cases}
$$

Consequently, (3.15) is established, where

$$
\left.C=\max \left\{\frac{\mathcal{L}\left(t_{0}\right)}{d_{1}}, E(0)\right\} e^{-\alpha t_{0}}\right\}
$$

Example. Note that there is always a large class of relaxation functions satisfying (H1) and (H2), our result (3.15) gives more general decay rate results. For example:

Exponential decay. Let

$$
h(t)=r e^{-(1+t)^{\theta}}, \quad 0<\theta \leq 1
$$

where $r>0$ to be chosen properly, then

$$
\zeta(t)=\theta(1+t)^{\theta-1}
$$

From (3.15), we get

$$
E(t) \leq C_{1} e^{-d(1+t)^{\theta}}
$$

where $C_{1}$ and $d$ are positives constants.
Polynomial decay. Let

$$
h(t)=\frac{r}{(1+t)^{\eta}}, \quad \eta>1
$$

then

$$
\zeta(t)=\frac{\eta}{1+t}
$$

From (3.15), we get

$$
E(t) \leq \frac{C_{2}}{(1+t)^{\eta \kappa}}
$$

where $C_{2}$ and $\kappa$ are positives constants.
Logarithmic decay. Let

$$
h(t)=\frac{r}{[\ln (1+t)]^{\eta}}, \quad \eta>1
$$

then

$$
\zeta(t)=\frac{\eta}{(1+t) \ln (1+t)}
$$

From (3.15), we get

$$
E(t) \leq \frac{C_{3}}{\ln (1+t)^{\eta \kappa}}
$$

where $C_{3}$ and $\kappa$ are positives constants.
For more examples of other types of relaxation functions, consult $[16,17]$.

## Acknowledgements

The authors would like to thank the anonymous referees for their valuable comments and suggestions and also express their gratitude to Directorate-General for Scientific Research and Technological Development (DGRSDT) for the financial support.

## References

[1] M. Aili and A. Khemmoudj, General decay of energy for a viscoelastic wave equation with a distributed delay term in the nonlinear internal dambing. Rend. Circ. Mat. Palermo (2) 69 (2020), no. 3, 861-881.
[2] F. Belhannache and S. A. Messaoudi, On the general stability of a viscoelastic wave equation with an integral condition. Acta Math. Appl. Sin. Engl. Ser. 36 (2020), no. 4, 857-869.
[3] S. Boulaaras and N. Mezouar, Global existence and decay of solutions of a singular nonlocal viscoelastic system with a nonlinear source term, nonlocal boundary condition, and localized damping term. Math. Methods Appl. Sci. 43 (2020), no. 10, 6140-6164.
[4] B. Lekdim and A. Khemmoudj, General decay of energy to a nonlinear viscoelastic twodimensional beam. Appl. Math. Mech. (English Ed.) 39 (2018), no. 11, 1661-1678.
[5] B. Lekdim and A. Khemmoudj, Uniform decay of a viscoelastic nonlinear beam in two dimensional space. Asian Journal of Mathematics and Computer Research 25 (2018), no. 1, 50-73.
[6] B. Lekdim and A. Khemmoudj, Existence and energy decay of solution to a nonlinear viscoelastic two-dimensional beam with a delay. Multidim. Syst. Sign. Process. 32 (2021), 915--931.
[7] B. Lekdim and A. Khemmoudj, Existence and general decay of solution for nonlinear viscoelastic two-dimensional beam with a nonlinear delay. Ric. Mat. (2021); https://doi.org/10.1007/ s11587-021-00598-w.
[8] B. Lekdim and A. Khemmoudj, General stability of two-dimensional viscoelastic nonlinear beam with bending couplings. In 2021 International Conference on Recent Advances in Mathematics and Informatics (ICRAMI), Tebessa, Algeria, pp. 1-4, IEEE, 2021.
[9] H. Mecheri, S. Mesloub and S. A. Messaoudi, On solutions of a singular viscoelastic equation with an integral condition. Georgian Math. J. 16 (2009), no. 4, 761-778.
[10] S. Mesloub, Mixed nonlocal problem for a nonlinear singular hyperbolic equation. Math. Methods Appl. Sci. 33 (2010), no. 1, 57-70.
[11] S. Mesloub and A. Bouziani, On a class of singular hyperbolic equation with a weighted integral condition. Int. J. Math. Math. Sci. 22 (1999), no. 3, 511-519.
[12] S. Mesloub and A. Bouziani, Mixed problem with integral conditions for a certain class of hyperbolic equations. J. Appl. Math. 1 (2001), no. 3, 107-116.
[13] S. Mesloub and F. Mesloub, Solvability of a mixed nonlocal problem for a nonlinear singular viscoelastic equation. Acta Appl. Math. 110 (2010), no. 1, 109-129.
[14] S. Mesloub and S. A. Messaoudi, A three-point boundary-value problem for a hyperbolic equation with a non-local condition. Electron. J. Differential Equations 2002, no. 62, 13 pp.
[15] S. Mesloub and S. A. Messaoudi, Global existence, decay, and blow up of solutions of a singular nonlocal viscoelastic problem. Acta Appl. Math. 110 (2010), no. 2, 705-724.
[16] S. A. Messaoudi, General decay of solutions of a viscoelastic equation. J. Math. Anal. Appl. 341 (2008), no. 2, 1457-1467.
[17] M. I. Mustafa, Well posedness and asymptotic behavior of a coupled system of nonlinear viscoelastic equations. Nonlinear Anal. Real World Appl. 13 (2012), no. 1, 452-463.
[18] E. Piskin, S. M. Boulaaras, H. Kandemir, B. B. Cherif and M. Biomy, On a couple of nonlocal singular viscoelastic equations with damping and general source terms: blow-up of solutions. J. Funct. Spaces 2021, Art. ID 9914386, 9 pp.
[19] S. Wu, Blow-up of solutions for a singular nonlocal viscoelastic equation. J. Partial Differ. Equ. 24 (2011), no. 2, 140-149.

## Authors' addresses:

## Billal Lekdim

1. Department of Mathematics, University Ziane Achour of Djelfa, 17000 Djelfa, Algeria
2. Laboratory of LSD, Faculty of Mathematics, USTHB, P.O. Box 32, El-Alia, 16111 Bab Ezzouar, Algiers, Algeria

E-mail: b.lekdim@univ-djelfa.dz
Mohammed Aili
Laboratory of LSD, Faculty of Mathematics, USTHB, P.O. Box 32, El-Alia, 16111 Bab Ezzouar, Algiers, Algeria

E-mail: ailimaths2015@gmail.com
Ammar Khemmoudj
Laboratory of LSD, Faculty of Mathematics, USTHB, P.O. Box 32, El-Alia, 16111 Bab Ezzouar, Algiers, Algeria

E-mail: akhemmoudj@yahoo.fr

