

Oscillatory Properties of Solutions to Two-Dimensional Emden–Fowler Type Systems

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On the half-line $[0, +\infty[$, we consider the system

$$\boxed{\begin{aligned} u' &= g(t)|v|^{1/\alpha} \operatorname{sgn} v, \\ v' &= -p(t)|u|^\alpha \operatorname{sgn} u, \end{aligned}} \quad (1)$$

where $\alpha > 0$ and $p, g: [0, +\infty[\rightarrow \mathbb{R}$ are locally Lebesgue integrable functions.

A pair (u, v) is said to be a *solution to system (1) on the interval* $I \subseteq [0, +\infty[$ if the functions $u, v: I \rightarrow \mathbb{R}$ are absolutely continuous on every compact interval contained in I and satisfy equalities (1) almost everywhere in I . In the paper [5], Mirzov proved that all non-extendable solutions to system (1) are defined on the whole interval $[0, +\infty[$. Therefore, speaking about a solution to system (1), we assume without loss of generality that it is defined on the whole interval $[0, +\infty[$. Mirzov also proved (see, e.g., [4, Theorem 9.3]) that all non-zero solutions (u, v) to system (1) are proper, i.e., the inequality $\sup\{|u(\tau)| + |v(\tau)| : t \leq \tau < +\infty\} > 0$ holds for every $t \geq 0$.

Definition 1. A solution (u, v) to system (1) is called *non-trivial* if $u \not\equiv 0$ on any neighbourhood of $+\infty$. We say that a non-trivial solution (u, v) to system (1) is *oscillatory* if the function u has a sequence of zeros tending to infinity, and *non-oscillatory* otherwise.

It is well known (see [5, Theorem 1.1]) that a certain analog of Sturm's theorem holds for system (1) under the additional assumption

$$g(t) \geq 0 \quad \text{for a.e. } t \geq 0. \quad (2)$$

In particular, if inequality (2) holds and system (1) has an oscillatory solution, then any other non-trivial solution is also oscillatory. Moreover, under assumption (2), if (u, v) is an oscillatory solution to system (1), then, together with u , the function v also oscillates. On the other hand, it is clear that if $g \equiv 0$ on some neighbourhood of $+\infty$, then all non-trivial solutions to system (1) are non-oscillatory.

Therefore, we assume throughout the paper that inequality (2) holds and

$$\operatorname{meas} \{\tau \geq t : g(\tau) > 0\} > 0 \quad \text{for every } t \geq 0. \quad (3)$$

Definition 2. We say that system (1) is *oscillatory* if all its non-trivial solutions are oscillatory.

We first assume that the coefficient g is non-integrable on $[0, +\infty[$, i.e.,

$$\int_0^\infty g(s) \, ds = +\infty. \tag{4}$$

Let

$$f_1(t) := \int_0^t g(s) \, ds \quad \text{for } t \geq 0.$$

In view of assumptions (2), (3), and (4), we have $\lim_{t \rightarrow +\infty} f_1(t) = +\infty$ and there exists a number $t_g \geq 0$ such that $f_1(t) > 0$ for $t > t_g$ and $f_1(t_g) = 0$. Since we are interested in behaviour of solutions in the neighbourhood of $+\infty$, we can assume without loss of generality that $t_g = 0$, i.e., $f_1(t) > 0$ for $t > 0$.

For any $\kappa > \alpha$, $\beta > 0$, and $\lambda < \alpha$, we put

$$k_1(t; \kappa, \beta, \lambda) := \frac{1}{f_1^{\kappa\beta}(t)} \int_0^t [f_1^\beta(t) - f_1^\beta(s)]^\kappa f_1^\lambda(s) p(s) \, ds \quad \text{for } t > 0, \tag{5}$$

$$c_1(t; \lambda) := \frac{\alpha - \lambda}{f_1^{\alpha-\lambda}(t)} \int_0^t \frac{g(s)}{f_1^{\lambda+1-\alpha}(s)} \left(\int_0^s f_1^\lambda(\xi) p(\xi) \, d\xi \right) ds \quad \text{for } t > 0. \tag{6}$$

