

On Investigation of Differential-Algebraic Systems with Two-Point Non-Linear Boundary Conditions

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We study the differential-algebraic two-point non-linear boundary value problem on a compact interval

$$x'(t) = f(t, x(t), y(t)), \quad t \in [a, b], \quad (1)$$

$$y(t) = g(t, x(t), y(t)), \quad t \in [a, b]; \quad (2)$$

$$B(x(a), y(b)) = d, \quad (3)$$

where $f : [a, b] \times \Omega_{\varrho_0} \times \Omega_{\varrho_1} \rightarrow \mathbb{R}^p$, $g : [a, b] \times \Omega_{\varrho_0} \times \Omega_{\varrho_1} \rightarrow \mathbb{R}^q$ and $B : \Omega_{\varrho_0} \times \Omega_{\varrho_1} \rightarrow \mathbb{R}^p$ are continuous functions defined on certain bounded sets $\Omega_{\varrho_0} \subset \mathbb{R}^p$, $\Omega_{\varrho_1} \subset \mathbb{R}^q$ specified below (see (7) and (9)), $d \in \mathbb{R}^p$. We assume that the functions f , g , B satisfy the Lipschitz conditions

$$|f(t, u_1, v_1) - f(t, u_2, v_2)| \leq K_1|u_1 - u_2| + K_2|v_1 - v_2|, \quad (4)$$

$$|g(t, u_1, v_1) - g(t, u_2, v_2)| \leq K_3|u_1 - u_2| + K_4|v_1 - v_2|, \quad (5)$$

for $t \in [a, b]$, $\{u_1, u_2\} \subset \Omega_{\varrho_0}$, $\{v_1, v_2\} \subset \Omega_{\varrho_1}$, where K_1, K_2, K_3, K_4 are non-negative matrices of dimensions $p \times p$, $p \times q$, $q \times p$, $q \times q$ such that the spectral radii of Q and K_4 satisfy the inequalities

$$r(Q) < 1, \quad r(K_4) < 1, \quad (6)$$

where

$$Q = \frac{3}{10} (b - a)K$$

and K is the $(p + q) \times (p + q)$ block matrix $K = \begin{pmatrix} K_1 & K_2 \\ K_3 & K_4 \end{pmatrix}$. By a solution of problem (1)–(3) we understand a pair of a continuously differentiable $x : [a, b] \rightarrow \Omega_{\varrho_0}$ and continuous $y : [a, b] \rightarrow \Omega_{\varrho_1}$ functions, satisfying (1)–(3).

We show that techniques similar to those of [1, 2] can be effectively applied to the study of problem (1), (2). Note that, although condition (6) ensures that equation (2) can theoretically be solved with respect to y , it may be difficult or impossible to do this explicitly, and this is not required in our approach.

In the sequel, 1_l is the unit matrix of dimension l . For any $x = \text{col}(x_1, \dots, x_l)$, $y = \text{col}(y_1, \dots, y_l)$, we write $|x| = \text{col}(|x_1|, \dots, |x_l|)$ and understand $x \leq y$ as $x_i \leq y_i$ for all $i = 1, 2, \dots, l$. The operations max and min for vector functions are also understood componentwise. Given any non-negative vector $\varrho \in \mathbb{R}^l$, we put

$$O_\varrho(z) = \{\xi \in \mathbb{R}^l : |\xi - z| \leq \varrho\}$$

for $z \in \mathbb{R}^l$ and

$$O_\varrho(U) = \bigcup_{z \in U} O_\varrho(z)$$

for a set $U \subset \mathbb{R}^l$. The set $O_\varrho(U)$ may be called the componentwise ϱ -neighbourhood of U .

Fix certain compact convex sets $D_0 \subset \mathbb{R}^p$, $D_1 \subset \mathbb{R}^p$ and put

$$\Omega_{\varrho_0} = O_{\varrho_0}(D_{a,b}), \tag{7}$$

where ϱ_0 is a non-negative vector and

$$D_{a,b} = \{(1 - \theta)z + \theta\eta : z \in D_0, \eta \in D_1, \theta \in [0, 1]\}.$$

Choose some $\tilde{y} \in \mathbb{R}^q$ and put

$$Y = \max_{(t,z,\eta) \in [a,b] \times D_0 \times D_1} |g(t, x_0(t, z, \eta), \tilde{y}) - \tilde{y}|,$$

where

$$x_0(t, z, \eta) = \left(1 - \frac{t - a}{b - a}\right)z + \frac{t - a}{b - a}\eta, \quad t \in [a, b], \tag{8}$$

for any $z \in D_0$, $\eta \in D_1$. Take a non-negative vector ϱ_1 and put

$$\Omega_{\varrho_1} = O_{\varrho_1}(\bar{y}_1), \tag{9}$$

where

$$\bar{y}_1 = \max_{(t,z,\eta) \in [a,b] \times D_0 \times D_1} |g(t, x_0(t, z, \eta), \tilde{y})|.$$

