

On the Cauchy Problem for Linear Systems of Impulsive Equations with Singularities

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Let $I \subset \mathbb{R}$ be an interval non-degenerate in the point, $t_0 \in \mathbb{R}$ and

$$I_{t_0} = I \setminus \{t_0\}.$$

Consider the linear system of impulsive equations with fixed and finite points of impulses actions

$$\frac{dx}{dt} = P(t)x + q(t) \text{ for a.a. } t \in I_{t_0} \setminus \{\tau_l\}_{l=1}^{\infty}, \tag{1}$$

$$x(\tau_l+) - x(\tau_l-) = G_l x(\tau_l) + g_l \quad (l = 1, 2, \dots), \tag{2}$$

where $P \in L_{loc}(I_{t_0}, \mathbb{R}^{n \times n})$, $q \in L_{loc}(I_{t_0}, \mathbb{R}^n)$, $G_l \in \mathbb{R}^{n \times n}$ ($l = 1, 2, \dots$), $g_l \in \mathbb{R}^n$ ($l = 1, 2, \dots$), $\tau_l \in I_{t_0}$ ($l = 1, 2, \dots$), $\tau_i \neq \tau_j$ if $i \neq j$ and $\lim_{l \rightarrow \infty} \tau_l = t_0$.

Let $H = \text{diag}(h_1, \dots, h_n) : I_{t_0} \rightarrow \mathbb{R}^{n \times n}$ be a diagonal matrix-functions with continuous diagonal elements $h_k : I_{t_0} \rightarrow]0, +\infty[$ ($k = 1, \dots, n$).

We consider the problem of finding a solution $x : I_{t_0} \rightarrow \mathbb{R}^n$ of the system (1), (2), satisfying the condition

$$\lim_{t \rightarrow t_0} (H^{-1}(t)x(t)) = 0. \tag{3}$$

The analogous problem for the systems (1) of ordinary differential equations with singularities are investigated in [2–4].

The singularity of the system (1) is considered in the sense that the matrix P and vector q functions, in general, are not integrable at the point t_0 . In general, the solution of the problem (1), (3) is not continuous at the point t_0 and, therefore, it is not a solution in the classical sense. But its restriction to every interval from I_{t_0} is a solution of the system (1). In connection with this we give the example from [4].

Let $\alpha > 0$ and $\varepsilon \in]0, \alpha[$. Then the problem

$$\frac{dx}{dt} = -\frac{\alpha x}{t} + \varepsilon |t|^{\varepsilon-1\alpha},$$

$$\lim_{t \rightarrow 0} (t^\alpha x(t)) = 0$$

has the unique solution $x(t) = |t|^{\varepsilon-\alpha} \text{sgn} t$. This function is not a solution of the equation on the set $I = \mathbb{R}$, but its restrictions to $] - \infty, 0[$ and $]0, +\infty[$ are solutions of that equation.

We give sufficient conditions for the unique solvability of the problem (1), (2); (3). The analogous results belong to I. Kiguradze [3, 4] for the Cauchy problem for systems of ordinary differential equations with singularities.

Some boundary value problems for linear impulsive systems with singularities are investigated in [1] (see, also the references herein).

In the paper, the use will be made of the following notation and definitions.

\mathbb{N} is the set of all natural numbers.

$\mathbb{R} =] - \infty, +\infty[$, $\mathbb{R}_+ = [0, +\infty[$, $[a, b]$ and $]a, b[$ ($a, b \in \mathbb{R}$) are, respectively, closed and open intervals.

$\mathbb{R}^{n \times m}$ is the space of all real $n \times m$ matrices $X = (x_{ij})_{i,j=1}^{n,m}$ with the norm

$$\|X\| = \max_{j=1, \dots, m} \sum_{i=1}^n |x_{ij}|.$$

$O_{n \times m}$ (or O) is the zero $n \times m$ matrix.

If $X = (x_{ij})_{i,j=1}^{n,m} \in \mathbb{R}^{n \times m}$, then $|X| = (|x_{ij}|)_{i,j=1}^{n,m}$.

$\mathbb{R}_+^{n \times m} = \{(x_{ij})_{i,j=1}^{n,m} : x_{ij} \geq 0 \text{ (} i = 1, \dots, n; j = 1, \dots, m)\}$.

$\mathbb{R}^n = \mathbb{R}^{n \times 1}$ is the space of all real column n -vectors $x = (x_i)_{i=1}^n$.

If $X \in \mathbb{R}^{n \times n}$, then X^{-1} , $\det X$ and $r(X)$ are, respectively, the matrix inverse to X , the determinant of X and the spectral radius of X ; I_n is the identity $n \times n$ -matrix.

The inequalities between the matrices are understood componentwise.

A matrix-function is said to be continuous, integrable, nondecreasing, etc., if each of its component is such.

If $X : [a, b] \rightarrow \mathbb{R}^{n \times m}$ is a matrix-function, then $X(t-)$ and $X(t+)$ are, respectively, the left and the right limits of the matrix-function $X : [a, b] \rightarrow \mathbb{R}^{n \times m}$ at the point t ($X(a-) = X(a)$, $X(b+) = X(b)$).

