

## Nonlinear Autonomous Boundary-Value Problem for Differential Algebraic System

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We suppose that  $A$  and  $B$  are  $(m \times n)$ -measurable matrices and  $Z(z, \varepsilon)$  is an  $n$  measurable vector function. We will call a weakly nonlinear autonomous periodic differential-algebraic boundary-value problem the problem of finding solutions [6]

$$z(t, \varepsilon) : z(\cdot, \varepsilon) \in \mathbb{C}^1[a, b(\varepsilon)], z(t, \cdot) \in \mathbb{C}[0, \varepsilon_0], b(0) := b^*$$

of the differential-algebraic system

$$A z' = B z + \varepsilon Z(z, \varepsilon), \tag{1}$$

satisfying the boundary condition

$$\ell z(\cdot, \varepsilon) = \alpha. \tag{2}$$

Here,  $\ell z(\cdot, \varepsilon)$  is a linear bounded vector functional

$$\ell z(\cdot, \varepsilon) : \mathbb{C}[a, b(\varepsilon)] \rightarrow \mathbb{R}^q.$$

We seek solutions of problem (1), (2) in a small neighborhood of the solution  $z_0(t) \in \mathbb{C}^1[a, b^*]$  of the generating Noether ( $q \neq n$ ) differential-algebraic boundary-value problem

$$A z'_0 = B z_0, \ell z_0(\cdot) = \alpha \in \mathbb{R}^q. \tag{3}$$

We assume that the vector function  $Z(z, \varepsilon)$  is a continuously differentiable with respect to the unknown  $z(t, \varepsilon)$  in a small neighborhood of the solution of the generating problem and continuously differentiable with respect to the small parameter  $\varepsilon$  in a small positive neighborhood of zero. The matrix  $A$  is generally assumed to be rectangular  $m \neq n$ , or square, but degenerate. Under the condition

$$P_{A^*} = 0 \tag{4}$$

the generating system (3) is reduced to the traditional system of ordinary differential equations [2]

$$z'_0 = A^+ B z_0 + P_{A\rho_0} \nu_0(t). \tag{5}$$

Moreover,  $A^+$  is a pseudoinverse (by Moore–Penrose) matrix,  $P_{A^*}$  is a matrix orthoprojector

$$P_{A^*} : \mathbb{R}^m \rightarrow N(A^*),$$

$P_{A_{\rho_0}}$  is an  $(n \times \rho_0)$  matrix formed by  $\rho_0$  linearly independent columns of the  $(n \times n)$  matrix orthoprojector

$$P_A : \mathbb{R}^n \rightarrow \mathbb{N}(A),$$

$\nu_0(t) \in \mathbb{R}^{\rho_0}$  is an arbitrary continuous vector function. Under the condition (4) system (1) will be called nondegenerate. Suppose that the boundary-value problem for system (3) corresponds to a critical case

$$P_{Q^*} \neq 0, \quad Q := \ell X_0(\cdot).$$

In the critical case for a fixed vector function  $\nu_0(t) \in \mathbb{C}[a, b^*]$  under the condition

$$P_{Q_d^*} \left\{ \alpha - \ell K [P_{A_{\rho_0}} \nu_0(s)](\cdot) \right\} = 0 \quad (6)$$

the generating problem (3) has an  $r$  parametric family of solutions [3]

$$z_0(t, c_r) = X_r(t)c_r + G[P_{A_{\rho_0}} \nu_0(s)](t), \quad c_r \in \mathbb{R}^r.$$

Here,  $X_0(t)$  is the normal ( $X_0(a) = I_n$ ) fundamental matrix of the homogeneous part of the differential system (5). Moreover,

$$G[P_{A_{\rho_0}} \nu_0(s)](t) := X_0(t)Q^+ \ell K [P_{A_{\rho_0}} \nu_0(s)](\cdot) + K [P_{A_{\rho_0}} \nu_0(s)](t)$$

is the generalized Green's operator of the generating periodic differential-algebraic boundary-value problem (3) and

$$K [P_{A_{\rho_0}} \nu_0(s)](t) := X_0(t) \int_a^t X_0^{-1}(s) P_{A_{\rho_0}} \nu_0(s) ds$$

is the generalized Green's operator of the Cauchy problem  $z(a) = 0$  for the differential-algebraic system (3). The matrix  $P_{Q_d^*}$  formed by  $d$  linearly independent rows of the matrix orthoprojector  $P_{Q^*}$ , and the matrix  $P_{Q_r}$  formed by  $r$  linearly independent columns of the matrix orthoprojector  $P_Q$ . Under condition (4) system (1) is reduced to the traditional system of the ordinary differential equations

$$z' = A^+ B z + P_{A_{\rho_0}} \nu_0(t) + \varepsilon A^+ Z(z, \varepsilon). \quad (7)$$

The boundary-value problem for the nondegenerate differential-algebraic system (6) differs significantly from similar nonautonomous boundary-value problems depending on an arbitrary vector function  $\nu_0(t) \in \mathbb{C}[a, b^*]$ . In exceptional cases, the autonomous boundary-value problem (1), (2) is solvable on a segment of fixed length.

