

Stability and Exponential Stability Indices of a Linear System Depending on a Parameter

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1 Introduction

For a given integer $n \geq 2$ let \mathcal{M}_n denote the class of linear differential systems

$$\dot{x} = A(t)x, \quad x \in \mathbb{R}^n, \quad t \in \mathbb{R}_+ \equiv [0, +\infty), \quad (1.1)$$

with continuous bounded coefficients defined on \mathbb{R}_+ .

Let us identify the system (1.1) with the matrix-valued function $A : \mathbb{R}_+ \rightarrow \mathbb{R}^{n \times n}$ and use the following notation: $A \in \mathcal{M}_n$.

Recall that the *characteristic exponent* (or the *Lyapunov exponent*) of a function $x(\cdot)$ is [6, p. 552], [1, p. 25]

$$\chi(x) = \overline{\lim}_{t \rightarrow +\infty} \ln \|x(t)\|^{1/t}.$$

We denote by $s(A)$ the stability index of a system $A \in \mathcal{M}_n$, i.e. the dimension of the linear subspace of bounded solutions to this system, and by $es(A)$ its exponential stability index, that is the dimension of the linear subspace of solutions to this system having negative characteristic exponents. One can see that the following inequality holds:

$$s(A) \geq es(A).$$

O. Perron in his paper [7] constructed an example of a system $A \in \mathcal{M}_2$ and its continuous exponentially decaying (2×2) -dimensioned perturbation $Q(\cdot)$ such that the initial system has its exponential stability index equal to 2, and the perturbed system

$$\dot{x} = (A(t) + Q(t))x, \quad x \in \mathbb{R}^2, \quad t \in \mathbb{R}_+,$$

has both its stability indices equal to 1.

There is another interesting example presented by O. Perron [8]. He describes a diagonal system $A \in \mathcal{M}_2$ with the exponential stability index equal to 2 (and with the same stability index) and its continuous higher-order perturbation $f(\cdot, \cdot)$ such that the stability index of the perturbed system $\dot{x} = A(t)x + f(t, x)$ equals 0 (and so does its exponential stability index).

Thus, both examples demonstrate the effect of loss of stability. These examples had initiated a lot of research aimed to learn how perturbations of different types can affect stability of systems in \mathcal{M}_n . The results obtained in this direction form a considerable part of the contemporary Lyapunov exponent theory. When a perturbation is in a certain sense “small”, the effect of loss of stability is called the Perron effect [5, Chapter 4]. Starting with the paper [4], this term is used only when perturbations do not decrease the Lyapunov exponents of the initial system, and we adhere to this terminology.

2 Statement of the problem and the main result

In this paper we present a kind of generalization of the Perron effect. To this end, for a system $A \in \mathcal{M}_n$ and a metric space M we consider the class $\mathcal{E}_n[A](M)$ consisting of jointly continuous matrix-valued functions $Q : \mathbb{R}_+ \times M \rightarrow \mathbb{R}^{n \times n}$ satisfying the following two conditions.

The first one is the estimate

$$\|Q(t, \mu)\| \leq C_Q \exp(-\sigma_Q t) \text{ for all } (t, \mu) \in \mathbb{R}_+ \times M,$$

where C_Q and σ_Q are positive constants (generally, different for each function Q).

The second condition is that the stability and exponential stability indices of the perturbed system $A + Q$, being functions of $\mu \in M$ and denoted by $s(\cdot; A + Q)$ and $es(\cdot; A + Q)$, do not exceed the corresponding stability indices of the system A , i.e.

$$s(\mu; A + Q) \leq s(A) \text{ and } es(\mu; A + Q) \leq es(A) \text{ for all } \mu \in M.$$

We state the problem in the following way. Our task is for any integer $n \geq 2$ and metric space M to give a complete functional description of the class of pairs $((s(A), es(A)), (s(\cdot; A + Q), es(\cdot; A + Q)))$ composed of the stability indices of the initial system A and those of the perturbed system $A + Q$. The system A here ranges over \mathcal{M}_n , and for every A the matrix-valued function Q ranges over the set $\mathcal{E}_n[A](M)$. Thus, our problem is to present a complete functional description of the following class:

$$\Sigma \mathcal{E}_n(M) \equiv \left\{ ((s(A), es(A)), (s(\cdot; A + Q), es(\cdot; A + Q))) \mid A \in \mathcal{M}_n, Q \in \mathcal{E}_n[A](M) \right\}.$$

Before we could formulate the main result, let us remind the reader that a function $f : M \rightarrow \mathbb{R}$ is called [3, pp. 266–267] a function of the class $(F_\sigma, *)$ if for any $r \in \mathbb{R}$ the preimage of the half-line $(r, +\infty)$ is an F_σ -set in the space M , i.e. it can be represented as a countable union of closed subsets of M . In particular, the class $(F_\sigma, *)$ is a subclass of Baire class 2 [3, p. 294]. Let us also denote the set $\{0, 1, \dots, n\}$ by \mathcal{Z}_n .