$\tilde{C}([a, b], D)$, where $D \subset \mathbb{R}^{n \times m}$, is the set of all absolutely continuous matrix-functions $X : [a, b] \rightarrow D$.

$\tilde{C}_{loc}(I_{t_0} \setminus \{\tau_l\}_{l=1}^{\infty}, D)$ is the set of all matrix-functions $X : I_{t_0} \rightarrow D$ whose restrictions to an arbitrary closed interval $[a, b]$ from $I_{t_0} \setminus \{\tau_l\}_{l=1}^{\infty}$ belong to $\tilde{C}([a, b], D)$.

$L([a, b]; D)$ is the set of all integrable matrix-functions $X : [a, b] \rightarrow D$.

$L_{loc}(I_{t_0}; D)$ is the set of all matrix-functions $X : I_{t_0} \rightarrow D$ whose restrictions to an arbitrary closed interval $[a, b]$ from I_{t_0} belong to $L([a, b], D)$.

A vector-function $x \in \tilde{C}_{loc}(I_{t_0} \setminus \{\tau_l\}_{l=1}^{\infty}, \mathbb{R}^n)$ is said to be a solution of the system (1), (2) if

$$x'(t) = P(t)x(t) + q(t) \text{ for a.a. } t \in I_{t_0} \setminus \{\tau_l\}_{l=1}^{\infty}$$

and there exist one-sided limits $x(\tau_l-)$ and $x(\tau_l+)$ ($l = 1, 2, \dots$) such that the equalities (2) hold.

We assume that

$$\det(I_n + G_l) \neq 0 \text{ (} l = 1, 2, \dots \text{)}.$$

The above inequalities guarantee the unique solvability of the Cauchy problem for the corresponding nonsingular systems, i.e. for the case when $P \in L_{loc}(I, \mathbb{R}^{n \times n})$ and $q \in L_{loc}(I, \mathbb{R}^n)$.

Let $P_0 \in L_{loc}(I_{t_0}, \mathbb{R}^{n \times n})$ and $G_{0l} \in \mathbb{R}^{n \times n}$ ($l = 1, 2, \dots$). Then a matrix-function $C_0 : I_{t_0} \times I_{t_0} \rightarrow \mathbb{R}^{n \times n}$ is said to be the Cauchy matrix of the homogeneous impulsive system

$$\frac{dx}{dt} = P_0(t)x, \tag{4}$$

$$x(\tau_l+) - x(\tau_l-) = G_{0l}x(\tau_l) \text{ (} l = 1, 2, \dots \text{)}, \tag{5}$$

if for every interval $J \subset I_{t_0}$ and $\tau \in J$ the restriction of the matrix-function $C_0(\cdot, \tau) : I_{t_0} \rightarrow \mathbb{R}^{n \times n}$ to J is the fundamental matrix of the system (4), (5) satisfying the condition $C_0(\tau, \tau) = I_n$. Therefore, C_0 is the Cauchy matrix of (4), (5) if and only if the restriction of C_0 on $J \times J$, for every interval $J \subset I_{t_0}$, is the Cauchy matrix of the system in the sense of definition given in [5].

We assume $I_{t_0}(\delta) = [t_0 - \delta, t_0 + \delta] \cap I_{t_0}$ for every $\delta > 0$.

Theorem. *Let there exist a matrix-function $P_0 \in L_{loc}(I_{t_0}, \mathbb{R}^{n \times n})$ and constant matrices $G_l \in \mathbb{R}^{n \times n}$ ($l = 1, 2, \dots$) and $B_0, B \in \mathbb{R}_+^{n \times n}$ such that*

$$\det(I_n + G_{0l}) \neq 0 \quad (l = 1, 2, \dots), \quad r(B) < 1,$$

and the estimates

$$|C_0(t, \tau)| \leq H(t)B_0H^{-1}(\tau) \quad \text{for } t \in I_{t_0}(\delta), \quad (t - t_0)(\tau - t_0) > 0, \quad |\tau - t_0| \leq |t - t_0|$$

and

$$\left| \int_{t_0}^t |C_0(t, \tau)(P(\tau) - P_0(\tau))H(\tau)| d\tau \right| + \left| \sum_{l \in \mathcal{N}_{t_0, t}} |C_0(t, \tau_l)G_{0l}(I_n + G_{0l})^{-1}(G_l - G_{0l})| \right| \leq H(t)B \quad \text{for } t \in I_{t_0}(\delta)$$

hold for some $\delta > 0$, where C_0 is the Cauchy matrix of the system (4), (5). Let, moreover,

$$\lim_{t \rightarrow t_0} \left\| \int_{t_0}^t H^{-1}(\tau)C_0(t, \tau)q(\tau) d\tau + \sum_{l \in \mathcal{N}_{t_0, t}} H^{-1}(\tau_l)C_0(t, \tau_l)G_{0l}(I_n + G_{0l})^{-1}g_l \right\| = 0.$$

Then the problem (1), (2); (3) has the unique solution.

References

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