

## On Investigation of Non-Linear Differential Systems with Mixed Boundary Conditions

**A. Rontó**

*Faculty of Business and Management, Brno University of Technology  
Brno, Czech Republic  
E-mail: andras.ronto@vut.cz*

**M. Rontó**

*Institute of Mathematics, University of Miskolc, Miskolc, Hungary  
E-mail: matronto@uni-miskolc.hu*

**N. Rontóová**

*Faculty of Business and Management, Brno University of Technology  
Brno, Czech Republic  
E-mail: Natalie.Rontoova@vut.cz*

**I. Varga**

*Faculty of Mathematics, Uzhhorod National University, Uzhhorod, Ukraine  
E-mail: iana.varga@uzhnu.edu.ua*

We study a non-linear differential system with mixed boundary conditions on a compact interval  $[a, b]$

$$\begin{aligned} x'(t) &= f_1(t, x(t), y(t)), \quad t \in [a, b], \\ y'(t) &= f_2(t, x(t), y(t)), \quad t \in [a, b], \end{aligned} \tag{1}$$

$$x(a) = x(b), \tag{2}$$

$$\phi(y) = d, \tag{3}$$

where  $x : [a, b] \rightarrow \mathbb{R}^p$ ,  $y : [a, b] \rightarrow \mathbb{R}^q$ ,  $d \in \mathbb{R}^q$ . It is supposed that  $f_1, f_2$  are continuous as functions  $f_1 : [a, b] \times U \times V \rightarrow \mathbb{R}^p$ ,  $f_2 : [a, b] \times U \times V \rightarrow \mathbb{R}^q$ , where bounded sets  $U \subset \mathbb{R}^p$ ,  $V \subset \mathbb{R}^q$  are specified later (see (4)). We also assume the continuity of  $\phi : V \rightarrow \mathbb{R}^q$ . Continuously differentiable solutions of problem (1)–(3) are considered. For problem (1)–(3) we will use an approach similar to that of [2, 3].

For vectors  $x = \text{col}(x_1, \dots, x_n) \in \mathbb{R}^n$  the notation  $|x| = \text{col}(|x_1|, \dots, |x_n|)$  is used and the inequalities between vectors are understood componentwise; the operations max and min for vectors are understood similarly.  $I$  denotes the identity matrix. For a non-negative vector  $\varrho$ , we define the componentwise  $\varrho$ -neighbourhood of a point  $z$  by putting

$$\mathcal{O}_\varrho(z) = \{\xi \in \mathbb{R}^n : |\xi - z| \leq \varrho\}.$$

The  $\varrho$ -neighbourhood of a set  $\Omega \subset \mathbb{R}^n$  is then defined as  $\mathcal{O}_\varrho(\Omega) = \bigcup_{z \in \Omega} \mathcal{O}_\varrho(z)$ . The particular sets  $\Omega$  and values of  $\varrho$  used in the assumptions are specified below in (4), (5).

We will use a reduction of the given problem to a family of simpler auxiliary boundary value problems [2]. Let us fix certain compact convex sets  $\mathcal{V}_a \subset \mathbb{R}^q$ ,  $\mathcal{V}_b \subset \mathbb{R}^q$  and  $\mathcal{U} \subset \mathbb{R}^p$ , take some positive vectors  $\varrho_U \in \mathbb{R}^p$ ,  $\varrho_V \in \mathbb{R}^q$  and put

$$U = \mathcal{O}_{\varrho_U}(\mathcal{U}), \quad V = \mathcal{O}_{\varrho_V}(\mathcal{C}(\mathcal{V}_a, \mathcal{V}_b)), \tag{4}$$

where

$$\mathcal{C}(X, Y) = \{(1 - \theta)x + \theta y : x \in X, y \in Y, 0 \leq \theta \leq 1\}.$$

It is convenient to choose the sets  $\mathcal{U}$ ,  $\mathcal{V}_a$ ,  $\mathcal{V}_b$  as some parallelepipeds. We will consider solutions  $(x, y)$  of problem (1)–(3) with values  $x(a) = x(b) \in \mathcal{U}$ ,  $y(a) \in \mathcal{V}_a$ ,  $y(b) \in \mathcal{V}_b$  and range in  $U \times V$ .

