

Topological Entropy of a Diagonalizable Linear System of Differential Equations

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Consider the linear differential system

$$\dot{x} = A(t)x, \quad x \in \mathbb{R}^n, \quad t \in \mathbb{R}_+ \equiv [0, \infty), \quad (1)$$

with a piecewise continuous operator function $A : \mathbb{R}_+ \rightarrow \text{End } \mathbb{R}^n$. Let us endow the space \mathbb{R}^n with the norm $\|x\| = \max_{1 \leq k \leq n} |x_k|$ and with the set of metrics

$$d_t^A(x_0, y_0) = \max_{\tau \in [0, t]} \|x(\tau, x_0) - x(\tau, y_0)\|, \quad x_0, y_0 \in \mathbb{R}^n, \quad t \in \mathbb{R}_+,$$

where $x(\cdot, a)$ is the solution to system (1) satisfying the condition $x(0, a) = a$. By $S_{\|\cdot\|}(A, \mathcal{K}, \varepsilon, t)$ we denote the ε -entropy of a compact metric space $\mathcal{K} \subset \mathbb{R}^n$ with the metric d_t^A [2] (that is, the minimum number of open balls of radius $\varepsilon > 0$ covering \mathcal{K}). Then the *topological entropy* [1] of system (1) is defined by the formula

$$h_{\text{top}}(A) = \sup_{\mathcal{K} \subset \mathbb{R}^n} \lim_{\varepsilon \rightarrow 0} \overline{\lim}_{t \rightarrow \infty} \frac{1}{t} \ln S_{\|\cdot\|}(A, \mathcal{K}, \varepsilon, t)$$

(its right-hand side does not depend on the choice of a norm $\|\cdot\|$, therefore the definition is correct).

In what follows we will use one more formula to calculate the topological entropy. For any $\varepsilon > 0$ and $n \in \mathbb{N}$ we denote by $N_{\|\cdot\|}(A, \mathcal{K}, \varepsilon, t)$ the ε -capacity of a compact metric space $\mathcal{K} \subset \mathbb{R}^n$ with the metric d_t^A [2] (i.e., the maximum number of points such that all their pairwise d_t^A -distances are greater than ε), then the topological entropy can be calculated by the formula

$$h_{\text{top}}(A) = \sup_{\mathcal{K} \subset \mathbb{R}^n} \lim_{\varepsilon \rightarrow 0} \overline{\lim}_{t \rightarrow \infty} \frac{1}{t} \ln N_{\|\cdot\|}(A, \mathcal{K}, \varepsilon, t).$$

In [3], it is asserted that for the Lyapunov exponents $\lambda_1(A) \leq \dots \leq \lambda_n(A)$ of any system (1) with a bounded operator function A , the equality

$$h_{\text{top}}(A) = \sum_{\lambda_i(A) > 0} \lambda_i(A) \quad (2)$$

holds. In fact, it may not hold, as shown by

Theorem 1. *For system (1) with the operator function*

$$A(t) = \text{diag}(a(t), b(t)), \quad \text{where } (a(t), b(t)) = \begin{cases} (1, 0), & t \in [0, 1]; \\ (1, 0), & t \in [(2n-1)!, (2n)!]; \\ (0, 1), & t \in [(2n)!, (2n+1)!], \end{cases} \quad n = 1, 2, \dots, \quad (3)$$

relation (2) becomes the inequality $1 < 2$.

Proof. Let us calculate the Lyapunov exponents of system (3). On the one hand, from the inequalities $a(t) \leq 1, b(t) \leq 1, t \geq 0$, we see that the Lyapunov exponents do not exceed 1.

On the other hand, from the inequalities

$$\begin{aligned} \overline{\lim}_{t \rightarrow +\infty} \frac{1}{t} \int_0^t a(\tau) d\tau &\geq \lim_{n \rightarrow +\infty} \frac{(2n)! - (2n-1)!}{(2n)!} = 1, \\ \overline{\lim}_{t \rightarrow +\infty} \frac{1}{t} \int_0^t b(\tau) d\tau &\geq \lim_{n \rightarrow +\infty} \frac{(2n+1)! - (2n)!}{(2n+1)!} = 1, \end{aligned}$$

it follows that the Lyapunov exponents of system (3) satisfy the equalities

$$\lambda_1(A) = \lambda_2(A) = 1 \text{ and } \lambda_1(A) + \lambda_2(A) = 2.$$

Let us calculate the topological entropy of system (3). For given $m, n \in \mathbb{N}$, consider the set of points of the form $\begin{pmatrix} x_1^{(k)} \\ 0 \end{pmatrix}$, where

$$x_1^{(k)} = \frac{k}{e^{(2n)! - (2n-1)!} m}, \quad k = 0, \dots, [e^{(2n)! - (2n-1)!} m]$$

