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ON A NONLOCAL BOUNDARY VALUE PROBLEM FOR
TWO-DIMENSIONAL NONLINEAR SINGULAR
DIFFERENTIAL SYSTEMS

Dedicated to the blessed memory of Professor Levan Magnaradze

Abstract. For two-dimensional nonlinear differential systems with strong singularities with respect to a time variable, unimprovable sufficient conditions for solvability and well-posedness of the Nicoletti type nonlocal boundary value problem are established.

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Let $-\infty < a < b < +\infty$, $C(]a, b[)$ be the space of continuous functions $u :]a, b[\rightarrow R$ with finite right and left limits $u(a+)$ and $u(b-)$ at the points a and b and with the norm $\|u\|_C = \sup \{|u(t)| : a < t < b\}$, and let $L^2(]a, b[)$ be the space of square integrable functions $u :]a, b[\rightarrow R$ with the norm

$$\|u\|_{L^2} = \left(\int_a^b u^2(t) dt \right)^{1/2}.$$

By $C_0^{1,2}(]a, b[; R^2)$ we denote the space of vector functions $(u_1, u_2) :]a, b[\rightarrow R^2$ with continuously differentiable components u_1 and u_2 , satisfying the conditions

$$u_1(a+) = 0, \quad \int_a^b (u_1'^2(t) + u_2^2(t)) dt < +\infty.$$

We consider the nonlinear differential system

$$\frac{du_1}{dt} = f_1(t, u_2), \quad \frac{du_2}{dt} = f_2(t, u_1) \tag{1}$$

with the Nicoletti type nonlocal boundary conditions

$$u_1(a+) = 0, \quad u_2(b-) = \varphi(u_1, u_2). \tag{2}$$

Here $f_1 :]a, b[\times R \rightarrow R$ and $f_2 :]a, b[\times R \rightarrow R$ are continuous functions, and $\varphi : C(]a, b[) \times L^2(]a, b[) \rightarrow R$ is a continuous functional.

A vector function $(u_1, u_2) :]a, b[\rightarrow R^2$ is said to be a solution of the problem (1), (2) if:

(i) u_1 and u_2 are continuously differentiable and satisfy the system (1) at every point of the interval $]a, b[$;

(ii) $u_1 \in C(]a, b[)$, $u_2 \in L^2(]a, b[)$, and the equalities (2) are satisfied.

In the present paper, unimprovable in a certain sense conditions are established guaranteeing, respectively, the solvability of (1), (2) in the space $C_0^{1,2}(]a, b[; R^2)$ and the stability of its solution with respect to small perturbations of right-hand sides of (1) and the functional φ . In contrast to the results from [2]–[6], concerning the solvability and well-posedness of the Nicoletti type problems, the theorems below cover the case, where the system (1) with respect to a time variable has a strong singularity at the point a in the Agarwal–Kiguradze sense [1], i.e., the case, where

$$\int_a^b (t-a) \left(|f_2(t, x)| - f_2(t, x) \operatorname{sgn}(x) \right) dt = +\infty \quad \text{for } x \neq 0.$$

Along with the problem (1), (2) we consider the auxiliary problem

$$\frac{du_1}{dt} = \lambda f_1(t, u_2), \quad \frac{du_2}{dt} = \lambda \delta(t) f_2(t, u_1), \quad (3)$$

$$u_1(a+) = 0, \quad u_2(b-) = \lambda \varphi(u_1, u_2), \quad (4)$$

dependent on a parameter $\lambda \in [0, 1]$ and an arbitrary continuous function $\delta : [a, b] \rightarrow [0, 1]$.