As is known [7], an autonomous boundary-value problem for system (7) differs significantly from similar nonautonomous boundary-value problems. Unlike the latter, the right end  $b(\varepsilon)$  of the interval  $[a, b(\varepsilon)]$ , on which we are finding solution of the nonlinear boundary-value problem for system (7), is unknown and must be defined in the process of constructing the solution itself. Let's use the technique [6, 7] which consists in defining the unknown function

$$b(\varepsilon) = b^* + \varepsilon(b^* - a)\beta(\varepsilon)$$

in terms of the new unknown

$$\beta(\varepsilon) \in \mathbb{C}[0, \varepsilon_0], \quad \beta(0) := \beta^*.$$

The function  $\beta(\varepsilon)$  is to be determined in the process of finding a solution of the boundary-value problem for system (7). The essence of the reception is to replace the independent variable

$$t = a + (\tau - a)(1 + \varepsilon\beta(\varepsilon))$$

and finding a solution for the nonlinear boundary-value problem (2), (7) and the function  $\beta(\varepsilon)$  as a function of a small parameter. In the critical case, under the condition (6) for a fixed function  $\nu_0(\tau)$  the condition of solving of the nonlinear boundary-value problem (2), (7) takes the form [6]

$$P_{Q_d^*} \left\{ (1 + \varepsilon\beta(\varepsilon)) \alpha - \ell K \left[ \beta(\varepsilon) (A^+ B z(s, \varepsilon) + P_{A_{\rho_0}} \nu_0(s)) + (1 + \varepsilon\beta(\varepsilon)) A^+ Z(z(s, \varepsilon), \varepsilon) \right] (\cdot) \right\} = 0. \quad (8)$$

Using the continuous of the nonlinear vector function  $Z(z(t, \varepsilon), \varepsilon)$  on  $\varepsilon$  in a small positive neighborhood of zero, we pass to the boundary for  $\varepsilon \rightarrow 0$  in equality (8) and obtain the necessary condition

$$F(\check{c}_0) := P_{Q_d^*} \left\{ \alpha - \ell K \left[ \beta^* (A^+ B z_0(s, c_r^*) + P_{A_{\rho_0}} \nu_0(s)) + A^+ Z(z_0(s, c_r^*), 0) \right] (\cdot) \right\} = 0 \quad (9)$$

for the existence of a solution of the boundary-value problem (1), (2) in a critical case. Here,

$$\check{c}_0 := \begin{pmatrix} c_r^* \\ \beta^* \end{pmatrix} \in \mathbb{R}^{r+1}.$$

Thus, the following lemma is proved.

**Lemma.** *Suppose that the autonomous differential-algebraic boundary-value problem (1), (2) for a fixed constant  $\nu_0 \in \mathbb{R}^{\rho_0}$  under conditions (4) and (6) corresponds to the critical case  $P_{Q^*} \neq 0$  and has the solution  $z(t, \varepsilon)$ , that for  $\varepsilon = 0$  is transformed into generating  $z(t, 0) = z_0(t, c_r^*)$ . Then the vector  $\check{c}_0$  satisfies to equation (9).*

The first  $r$  components  $c_r^* \in \mathbb{R}^r$  of the root of equation (9) determine the amplitude of the generating solution  $z_0(t, c_r^*)$  in a small neighborhood of which can exist the desired solution of the original problem (1), (2). In addition, from equation (9) can be found the value  $\beta^*$  which determines the first approximation to the unknown function

$$b_1(\varepsilon) = b^* + \varepsilon(b^* - a)\beta^*.$$

If equation (9) has no real roots, then the original differential-algebraic problem (1), (2) does not have the desired solutions. Equation (9) will be further called the equation for generating constants of the autonomous nonlinear differential-algebraic boundary-value problem (1), (2). The statement of the lemma generalizes the corresponding results of [1, 5] onto the case of the autonomous nonlinear differential-algebraic boundary-value problem (1), (2), namely, for the case of  $A \neq I_n$ . As is known [1, 5, 6], the nondegenerate differential-algebraic problem (1) (2) is solvable when the roots of the equation for generating constants (9) are simple. Proposed in the article scheme of study of the nonlinear autonomous boundary-value problem for a nondegenerate system of differential-algebraic equations can be transferred, analogously to [3], onto degenerate systems of differential-algebraic equations. The above-proposed scheme of study of the nonlinear autonomous boundary value problem for a nondegenerate system of differential-algebraic equations can be transferred, analogously to [4], onto systems of differential-algebraic equations with a matrix of variable rank at the derivative, and analogously to [8], onto nonlinear boundary-value problems not solved with respect to the derivative.

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