

## Asymptotic Representation for Solutions of Systems of Differential Equations with Rapidly Varying Nonlinearities

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We consider the system of differential equations

$$\begin{cases} y'_1 = \alpha_1 p_1(t) \varphi_2(y_2), \\ y'_2 = \alpha_2 p_2(t) \varphi_1(y_1), \end{cases} \tag{1}$$

where  $\alpha_i \in \{-1, 1\}$  ( $i = 1, 2$ ),  $p_i : [a, \omega[ \rightarrow ]0, +\infty[$  ( $i = 1, 2$ ) are continuous functions,  $-\infty < a < \omega \leq +\infty$ ,  $\varphi_i : \Delta(Y_i^0) \rightarrow ]0; +\infty[$  ( $i = 1, 2$ ) ( $\Delta(Y_i^0)$  is a one-sided neighborhood of  $Y_i^0$ ,  $Y_i^0$  equals either 0, or  $\pm\infty$ ) are twice continuously differentiable functions that satisfy the conditions

$$\begin{aligned} \varphi'_i(z) \neq 0 \text{ when } z \in \Delta(Y_i^0), \quad \lim_{\substack{z \rightarrow Y_i^0 \\ z \in \Delta(Y_i^0)}} \varphi_i(z) = \Phi_i^0 \in \{0, +\infty\}, \\ \lim_{\substack{z \rightarrow Y_i^0 \\ z \in \Delta(Y_i^0)}} \frac{\varphi''_i(z) \varphi_i(z)}{[\varphi'_i(z)]^2} = \gamma_i \quad (i = 1, 2). \end{aligned}$$

Such system of differential equations when  $\varphi_i(y_i) = |y_i|^{\sigma_i}$  ( $i = \overline{1, n}$ ) is called the system of differential equations of Emden–Fowler type. While  $t \uparrow \omega$ , the asymptotic representations for its non-oscillating solutions were established in [2, 6]. When  $\gamma_i \neq 1$  ( $i = 1, 2$ ), system (1) is the system with regularly varying nonlinearities. Such system of differential equations had been investigated in [4].

This work considers situation, when  $\gamma_1 = 1$ , that means function  $\varphi_1$  is rapidly varying when  $y_1 \rightarrow Y_1^0$  [1, 5]. In this situation, special case of system (1) is a two-term non-autonomous differential equation with rapidly varying nonlinearity (see [3]).

A solution  $(y_i)_{i=1}^2$  of system (1), defined on the interval  $[t_0, \omega[ \subset [a, \omega[$ , is called  $\mathcal{P}_\omega(\Lambda_1, \Lambda_2)$ -solution, if functions  $u_i(t) = \varphi_i(y_i(t))$  ( $i = 1, 2$ ) satisfy the following conditions:

$$\lim_{t \uparrow \omega} u_i(t) = \Phi_i^0, \quad \lim_{t \uparrow \omega} \frac{u_i(t) u'_{i+1}(t)}{u'_i(t) u_{i+1}(t)} = \Lambda_i \quad (i = 1, 2).$$

Note that the second condition in the definition of  $\mathcal{P}_\omega(\Lambda_1, \Lambda_2)$ -solution implies

$$\prod_{i=1}^2 L_i = 1.$$

For system (1) in case, when  $\Lambda_i \neq 0$  ( $i = 1, 2$ ), the necessary and sufficient conditions for the existence of  $\mathcal{P}_\omega(\Lambda_1, \Lambda_2)$ -solutions are established, as well as the asymptotic representation for these solutions when  $t \uparrow \omega$ .

In order to formulate the theorem, we introduce several auxiliary notations:

$$I_i(t) = \begin{cases} \int_{A_1}^t p_1(\tau) d\tau & \text{for } i = 1, \\ \int_{A_2}^t I_1(\tau)p_2(\tau) d\tau & \text{for } i = 2, \end{cases} \quad \beta_i = \begin{cases} -\Lambda_1, & \text{if } i = 1, \\ -1, & \text{if } i = 2, \end{cases}$$

where limits of integration  $A_i \in \{\omega, a\}$  are chosen in such a way that corresponding integral  $I_i$  aims either to zero, or to  $\infty$  when  $t \uparrow \omega$ .

$$A_i^* = \begin{cases} 1, & \text{if } A_i = a, \\ -1, & \text{if } A_i = \omega \end{cases} \quad (i = 1, 2).$$

**Theorem.** Let  $\Lambda_i \in \mathbb{R} \setminus \{0\}$  ( $i = 1, 2$ ) and  $\gamma_1 = 1$ . Then for the existence of  $\mathcal{P}_\omega(\Lambda_1, \Lambda_2)$  – solutions of (1) it is necessary and, if algebraic equation

$$\nu[\nu + (1 - \gamma_2)\Lambda_1] = 1$$

does not have roots with zero real part, it is also sufficient that for each  $i = 1, 2$

$$\lim_{t \uparrow \omega} \frac{I_i(t)I'_{i+1}(t)}{I'_i(t)I_{i+1}(t)} = \Lambda_i \frac{\beta_{i+1}}{\beta_i}$$

and following conditions are satisfied

$$A_i^* \beta_i > 0 \text{ when } \Phi_i^0 = +\infty, \quad A_i^* \beta_i < 0 \text{ when } \Phi_i^0 = 0, \\ \text{sign} [\alpha_i A_i^* \beta_i] = \text{sign } \varphi'_i(z).$$

Moreover, components of each solution of that type admit the following asymptotic representation when  $t \uparrow \omega$

$$\frac{\varphi_i(y_i(t))}{\varphi'_i(y_i(t))\varphi_{i+1}(y_{i+1}(t))} = \alpha_i \beta_i I_i(t)[1 + o(1)], \quad \text{if } i = 1, \\ \frac{\varphi_i(y_i(t))}{\varphi'_i(y_i(t))\varphi_{i+1}(y_{i+1}(t))} = \alpha_i \beta_i \frac{I_i(t)}{I_1(t)} [1 + o(1)], \quad \text{if } i = 2.$$

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