Theorem 1 (A principle of a priori boundedness). *Let there exist a nonnegative function $g \in L^2(]a, b[)$ and a positive constant ρ such that*

$$|f_1(t, x)| \leq g(t)(1 + |x|) \quad \text{for } a < t < b, \quad x \in R,$$

and for any number $\lambda \in [0, 1]$ and an arbitrary continuous function $\delta : [a, b] \rightarrow [0, 1]$ every solution (u_1, u_2) of the problem (3), (4) admits the estimate

$$\|u_1'\|_{L^2} + \|u_2\|_{L^2} < \rho.$$

Then the problem (1), (2) has at least one solution in the space $C_0^{1,2}(]a, b[; R^2)$.

Consider now the case, where

$$\begin{aligned} & \varphi(u_1, u_2) \operatorname{sgn}(u_1(b-)) \leq \\ & \leq \alpha_0 + \alpha_1 \|u_1'\|_{L^2} + \alpha_2 \|u_2\|_{L^2} \quad \text{for } (u_1, u_2) \in C_0^{1,2}(]a, b[; R^2), \end{aligned} \quad (5)$$

and in the domain $]a, b[\times R$ the inequalities

$$\ell_0 |x| \leq [f_1(t, x) - f_1(t, 0)] \operatorname{sgn}(x) \leq \ell_1 |x|, \quad (6)$$

$$[f_2(t, x) - f_2(t, 0)] \operatorname{sgn}(x) \geq -\frac{\ell}{(t-a)^2} |x| \quad (7)$$

are fulfilled.

On the basis of Theorem 1, the following theorem can be proved.

Theorem 2. *Let*

$$\int_a^b f_1^2(t, 0) dt < +\infty, \quad \int_a^b (t-a)^{1/2} |f_2(t, 0)| dt < +\infty, \quad (8)$$

and let the conditions (5)–(7) hold, where $\alpha_i \geq 0$ ($i = 0, 1, 2$), $\ell_k > 0$ ($k = 0, 1$), and $\ell \geq 0$ are constants such that

$$(b-a)^{1/2} (\alpha_1 \ell_1 + \alpha_2) \ell_1 + 4\ell_1^2 \ell < \ell_0. \quad (9)$$

Then the problem (1), (2) has at least one solution in the space $C_0^{1,2}(]a, b[; R^2)$.

Particular case of the boundary conditions (2) are the multi-point boundary conditions

$$u_1(a+) = 0, \quad u_2(b-) = \sum_{k=1}^{n-1} \beta_k u_1(t_k) + \beta_n u_1(b-) + \beta_0, \quad (10)$$

where $\beta_k \in R$ ($k = 0, \dots, n$).

Suppose

$$[\beta_n]_+ = \frac{1}{2} (|\beta_n| + \beta_n).$$

From Theorem 2 it follows

Corollary 1. *Let the conditions (6)–(8) be satisfied, where $\ell_k > 0$ ($k = 0, 1$) and $\ell \geq 0$ are constants such that*

$$\frac{2}{\pi} (b-a)^{1/2} \left(\sum_{k=1}^{n-1} |\beta_k| (t_k - a)^{1/2} + [\beta_n]_+ (b-a)^{1/2} \right) \ell_1^2 + 4\ell_1^2 \ell < \ell_0. \quad (11)$$

Then the problem (1), (10) has at least one solution in the space $C_0^{1,2}(]a, b[; R^2)$.

Now we consider the perturbed problem

$$\frac{dv_1}{dt} = f_1(t, v_2) + q_1(t), \quad \frac{dv_2}{dt} = f_2(t, v_1) + q_2(t), \quad (12)$$

$$v_1(a+) = 0, \quad v_2(b-) = \varphi(v_1, v_2) + \alpha, \quad (13)$$

and we introduce the following

Definition. The problem (1), (2) is said to be **well-posed** in the space $C_0^{1,2}(]a, b[; R^2)$ if it has a unique solution (u_1, u_2) in that space and there exists a positive constant r such that for any continuous functions $q_i :]a, b[\rightarrow R$ ($i = 1, 2$), satisfying the condition

$$\nu(q_1, q_2) = \left(\int_a^b q_1^2(t) dt \right)^{1/2} + \int_a^b (t-a)^{1/2} |q_2(t)| dt < +\infty,$$

and for any real number α , the problem (12), (13) has at least one solution $(v_1, v_2) \in C_0^{1,2}(]a, b[; R^2)$, and every such solution admits the estimate

$$\|v_1' - u_1'\|_{L^2} + \|v_2 - u_2\|_{L^2} \leq r(\nu(q_1, q_2) + |\alpha|).$$