The solution to the problem is stated by the following

Theorem 1. *Let M be a metric space and $n \geq 2$ an integer. A pair $((\alpha_0, \beta_0), (\alpha(\cdot), \beta(\cdot)))$ with $\alpha_0, \beta_0 \in \mathcal{Z}_n$ and $\alpha(\cdot), \beta(\cdot) : M \rightarrow \mathcal{Z}_n$ belongs to the class $\Sigma \mathcal{E}_n(M)$ if and only if the following conditions are met:*

- 1) $\alpha_0 \geq \beta_0$;
- 2) $\alpha(\mu) \geq \beta(\mu)$ for all $\mu \in M$;
- 3) $\alpha(\mu) \leq \alpha_0, \beta(\mu) \leq \beta_0$ for all $\mu \in M$;
- 4) the functions $\alpha(\cdot)$ and $\beta(\cdot)$ are of the class $(F_\sigma, *)$.

3 Corollaries and remarks

Let M be a metric space. For an integer $n \geq 2$ we consider a family of linear systems depending on a parameter $\mu \in M$ of the form

$$\dot{x} = \mathcal{A}(t, \mu)x, \quad x \in \mathbb{R}^n, \quad t \in \mathbb{R}_+, \tag{3.1}$$

such that for each fixed $\mu \in M$ the matrix-valued function $\mathcal{A}(\cdot, \mu) : \mathbb{R}_+ \rightarrow \mathbb{R}^{n \times n}$ is continuous and bounded (generally, the bounding constant is different for each μ).

Usually, a family of mappings $\mathcal{A}(\cdot, \mu)$, $\mu \in M$, is considered under one of the two following natural assumptions: the family is continuous in **a**) the compact-open topology or **b**) the uniform topology. The case **a**) is equivalent to the condition that if a sequence $(\mu_k)_{k \in \mathbb{N}}$ of points from M converges to a point $\mu_0 \in M$, then the sequence $(\mathcal{A}(t, \mu_k))_{k \in \mathbb{N}}$ of matrices converges uniformly over each interval $[0, T] \subset \mathbb{R}_+$ to the matrix $\mathcal{A}(t, \mu_0)$ as $k \rightarrow +\infty$. The case **b**) differs from **a**) in that the convergence is uniform over the whole half-line \mathbb{R}_+ . We denote the class of families (3.1) that are continuous in the compact-open topology by $\mathcal{C}^n(M)$ and those that are continuous in the uniform topology by $\mathcal{U}^n(M)$. Clearly, $\mathcal{U}^n(M) \subset \mathcal{C}^n(M)$.

Further, we identify the family (3.1) with the matrix-valued function $\mathcal{A}(\cdot, \cdot)$ specifying it and use the following notation: $\mathcal{A} \in \mathcal{C}^n(M)$ or $\mathcal{A} \in \mathcal{U}^n(M)$.

Corollary. *Let M be a metric space. For any integer $n \geq 2$, the classes of pairs of functions*

$$\Sigma \mathcal{C}_n(M) \equiv \{(\mathfrak{s}(\cdot; \mathcal{A}), \mathfrak{es}(\cdot; \mathcal{A})) \mid \mathcal{A} \in \mathcal{C}^n(M)\}$$

and

$$\Sigma \mathcal{U}_n(M) \equiv \{(\mathfrak{s}(\cdot; \mathcal{A}), \mathfrak{es}(\cdot; \mathcal{A})) \mid \mathcal{A} \in \mathcal{U}^n(M)\}$$

coincide with one another and consist of the pairs $(\alpha(\cdot), \beta(\cdot))$ of functions $M \rightarrow \mathcal{Z}_n$ of the class $(F_\sigma, *)$ that satisfy the inequality $\alpha(\mu) \geq \beta(\mu)$ for all $\mu \in M$.

Remark. The description of the classes composed of the second elements of the pairs from $\Sigma \mathcal{C}_n(M)$ and $\Sigma \mathcal{U}_n(M)$ was obtained in the paper [2]. Those classes coincide with one another and consist of functions $M \rightarrow \mathcal{Z}_n$ from the class $(F_\sigma, *)$.

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