Introduce the notation

$$\delta_{U \times V}(f_k) = \frac{1}{2} \left( \max_{[a,b] \times U \times V} f_k - \min_{[a,b] \times U \times V} f_k \right), \quad k = 1, 2,$$

and assume that the positive vectors  $\varrho_U$ ,  $\varrho_V$  can be chosen so that

$$\varrho_U \geq \frac{b - a}{2} \delta_{U \times V}(f_1), \quad \varrho_V \geq \frac{b - a}{2} \delta_{U \times V}(f_2). \tag{5}$$

Let  $f_1$ ,  $f_2$  satisfy the Lipchitz condition on  $U$ ,  $V$ :

$$|f_k(t, x, y) - f_k(t, \tilde{x}, \tilde{y})| \leq K_{k1}|x - \tilde{x}| + K_{k2}|y - \tilde{y}|, \quad k = 1, 2, \tag{6}$$

for  $t \in [a, b]$ ,  $\{x, \tilde{x}\} \subset U$ ,  $\{y, \tilde{y}\} \subset V$ , where  $K_{11}$ ,  $K_{12}$ ,  $K_{21}$ ,  $K_{22}$  are positive matrices of dimensions  $p \times p$ ,  $p \times q$ ,  $q \times p$ ,  $q \times q$ . We assume that the maximal in modulus eigenvalue of the matrix  $K = \begin{pmatrix} K_{11} & K_{12} \\ K_{21} & K_{22} \end{pmatrix}$  is small enough:

$$r(Q) < 1, \tag{7}$$

where  $Q = \frac{3}{10} (b - a)K$ .

We introduce the vectors of parameters  $z \in \mathbb{R}^p$ ,  $\gamma \in \mathbb{R}^q$ ,  $\lambda \in \mathbb{R}^q$  by formally putting

$$z = x(a) = x(b), \quad \gamma = y(a), \quad \lambda = y(b)$$

and, instead of problem (1)–(3), consider the following two auxiliary boundary value problems with periodic and two-point linear separated conditions at  $a$  and  $b$ :

$$x'(t) = f_1(t, x, y), \quad t \in [a, b], \tag{8}$$

$$x(a) = z, \quad x(b) = z \tag{9}$$

and

$$y'(t) = f_2(t, x, y), \quad t \in [a, b], \tag{10}$$

$$y(a) = \gamma, \quad y(b) = \lambda. \tag{11}$$

As will be seen from statements below, there is a certain relation to the original problem depending on the choice of the values of  $z$ ,  $\gamma$  and  $\lambda$ . Let us relate problems (8), (9) and (10), (11) to the sequences of functions

$$x_{m+1}(t, z, \gamma, \lambda) = z + \int_a^t f_1(s, x_m(s, z, \gamma, \lambda), y_m(s, z, \gamma, \lambda)) ds - \frac{t - a}{b - a} \int_a^b f_1(s, x_m(s, z, \gamma, \lambda), y_m(s, z, \gamma, \lambda)) ds \tag{12}$$

and

$$y_{m+1}(t, z, \gamma, \lambda) = \gamma + \int_a^t f_2(s, x_m(s, z, \gamma, \lambda), y_m(s, z, \gamma, \lambda)) ds - \frac{t-a}{b-a} \int_a^b f_2(s, x_m(s, z, \gamma, \lambda), y_m(s, z, \gamma, \lambda)) ds + \frac{t-a}{b-a} (\lambda - \gamma), \quad (13)$$

where  $t \in [a, b]$ ,  $m = 0, 1, \dots$ ,

$$x_0(t, z) = z, \quad y_0(t, \gamma, \lambda) = \gamma + \frac{t-a}{b-a} (\lambda - \gamma).$$