We assume in what follows that the non-negative vectors ϱ_0 , ϱ_1 can be chosen so that

$$\varrho_0 \geq \frac{1}{2} (b - a) \delta_{\varrho_0, \varrho_1}(f), \tag{10}$$

$$\varrho_1 \geq (1_q - K_4)^{-1} \left(\frac{1}{2} (b - a) K_3 \delta_{\varrho_0, \varrho_1}(f) + K_4 Y \right) + Y, \tag{11}$$

where

$$\delta_{\varrho_0, \varrho_1}(f) = \frac{1}{2} \left(\max_{(t,x,y) \in [a,b] \times \Omega_{\varrho_0} \times \Omega_{\varrho_1}} f(t, x, y) - \min_{(t,x,y) \in [a,b] \times \Omega_{\varrho_0} \times \Omega_{\varrho_1}} f(t, x, y) \right).$$

Together with inequalities (6), conditions (10), (11) may be regarded as smallness conditions on the functions f and g in a neighbourhood of sets D_0 and D_1 . When some of these conditions are violated, one can apply a technique from [3] in order to construct convergent iterations.

Instead of the original boundary value problem (1)–(3), consider the family of auxiliary two-point boundary value problems

$$x'(t) = f(t, x(t), y(t)), \quad t \in [a, b], \quad (12)$$

$$y(t) = g(t, x(t), y(t)), \quad t \in [a, b];$$

$$x(a) = z, \quad x(b) = \eta, \quad (13)$$

where $z \in D_0$ and $\eta \in D_1$ are free parameters. We focus on continuously differentiable $x : [a, b] \rightarrow \Omega_{\rho_0}$ and continuous $y : [a, b] \rightarrow \Omega_{\rho_1}$ solutions of problem (12), (13) with values $x(a) \in D_0$ and $x(b) \in D_1$. As it will be indicated below, one can then go back to the original problem by choosing the values of z and η appropriately.

In relation to the two-point boundary value problem (12), (13), introduce the sequences of functions

$$x_{m+1}(t, z, \eta) = z + \int_a^t f(s, x_m(s, z, \eta), y_m(s, z, \eta)) ds - \frac{t-a}{b-a} \int_a^b f(s, x_m(s, z, \eta), y_m(s, z, \eta)) ds + \frac{t-a}{b-a} (\eta - z), \quad (14)$$

$$y_{m+1}(t, z, \eta) = g(t, x_m(t, z, \eta), y_m(t, z, \eta)), \quad t \in [a, b], \quad m = 1, 2, \dots, \quad (15)$$

where

$$y_0(t, z, \eta) = \tilde{y}, \quad t \in [a, b],$$

with a fixed value of \tilde{y} and the function x_0 given by (8).

For $1 \leq i_1 < i_2 \leq n$, let J_{i_1, i_2} be the $(i_2 - i_1 + 1) \times n$ block matrix with the unit matrix of dimension $i_2 - i_1 + 1$ placed starting from the i_1 th column, that is

$$J_{i_1, i_2} = (0 \quad 1_{i_2 - i_1 + 1} \quad 0), \quad (16)$$

where the symbols 0 stand for the zero blocks of appropriate dimensions.

Theorem 1. *Let conditions (4)–(6) and (10), (11) be fulfilled. Then, for all fixed $z \in D_0$ and $\eta \in D_1$:*

1) *The functions of sequence (14) have range in Ω_{ρ_0} , satisfy the two-point conditions (13), and the limit*

$$x_\infty(t, z, \eta) = \lim_{m \rightarrow \infty} x_m(t, z, \eta)$$

exists uniformly on $[a, b] \times D_0 \times D_1$. The function $x_\infty(\cdot, z, \eta)$ satisfies conditions (13) and is continuously differentiable.

2) *The functions of sequence (15) have range in Ω_{ρ_1} and converge to a continuous limit function*

$$y_\infty(t, z, \eta) = \lim_{m \rightarrow \infty} y_m(t, z, \eta)$$

uniformly on $[a, b] \times D_0 \times D_1$.

