

On Relations Between Perron and Lyapunov Regularity Coefficients of Parametric Linear Differential Equations

A. Vaidzelevich

Institute of Mathematics, National Academy of Sciences of Belarus, Minsk, Belarus

E-mail: voidzelevich@gmail.com

For any $n \in \mathbb{N}$ we consider the linear system of differential equations

$$\dot{x} = A(t)x, \quad x \in \mathbb{R}^n, \quad t \geq 0, \quad (1)$$

with a continuous coefficient $n \times n$ matrix uniformly bounded on the time half-line. Along with system (1), consider the adjoint system

$$\dot{y} = -A^T(t)y, \quad y \in \mathbb{R}^n, \quad t \geq 0. \quad (2)$$

Obviously, the adjoint to system (2) is system (1); therefore, systems (1) and (2) are said to be mutually adjoint. Everywhere below, we identify system (1) with its coefficient matrix.

The so-called Perron and Lyapunov regularity coefficients $\sigma_P(A)$ and $\sigma_L(A)$, respectively, defined for each system (1) play an important role in the asymptotic theory of linear differential systems [3,4]. They essentially specify the response of system (1) to linear exponentially decreasing perturbations and nonlinear perturbations of a higher smallness order; in particular, the vanishing of at least one (and hence both) of them is equivalent to the Lyapunov regularity of system (1).

Let $\lambda_1(A) \leq \dots \leq \lambda_n(A)$ be the Lyapunov exponents of system (1) arranged in nondecreasing order, and let $\mu_1(A) \geq \dots \geq \mu_n(A)$ be the Lyapunov exponents of the adjoint system (2) arranged in nonascending order. By Sp we denote the trace of a matrix. Then, by definition,

$$\sigma_P(A) = \max_{1 \leq i \leq n} \{\lambda_i(A) + \mu_i(A)\} \quad \text{and} \quad \sigma_L(A) = \sum_{i=1}^n \lambda_i(A) - \lim_{t \rightarrow +\infty} \frac{1}{t} \int_0^t \text{Sp } A(\tau) \, d\tau.$$

It was shown in the monograph [2, § 1] that the regularity coefficients of any n -dimensional system (1) satisfy the inequalities

$$0 \leq \sigma_P(A) \leq \sigma_L(A) \leq n\sigma_P(A). \quad (3)$$

In the paper [5], it has been shown that inequalities (3) describe all possible relations between the regularity coefficients of differential systems. In other words, it was shown that for any positive integer n and ordered pair of numbers $(p; \ell)$ satisfying the inequalities $0 \leq p \leq \ell \leq np$, there exists a system A such that $\sigma_P(A) = p$ and $\sigma_L(A) = \ell$.

Let M be a metric space. Along with the individual system (1) we consider a family of linear differential systems

$$\dot{x} = A(t, \xi)x, \quad x \in \mathbb{R}^n, \quad t \geq 0, \quad (4)$$

such that for every $\xi \in M$ the matrix-valued function $A(\cdot, \xi): [0, +\infty) \rightarrow \mathbb{R}^{n \times n}$ is continuous and uniformly bounded on the time half-line, i.e. there exists $a_\xi \in \mathbb{R}$ such that $\sup_{t \in [0, +\infty)} \|A(t, \xi)\| \leq a_\xi$.

Moreover, we suppose that the family of matrix-valued functions $A(\cdot, \xi)$, $\xi \in M$, is continuous in

compact-open topology, in other words, if a sequence $(\xi_k)_{k \in \mathbb{N}}$, $\xi_k \in M$, converges to ξ_0 , then the sequence of functions $A(\cdot, \xi_k)$ converges to $A(\cdot, \xi_0)$ uniformly on every interval of $[0, +\infty)$. For a symbol $\varkappa \in \{P, L\}$ by $\sigma_{\varkappa}^A(\cdot): M \rightarrow \mathbb{R}$ we denote a function acting by the rule $\xi \mapsto \sigma_{\varkappa}(A(\cdot, \xi))$. In a natural way a problem of complete description of pair $(\sigma_P^A(\cdot), \sigma_L^A(\cdot))$ arises. First we need introduce some notation to formulate a solution of this problem.

Let $f(\cdot)$ be a real-valued function defined on some set M . For a number $r \in \mathbb{R}$ and for the function $f(\cdot)$ the Lebesgue set $[f \geq r]$ is defined as the set $[f \geq r] \stackrel{\text{def}}{=} \{t \in M: f(t) \geq r\}$. If M is a topological space then G_δ stands for a system of subsets in M which can be represented as countable intersections of open sets. We say [1, pp. 223–224] that a function $f(\cdot): M \rightarrow \mathbb{R}$ belongs to the class $(*, G_\delta)$, or $f(\cdot)$ is a function of the class $(*, G_\delta)$ if its Lebesgue set satisfies the condition $[f \geq r] \in G_\delta$ for any $r \in \mathbb{R}$.

Theorem. *For functions $p(\cdot), \ell(\cdot): M \rightarrow \mathbb{R}$ there exists a parametric system (4) such that $\sigma_P^A(\cdot) \equiv p(\cdot)$ and $\sigma_L^A(\cdot) \equiv \ell(\cdot)$ if and only if $p(\cdot), \ell(\cdot)$ are functions of the class $(*, G_\delta)$ and for every $\xi \in M$ the following inequalities*

$$0 \leq p(\xi) \leq \ell(\xi) \leq np(\xi)$$

hold.

References

- [1] F. Hausdorff, *Theory of sets*. (Russian) KomKniga, Moscow, 1937.
- [2] N. A. Izobov, *Lyapunov Exponents and Stability*. Stability, Oscillations and Optimization of Systems, 6. Cambridge Scientific Publishers, Cambridge, 2012.
- [3] A. M. Ljapunov, *Collected Works*. Vol. II. (Russian) Izdat. Akad. Nauk SSSR, Moscow, 1956.
- [4] O. Perron, Die Ordnungszahlen linearer Differentialgleichungssysteme. (German) *Math. Z.* **31** (1930), no. 1, 748–766.
- [5] A. S. Voidelevich, Complete description of relations between irregularity coefficients of linear differential systems. (Russian) *Differ. Uravn.* **50** (2014), no. 3, 283–289; translation in *Differ. Equ.* **50** (2014), no. 3, 279–285.