**Theorem 1.** *Let conditions (5), (6), (7) be fulfilled. Then, for all fixed  $z \in \mathcal{U}$ ,  $\gamma \in \mathcal{V}_a$ ,  $\lambda \in \mathcal{V}_b$ :*

1. *Each of the functions of sequence (12) has range in  $U$ , is continuously differentiable on  $[a, b]$ , and satisfies conditions (9). The limit*

$$x_\infty(t, z, \gamma, \lambda) = \lim_{m \rightarrow \infty} x_m(t, z, \gamma, \lambda) \quad (14)$$

*exists uniformly in  $(t, z, \gamma, \lambda) \in [a, b] \times \mathcal{U} \times \mathcal{V}_a \times \mathcal{V}_b$ . Function (14) satisfies the boundary condition (9).*

2. *Each of the functions of sequence (13) has range in  $V$ , is continuously differentiable on  $[a, b]$ , and satisfies conditions (11). The limit*

$$y_\infty(t, z, \gamma, \lambda) = \lim_{m \rightarrow \infty} y_m(t, z, \gamma, \lambda) \quad (15)$$

*exists uniformly in  $(t, z, \gamma, \lambda) \in [a, b] \times \mathcal{U} \times \mathcal{V}_a \times \mathcal{V}_b$ . Function (15) satisfies the boundary condition (11).*

3. *The functions  $x_\infty(\cdot, z, \gamma, \lambda)$ ,  $y_\infty(\cdot, z, \gamma, \lambda)$  form the unique continuously differentiable solution of the system of integral equations*

$$x(t) = z + \int_a^t f_1(s, x(s), y(s)) ds - \frac{t-a}{b-a} \int_a^b f_1(s, x(s), y(s)) ds,$$

$$y(t) = \gamma + \frac{t-a}{b-a} (\lambda - \gamma) + \int_a^t f_2(s, x(s), y(s)) ds - \frac{t-a}{b-a} \int_a^b f_2(s, x(s), y(s)) ds.$$

4. *The following error estimate holds:*

$$|x_\infty(t, z, \gamma, \lambda) - x_m(t, z, \gamma, \lambda)| \leq \frac{10}{9} \alpha_1(t) \left\{ Q^m (I_{p+q} - Q)^{-1} \begin{pmatrix} \delta_{U \times V}(f_1) \\ \delta_{U \times V}(f_2) \end{pmatrix} \right\}_1^p,$$

$$|y_\infty(t, z, \gamma, \lambda) - y_m(t, z, \gamma, \lambda)| \leq \frac{10}{9} \alpha_1(t) \left\{ Q^m (I_{p+q} - Q)^{-1} \begin{pmatrix} \delta_{U \times V}(f_1) \\ \delta_{U \times V}(f_2) \end{pmatrix} \right\}_{p+1}^{p+q},$$

where

$$\alpha_1(t) = 2(t-a) \left( 1 - \frac{t-a}{b-a} \right), \quad t \in [a, b],$$

and  $\{u\}_1^p = \text{col}(u_1, u_2, \dots, u_p)$ ,  $\{u\}_{p+1}^{p+q} = \text{col}(u_{p+1}, u_{p+2}, \dots, u_{p+q})$  for a vector  $u \in \mathbb{R}^n$ .

The idea of proof is to show that (12), (13) are Cauchy sequences in the Banach spaces  $C([a, b], \mathbb{R}^p)$  and  $C([a, b], \mathbb{R}^q)$ , respectively.