($[\cdot]$ is an integer part of the number). Since the distance $d_{(2n)!}^A \left(\begin{pmatrix} x_1^{(k)} \\ 0 \end{pmatrix}, \begin{pmatrix} x_1^{(l)} \\ 0 \end{pmatrix} \right), k \neq l$, satisfies the inequality

$$d_{(2n)!}^A \left(\begin{pmatrix} x_1^{(k)} \\ 0 \end{pmatrix}, \begin{pmatrix} x_1^{(l)} \\ 0 \end{pmatrix} \right) = \frac{|k - l|}{e^{(2n)! - (2n-1)!} m} e^{(2n)! - (2n-1)! + (2n-2)! - (2n-3)! + \dots} > \frac{1}{m},$$

then

$$N\left(A, [0, 1] \times \{0\}, \frac{1}{m}, (2n)!\right) \geq e^{(2n)! - (2n-1)!} m,$$

and hence

$$h_{\text{top}}(A) \geq \lim_{n \rightarrow \infty} \left(\frac{(2n)! - (2n-1)!}{(2n)!} + \frac{\ln m}{(2n)!} \right) = 1.$$

Let us prove the opposite inequality $h_{\text{top}}(A) \leq 1$. For an arbitrary compact set $K \subset \mathbb{R}^2$ we denote by γ_K a positive number such that $K \subset [-\gamma_K, \gamma_K] \times [-\gamma_K, \gamma_K]$.

For any $t > 0$ and $m \in \mathbb{N}$, the set of points $V_{t,m}$ of the form $\begin{pmatrix} x_1^{(k)} \\ x_2^{(l)} \end{pmatrix}$, where

$$\begin{aligned} x_1^{(k)} &= \frac{k\gamma_K}{m} e^{-\int_0^t a(\tau) d\tau}, \quad k = -\left[e^{\int_0^t a(\tau) d\tau} m \right], \dots, \left[e^{\int_0^t a(\tau) d\tau} m \right], \\ x_2^{(l)} &= \frac{l\gamma_K}{m} e^{-\int_0^t b(\tau) d\tau}, \quad l = -\left[e^{\int_0^t b(\tau) d\tau} m \right], \dots, \left[e^{\int_0^t b(\tau) d\tau} m \right], \end{aligned}$$

is a $\frac{\gamma_K}{m}$ -covering of the square $[-\gamma_K, \gamma_K] \times [-\gamma_K, \gamma_K]$. Indeed, let an arbitrary point $(x_1, x_2) \in [-\gamma_K, \gamma_K] \times [-\gamma_K, \gamma_K]$ be given. Then by the definition of the set $V_{t,m}$ there exists a point $(x_1^{(k_0)}, x_2^{(l_0)})$ such that

$$|x_1^{(k_0)} - x_1| \leq \frac{\gamma_K}{m} e^{-\int_0^t a(\tau) d\tau}, \quad |x_2^{(l_0)} - x_2| \leq \frac{\gamma_K}{m} e^{-\int_0^t b(\tau) d\tau}.$$

It follows that

$$|x_1^{(k_0)} - x_1| e^{\int_0^t a(\tau) d\tau} \leq \frac{\gamma_K}{m}, \quad |x_2^{(l_0)} - x_2| e^{\int_0^t b(\tau) d\tau} \leq \frac{\gamma_K}{m}.$$

Thus $S_{\|\cdot\|}(A, \mathcal{K}, \varepsilon, t)$ does not exceed the cardinality of the set $V_{t,m}$, which equals

$$\left(2 \left[e^{\int_0^t a(\tau) d\tau} m \right] + 1\right) \left(2 \left[e^{\int_0^t b(\tau) d\tau} m \right] + 1\right) \leq 9m^2 e^{\int_0^t (a(\tau)+b(\tau)) d\tau} = 9m^2 e^t,$$

whence we get $h_{\text{top}}(A) \leq 1$. □

For an arbitrary piecewise continuous function $a(\cdot) : \mathbb{R}_+ \rightarrow \mathbb{R}$, let

$$a^+(t) = \max_{s \in [0;t]} \int_0^s a(\tau) d\tau.$$

Theorem 2. *If system (1) can be reduced to a diagonal form*

$$\dot{y} = \text{diag}(b_1(t), \dots, b_n(t))y,$$

by means of a transformation $x = Q(t)y$ such that

$$\overline{\lim}_{t \rightarrow +\infty} \frac{1}{t} \ln \|Q(t)\| = \overline{\lim}_{t \rightarrow +\infty} \frac{1}{t} \ln \|Q^{-1}(t)\| = 0,$$

then

$$h_{\text{top}}(A) = \overline{\lim}_{t \rightarrow +\infty} \frac{1}{t} \sum_{k=1}^n b^+(t).$$

Given a metric space \mathcal{M} and a continuous map

$$A : \mathcal{M} \times \mathbb{R}_+ \rightarrow \text{End } \mathbb{R}^n \tag{4}$$

we form the function

$$\mu \longmapsto h_{\text{top}}(A(\mu, \cdot)). \tag{5}$$

Results of [4, 5] imply

Theorem 3. *For any mapping (4), function (5) belongs to the third Baire class. If $\mathcal{M} = [0, 1]$, then for some mapping (4) function (5) does not belong to the first Baire class.*

References

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