Theorem 3. *Let*

$$\begin{aligned} \varphi(u_1, u_2) \operatorname{sgn}(u_1(b-)) &\leq \\ &\leq \alpha_1 \|u_1'\|_{L^2} + \alpha_2 \|u_2\|_{L^2} \quad \text{for } (u_1, u_2) \in C_0^{1,2}(]a, b[; R^2), \end{aligned}$$

and let in the domain $]a, b[\times R$ the conditions

$$\ell_0 |x| \leq f_1(t, x) \operatorname{sgn}(x) \leq \ell_1 |x|, \quad (14)$$

$$f_2(t, x) \operatorname{sgn}(x) \geq -\frac{\ell}{(t-a)^2} |x| \quad (15)$$

be fulfilled, where $\alpha_i \geq 0$ ($i = 1, 2$), $\ell_k > 0$ ($k = 0, 1$), and $\ell \geq 0$ are constants, satisfying the inequality (9). Then the problem (1), (2) is well-posed in the space $C_0^{1,2}(]a, b[; R^2)$.

In the case, where the boundary conditions (2) have the form

$$u_1(a+) = 0, \quad u_2(b-) = \sum_{k=1}^{n-1} \beta_k u_1(t_k) + \beta_n u_1(b-), \quad (16)$$

Theorem 3 yields

Corollary 2. *Let in the domain $]a, b[\times R$ the conditions (14) and (15) be satisfied, where $\ell_k > 0$ ($k = 0, 1$) and $\ell \geq 0$ are constants, satisfying the inequality (11). Then the problem (1), (16) is well-posed in the space $C_0^{1,2}(]a, b[; R^2)$.*

As an example, we consider the differential system

$$\frac{du_1}{dt} = p_1(t, u_2)u_2, \quad \frac{du_2}{dt} = \frac{p_2(t, u_1)}{(t-a)^2} u_1, \quad (17)$$

where $p_1 :]a, b[\times R \rightarrow R$ and $p_2 :]a, b[\times R \rightarrow R$ are continuous functions. For this system from Corollary 2 it follows

Corollary 3. *Let in the domain $]a, b[\times R$ the conditions*

$$\ell_0 \leq p_1(t, x) \leq \ell_1, \quad p_2(t, x) \geq -\ell$$

be satisfied, where $\ell_i > 0$ ($i = 0, 1$) and $\ell \geq 0$ are constants, satisfying the inequality (11). Then the problem (17), (16) is well-posed.

Remark 1. If the conditions of Corollary 3 are satisfied and in the domain $]a, b[\times R$ the inequality

$$p_2(t, x) \leq -\bar{\ell}$$

holds, where $\bar{\ell}$ is a positive constant, then the system (17) with respect to a time variable has a strong singularity at the point a in the Agarwal–Kiguradze sense.

Remark 2. The condition (9) in Theorems 2 and 3 is unimprovable and it cannot be replaced by the condition

$$(b-a)^{1/2}(\alpha_1 \ell_1 + \alpha_2) \ell_1 + 4\ell_1^2 \ell \leq \ell_0.$$

Also, the strict inequality (11) in Corollaries 1–3 cannot be replaced by the non-strict one

$$\frac{2}{\pi} (b-a)^{1/2} \left(\sum_{k=1}^{n-1} |\beta_k| (t_k - a)^{1/2} + [\beta_n]_+ (b-a)^{1/2} \right) \ell_1^2 + 4\ell_1^2 \ell \leq \ell_0.$$

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