Under conditions of Theorem 1, functions (14), (15) are solutions of the Cauchy problems for the forced systems

$$\begin{aligned} x'(t) &= f_1(t, x(t), y(t)) + \Delta_U(z, \gamma, \lambda), \quad x(a) = z, \\ y'(t) &= f_2(t, x(t), y(t)) + \Delta_V(z, \gamma, \lambda), \quad x(a) = \gamma, \end{aligned}$$

where  $\Delta_U : \mathcal{U} \times \mathcal{V}_a \times \mathcal{V}_b \rightarrow \mathbb{R}^p$  and  $\Delta_V : \mathcal{U} \times \mathcal{V}_a \times \mathcal{V}_b \rightarrow \mathbb{R}^p$  are the mappings given by the formulas

$$\begin{aligned} \Delta_U(z, \gamma, \lambda) &= -\frac{1}{b-a} \int_a^b f_1(s, x_\infty(s, z, \gamma, \lambda), y_\infty(s, z, \gamma, \lambda)) ds, \\ \Delta_V(z, \gamma, \lambda) &= \frac{1}{b-a} (\lambda - \gamma) - \frac{1}{b-a} \int_a^b f_2(s, x_\infty(s, z, \gamma, \lambda), y_\infty(s, z, \gamma, \lambda)) ds. \end{aligned}$$

**Theorem 2.** *Under the assumptions of Theorem 1, the limit functions (14), (15) of sequences (12), (13) form a solution of the boundary value problem (1)–(3) if and only if the parameters  $(z, \gamma, \lambda)$  satisfy the system of  $p + 2q$  equations*

$$\Delta_U(z, \gamma, \lambda) = 0, \quad \Delta_V(z, \gamma, \lambda) = 0, \quad \Lambda(z, \gamma, \lambda) = 0, \tag{16}$$

where

$$\Lambda(z, \gamma, \lambda) = \phi(y_\infty(\cdot, \gamma, \lambda)) - d. \tag{17}$$

The proof can be carried out similarly to [1, 2]. The next statement shows that the system of determining equations (16) determines all possible solutions of the original non-linear boundary value problem (1)–(3) having range in  $U \times V$ .

**Theorem 3.** *Let the assumptions of Theorem 1 hold.*

1. *If there exist some  $(z_*, \gamma_*, \lambda_*) \in \mathcal{U} \times \mathcal{V}_a \times \mathcal{V}_b$  satisfying the system of determining equations (16), then problem (1)–(3) has a solution  $(x_*, y_*)$  such that*

$$x_*(a) = x_*(b) = z_*, \quad y_*(a) = \gamma_*, \quad y_*(b) = \lambda_*$$

and, moreover,

$$x_*(\cdot) = x_\infty(\cdot, z_*, \gamma_*, \lambda_*), \quad y_*(\cdot) = y_\infty(\cdot, z_*, \gamma_*, \lambda_*).$$

2. *If the boundary value problem (1)–(3) has a solution  $(x_*, y_*)$  with the range in  $U \times V$ , then the system of determining equations (16) is satisfied with*

$$z = x_*(a), \quad \gamma = y_*(a), \quad \lambda = y_*(b).$$

The proof can be carried out by analogy to [1, 2].

The solvability of system (16), under additional conditions, can be proved if a solution of an approximate determining system

$$\Delta_{U,m}(z, \gamma, \lambda) = 0, \quad \Delta_{V,m}(z, \gamma, \lambda) = 0, \quad \Lambda_m(z, \gamma, \lambda) = 0,$$

has been found, where  $m$  is fixed and  $\Delta_{U,m}, \Delta_{V,m}, \Lambda_m$  are defined similarly to (17) with  $x_\infty, y_\infty$  replaced by  $x_m, y_m$ . Practical calculations using Maple confirm the constructiveness of the proposed approach.

## References

- [1] A. Rontó and M. Rontó, Successive approximation techniques in non-linear boundary value problems for ordinary differential equations. *Handbook of differential equations: ordinary differential equations. Vol. IV*, 441–592, Handb. Differ. Equ., Elsevier/North-Holland, Amsterdam, 2008.
- [2] A. Rontó, M. Rontó and J. Varha, A new approach to non-local boundary value problems for ordinary differential systems. *Appl. Math. Comput.* **250** (2015), 689–700.
- [3] A. Rontó, M. Rontó and I. Varga, Necessary solvability conditions for non-linear integral boundary value problems. *Reports of QUALITDE* **1** (2022), 179–183.