3) The functions $x = x_\infty(\cdot, z, \eta)$, $y = y_\infty(\cdot, z, \eta)$ satisfy equation (2) and the Cauchy problem with a constant forcing term:

$$x'(t) = f(t, x(t), y(t)) + \frac{1}{b-a} \Delta(z, \eta), \quad t \in [a, b]; \quad x(a) = z, \tag{17}$$

where $\Delta : D_0 \times D_1 \rightarrow \mathbb{R}^p$ is the mapping given by the formula

$$\Delta(z, \eta) = \eta - z - \int_a^b f(s, x_\infty(s, z, \eta), y_\infty(s, z, \eta)) ds. \tag{18}$$

Other couples of functions (x, y) having range in the set $\Omega_{\varrho_0} \times \Omega_{\varrho_1}$ and satisfying (2), (17) do not exist.

4) The estimates

$$|x_\infty(t, z, \eta) - x_m(t, z, \eta)| \leq \frac{10}{9} \alpha_1(t) J_{1,p} K^\sigma Q^{m-\sigma} (1_{p+q} - Q)^{-1} \begin{pmatrix} \delta_{\varrho_0, \varrho_1}(f) \\ Y \end{pmatrix},$$

$$|y_\infty(t, z, \eta) - y_m(t, z, \eta)| \leq \frac{10}{9} \alpha_1(t) J_{p+1, p+q} K^{\sigma+1} Q^{m-\sigma-1} (1_{p+q} - Q)^{-1} \begin{pmatrix} \delta_{\varrho_0, \varrho_1}(f) \\ Y \end{pmatrix}$$

hold for all $t \in [a, b]$ and m sufficiently large, where

$$\sigma = \begin{cases} 0 & \text{if } b - a > \frac{10}{3}, \\ 1 & \text{if } b - a \leq \frac{10}{3}. \end{cases}$$

By (16), the left multiplication of a vector column by $J_{1,p}$ (resp., $J_{p+1, p+q}$) means the selection of the components $1, 2, \dots, p$ (resp., $p + 1, \dots, p + q$).

For $z \in \Omega_{\varrho_0}$, $\eta \in \Omega_{\varrho_1}$, let us put

$$\Lambda(z, \eta) = B(x_\infty(a, z, \eta), y_\infty(b, z, \eta)) - d.$$

The functions Δ and Λ determine the relation of the functions $x_\infty(\cdot, z, \eta)$ and $y_\infty(\cdot, z, \eta)$ to solutions of the original problem (1)–(3).

Theorem 2. Under the assumptions of Theorem 1, the couple of functions $(x_\infty(\cdot, z, \eta), y_\infty(\cdot, z, \eta))$ is a solution of the boundary value problem (1)–(3) if and only if the parameters z, η satisfy the system of $2p$ algebraic or transcendental equations

$$\Delta(z, \eta) = 0, \quad \Lambda(z, \eta) = 0. \tag{19}$$

The next statement proves that the system of determining equations (19) determines all possible solutions of the original non-linear boundary value problem (1)–(3) in the regions $\Omega_{\varrho_0}, \Omega_{\varrho_1}$.

Theorem 3. Under the assumptions of Theorem 1, the following assertions hold:

1) If there exist a pair of vectors $(z_*, \eta_*) \in D_0 \times D_1$ satisfying the system of determining equations (19), then the boundary value problem (1)–(3) has a solution (x_*, y_*) such that $x_*([a, b]) \subset \Omega_{\varrho_0}$, $y_*([a, b]) \subset \Omega_{\varrho_1}$ and

$$x_*(a) = z_*, \quad x_*(b) = \eta_*.$$

Moreover, this solution has the form

$$(x_*, y_*) = (x_\infty(\cdot, z_*, \eta_*), y_\infty(\cdot, z_*, \eta_*)).$$

2) If problem (1)–(3) has a solution (x_*, y_*) with $(x_*(a), x_*(b)) \in D_0 \times D_1$ and range in $\Omega_{\rho_0} \times \Omega_{\rho_1}$, then the system of determining equations (19) is satisfied with $z = x_*(a)$, $\eta = x_*(b)$.

The practical investigation of problem (1)–(3) is carried out by studying the approximate determining equations

$$\Delta_m(z, \eta) = 0, \quad \Lambda_m(z, \eta) = 0, \quad (20)$$

where

$$\Lambda_m(z, \eta) = B(x_m(a, z, \eta), y_m(b, z, \eta)) - d$$

and

$$\Delta_m(z, \eta) = \eta - z - \int_a^b f(s, x_m(s, z, \eta), y_m(s, z, \eta)) ds,$$

for some fixed m . Assuming that the Lipschitz condition holds for B ,

$$|B(u_1, v_1) - B(u_2, v_2)| \leq K_5|u_1 - u_2| + K_6|v_1 - v_2|,$$

under additional assumptions, we prove the existence of a solution of the original problem (1)–(3) by showing that the solvability of the approximate determining equations (20) in the respective region implies that of (19). A practical computation using Maple confirms the constructiveness of the proposed approach.

References

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