On Existence of Solutions with Prescribed Number of Zeros to High-Order Emden–Fowler Equations with Regular Nonlinearity and Variable Coefficient

V. V. Rogachev

Lomonosov Moscow State University, Moscow, Russia E-mail: valdakhar@gmail.com

1 Introduction

The problem of existence of solutions with a countable number of zeros on a given domain to Emden–Fowler type equations is investigated. Consider the equation

$$y^{(n)} + p(t, y, y', \dots, y^{(n-1)})|y|^k \operatorname{sgn} y = 0, \ 0 < m \le p(t, \xi_1, \dots, \xi_n) \le M < +\infty, \ t \in \mathbb{R},$$
(1.1)

where $n \in \mathbb{N}$, $n \ge 2$, $k \in \mathbb{R}$, k > 1, the function $p(t, \xi_1, \ldots, \xi_n)$ is continuous, and Lipschitz continuous in ξ_1, \ldots, ξ_n .

We prove that equation (1.1) has solutions with a countable set of zeros on every finite interval [a, b). The existence of solutions with a given finite number of zeros was considered in the previous papers, and results from them will be used to prove the main result. Namely, [3] is devoted to the case of the third- and the fourth-order Emden–Fowler type equations with constant p, [4,6] deal with the third-order equation with a variable coefficient, and [5,8] expand the previous results to the higher-order case. They based on the result obtained in [1,2]. Some results of the papers [3–6,8] can be summarized as

Theorem 1.1. For any integer $S \ge 2$ and any finite interval $[a, b] \subset \mathbb{R}$ equation (1.1) has a solution y(t) defined on the interval, y(t) has exactly S zeros on the interval and y(a) = 0, y(b) = 0.

Now, this theorem is expanded to the new case.

2 The main result

Theorem 2.1 ([7]). For any finite interval $[a, b) \subset \mathbb{R}$ equation (1.1) has a solution y(t) defined on the interval, y(t) a countable set of zeros on the interval and y(a) = 0.

3 Sketch of the proof

The idea of the proof is similar to that of the proof of the main result from [8]. Suppose that y(t) is a maximally extended solution to (1.1) with initial data $y(a) = 0, y'(a) = y_1 > 0, \ldots, y^{(n-1)}(a) = y_{n-1} > 0$. In [1] it is proved that y(t) has the countable number of zeroes. By t_N we denote a position of the N-th zero of y(t) after the point a. In [8] it was proved that t_N is a continuous function on (y_1, \ldots, y_{n-1}) . Lower and upper estimates of the continuous function $t_N(y_1, \ldots, y_{n-1})$ show that the N-th zero of the solution can be located at any point on the axis after a, hence solution with exactly N zeros can be defined on any [a, b], if we choose appropriate initial data.

Proof of Theorem 2.1 has the same idea with some minor modifications. We know (see, for example, [1, Ch. 7]) that t_N tends to some finite limit t_* as $N \to +\infty$, but the solution itself is not defined at the point t_* . It appears that $t_*(y_1, \ldots, y_{n-1})$ is also a continuous function of the variables (y_1, \ldots, y_{n-1}) – like $t_N(y_1, \ldots, y_{n-1})$. In addition, we obtain upper and lower estimates of t_* with the help of [1, p. 193, Lemmas 7.1, 7.2, 7.3] and Theorem 1.1.

We prove the continuity of $t_*(y_1, \ldots, y_{n-1})$ using the continuity of every $t_N(y_1, \ldots, y_{n-1})$ and lemmas [1, p. 193, Lemmas 7.1, 7.2, 7.3], since they give some estimates on the distance between t_N and t_{N+1} in comparison with the distance between t_N and t_{N-1} . The proposition of discontinuity of $t_*(y_1, \ldots, y_{n-1})$ contradicts with those estimates.

4 Future plans

Papers [4,5] demonstrate that Theorem 1.1 still holds true when $k \in (0,1)$, so in future I hope to expand Theorem 2.1 on this case as well.

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