Theorem 1. *Let conditions (2), (3), and (4) hold, $\kappa > \alpha$, $\beta > 0$, $\lambda < \alpha$, and either*

$$\limsup_{t \rightarrow +\infty} k_1(t; \kappa, \beta, \lambda) = +\infty \tag{7}$$

or

$$\begin{cases} -\infty < \limsup_{t \rightarrow +\infty} k_1(t; \kappa, \beta, \lambda) < +\infty, \\ \text{the function } c_1(\cdot; \lambda) \text{ does not possess a finite limit as } t \rightarrow +\infty. \end{cases} \tag{8}$$

Then system (1) is oscillatory.

Observe that condition (7) with $\beta = 1$, $\lambda = 0$ and $g \equiv 1$ reduces to the condition

$$\limsup_{t \rightarrow +\infty} \frac{1}{t^\kappa} \int_0^t (t-s)^\kappa p(s) \, ds = +\infty \quad \text{for some } \kappa > \alpha \tag{9}$$

which is the half-linear extension of the classical Kamenev linear oscillation criterion (see [2]). Conditions (8) then give a possible counterpart of the oscillation criterion (9).

It is well known that system (1) is oscillatory provided that the function

$$M: t \mapsto \frac{1}{f_1(t)} \int_0^t g(s) \left(\int_0^s p(\xi) \, d\xi \right) ds \tag{10}$$

is bounded from below in some neighbourhood of $+\infty$ and does not have a finite limit as $t \rightarrow +\infty$ (see, e.g., [4, Theorem 12.3]). However, Theorem 1 can be applied also in the case, where the lower limit of the function M given by (10) is $-\infty$.

Now we formulate a Hartman–Wintner type result which follows from Theorem 1. For any $\lambda < \alpha$ and $\nu < 1$, we put

$$\tilde{c}_1(t; \lambda, \nu) := \frac{1 - \nu}{f_1^{1-\nu}(t)} \int_0^t \frac{g(s)}{f_1^\nu(s)} \left(\int_0^s f_1^\lambda(\xi) p(\xi) d\xi \right) ds \quad \text{for } t > 0. \quad (11)$$

Corollary 1. *Let conditions (2), (3), and (4) hold, $\lambda < \alpha$, $\nu < 1$, and either*

$$\lim_{t \rightarrow +\infty} \tilde{c}_1(t; \lambda, \nu) = +\infty$$

or

$$-\infty < \liminf_{t \rightarrow +\infty} \tilde{c}_1(t; \lambda, \nu) < \limsup_{t \rightarrow +\infty} \tilde{c}_1(t; \lambda, \nu).$$

Then system (1) is oscillatory.

Observe that Corollary 1 with $\lambda = 0$ and $\nu = 0$ coincide with the above-mentioned Mirzov's result, namely Theorem 12.3 from [4]. On the other hand, it is worth mentioning that Corollary 1 with $g \equiv 1$, $\lambda = 0$ and $\nu = 1 - \alpha$ is in compliance with Theorem 1.1 stated in [3].

Unlike the above part, we assume in what follows that g is integrable on $[0, +\infty[$, i.e.,

$$\int_0^{+\infty} g(s) ds < +\infty. \quad (12)$$

Let

$$f_2(t) := \int_t^{+\infty} g(s) ds \quad \text{for } t \geq 0.$$

In view of assumptions (2), (3), and (12), we have $\lim_{t \rightarrow +\infty} f_2(t) = 0$ and $f_2(t) > 0$ for $t \geq 0$.

For any $\kappa > \alpha$, $\beta > 0$, and $\lambda > \alpha$, we put

$$k_2(t; \kappa, \beta, \lambda) := f_2^{\kappa\beta}(t) \int_0^t [f_2^{-\beta}(t) - f_2^{-\beta}(s)]^\kappa f_2^\lambda(s) p(s) ds \quad \text{for } t \geq 0, \quad (13)$$

$$c_2(t; \lambda) := (\lambda - \alpha) f_2^{\lambda - \alpha}(t) \int_0^t \frac{g(s)}{f_2^{\lambda + 1 - \alpha}(s)} \left(\int_0^s f_2^\lambda(\xi) p(\xi) d\xi \right) ds \quad \text{for } t \geq 0. \quad (14)$$

Theorem 2. *Let conditions (2), (3), and (12) hold, $\kappa > \alpha$, $\beta > 0$, $\lambda > \alpha$, and either*

$$\limsup_{t \rightarrow +\infty} k_2(t; \kappa, \beta, \lambda) = +\infty \quad (15)$$

or

$$\left\{ \begin{array}{l} -\infty < \limsup_{t \rightarrow +\infty} k_2(t; \kappa, \beta, \lambda) < +\infty, \\ \text{the function } c_2(\cdot; \lambda) \text{ does not possess a finite limit as } t \rightarrow +\infty. \end{array} \right. \quad (16)$$

Then system (1) is oscillatory.

Analogously to the “non-integrable” case, the following Hartman–Wintner type result can be derived from Theorem 2. For any $\lambda > \alpha$ and $\nu > 1$, we put

$$\tilde{c}_2(t; \lambda, \nu) := (\nu - 1) f_2^{\nu-1}(t) \int_0^t \frac{g(s)}{f_2^\nu(s)} \left(\int_0^s f_2^\lambda(\xi) p(\xi) d\xi \right) ds \quad \text{for } t \geq 0. \quad (17)$$

Corollary 2. *Let conditions (2), (3), and (12) hold, $\lambda > \alpha$, $\nu > 1$, and either*

$$\lim_{t \rightarrow +\infty} \tilde{c}_2(t; \lambda, \nu) = +\infty$$

or

$$-\infty < \liminf_{t \rightarrow +\infty} \tilde{c}_2(t; \lambda, \nu) < \limsup_{t \rightarrow +\infty} \tilde{c}_2(t; \lambda, \nu).$$

Then system (1) is oscillatory.

As far as we know, a Hartman–Wintner type result for the half-linear equation

$$\boxed{(r(t)|u'|^{q-1} \operatorname{sgn} u')' + p(t)|u|^{q-1} \operatorname{sgn} u = 0} \tag{18}$$

in the case, where

$$\int_0^{+\infty} r^{\frac{1}{1-q}}(s) \, ds < +\infty \tag{19}$$

is satisfied, is known only under the additional assumption that $p(t) \geq 0$ for a. e. $t \geq 0$ (see survey given in [1, Section 2.2]). We can exclude this additional assumption and derive from Corollary 2 the following statement.

Corollary 3. *Let $\lambda > q - 1$ and relation (19) hold. Then each of following two conditions is sufficient for oscillation of (18):*

$$\begin{aligned} & \lim_{t \rightarrow +\infty} R(t) \int_0^t \frac{1}{r^{\frac{1}{q-1}}(s)R^2(s)} \left(\int_0^s R^\lambda(\xi)p(\xi) \, d\xi \right) ds = +\infty, \\ -\infty & < \liminf_{t \rightarrow +\infty} R(t) \int_0^t \frac{1}{r^{\frac{1}{q-1}}(s)R^2(s)} \left(\int_0^s R^\lambda(\xi)p(\xi) \, d\xi \right) ds < \\ & < \limsup_{t \rightarrow +\infty} R(t) \int_0^t \frac{1}{r^{\frac{1}{q-1}}(s)R^2(s)} \left(\int_0^s R^\lambda(\xi)p(\xi) \, d\xi \right) ds, \end{aligned}$$

where $R(t) := \int_t^{+\infty} r^{\frac{1}{1-q}}(s) \, ds$ for $t \geq 0$.

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