

On the Nonlinear Boundary Value Problems for Systems of Impulsive Equations with Finite Points of Impulses Actions

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We consider the general nonlinear boundary value problem for the system of impulsive equations with finite number of impulses points

$$\frac{dx}{dt} = f(t, x) \text{ almost everywhere on } [a, b] \setminus \{\tau_1, \dots, \tau_{m_0}\}, \quad (1)$$

$$x(\tau_l+) - x(\tau_l-) = I_l(x(\tau_l)) \quad (l = 1, \dots, m_0); \quad (2)$$

$$h(x) = 0, \quad (3)$$

where $-\infty < a < \tau_1 < \dots < \tau_{m_0} \leq b < \infty$, m_0 is a natural number, $f \in \text{Car}([a, b] \times \mathbb{R}^n, \mathbb{R}^n)$, $I_l : \mathbb{R}^n \rightarrow \mathbb{R}^n$ ($l = 1, \dots, m_0$) are continuous operators, and $h : C_s([a, b], \mathbb{R}^n; m_0) \rightarrow \mathbb{R}^n$ is a continuous, nonlinear in general, vector-functional.

We give the Conti–Opial type theorems (among them effective sufficient conditions) for the solvability of the problem which are analogous to ones given in [1] (see also the references therein) for ordinary differential equations.

Basic notation and definitions. $\mathbb{R} =] - \infty, +\infty[$, $\mathbb{R}_+ = [0, +\infty[$. $\mathbb{R}^{n \times m}$ is the space of all real $n \times m$ -matrices $X = (x_{ij})_{i,j=1}^{n,m}$; $|X| = (|x_{ij}|)_{i,j}^{n,m}$. $\mathbb{R}_+^{n \times m}$ is the set of all real nonnegative $n \times m$ -matrices. $I_{n \times n}$ is the identity $n \times n$ -matrix. $r(X)$ is the spectral radius of $X \in \mathbb{R}^{n \times n}$. $\mathbb{R}^n = \mathbb{R}^{n \times 1}$.

$X(t-)$ and $X(t+)$ are one-sided limits of the matrix-function X at the point t .

$C([a, b], \mathbb{R}^n; m_0)$ is the set of all vector-functions $x : [a, b] \rightarrow \mathbb{R}^n$, having the one sided limits $x(\tau_l-)$ and $x(\tau_l+)$ ($l = 1, \dots, m_0$), whose restrictions to every closed interval from $[a, b] \setminus \{\tau_1, \dots, \tau_{m_0}\}$ is continuous. $C_s([a, b], \mathbb{R}^n; m_0)$ is the Banach space with the norm $\|x\|_s = \sup\{\|x(t)\| : t \in [a, b]\}$.

$\tilde{C}([a, b], \mathbb{R}^n; m_0)$ is the set of all matrix-functions $x : [a, b] \rightarrow \mathbb{R}^n$, having the one sided limits $x(\tau_l-)$ and $x(\tau_l+)$ ($l = 1, \dots, m_0$), whose restrictions to an arbitrary closed interval from $[a, b] \setminus \{\tau_k\}_{k=1}^{m_0}$ is absolutely continuous.

If B_1 and B_2 are normed spaces, then an operator $g : B_1 \rightarrow B_2$ (nonlinear, in general) is positive homogeneous if $g(\lambda x) = \lambda g(x)$ for every $\lambda \in \mathbb{R}_+$ and $x \in B_1$. An operator $\varphi : C([a, b], \mathbb{R}^{n \times m}; m_0) \rightarrow \mathbb{R}^n$ is called nondecreasing if for every x, y such that $x(t) \leq y(t)$ for $t \in [a, b]$ the inequality $\varphi(x)(t) \leq \varphi(y)(t)$ holds for $t \in [a, b]$.

$\text{Car}([a, b] \times D_1, D_2)$, where $D_1 \subset \mathbb{R}^n$ and $D_2 \subset \mathbb{R}^{n \times m}$, is the standard Carathéodory class of all mappings $F : [a, b] \times D_1 \rightarrow D_2$; $\text{Car}^0([a, b] \times D_1, D_2)$ is the set of all mappings F such that the matrix-function $F(\cdot, x(\cdot))$ is measurable for every vector-function $x \in C([a, b], D_1; m_0)$.

By a solution of the impulsive system (1), (2) we understand a continuous from the left vector-function $x \in \tilde{C}([a, b], \mathbb{R}^n; m_0)$ satisfying both the system (1) a. e. on $[a, b] \setminus \{\tau_1, \dots, \tau_{m_0}\}$ and the relation (2) for every $k \in \{1, \dots, m_0\}$.

Definition. Let $\ell : C_s([a, b], \mathbb{R}^n; m_0) \rightarrow \mathbb{R}^n$ and $\ell_0 : C_s([a, b], \mathbb{R}^n; m_0) \rightarrow \mathbb{R}_+^n$ be, respectively, a linear continuous and a positive homogeneous operators. We say that a pair $(P, \{J_l\}_{l=1}^{m_0})$, consisting of a matrix-function $P \in \text{Car}([a, b] \times \mathbb{R}^n, \mathbb{R}^{n \times n})$ and a finite sequence of continuous operators $J_l = (J_{li})_{i=1}^n : \mathbb{R}^n \rightarrow \mathbb{R}^n$ ($l = 1, \dots, m_0$), satisfy the Opial condition with respect to the pair (ℓ, ℓ_0) if:

- (a) there exist a matrix-function $\Phi \in L([a, b], \mathbb{R}_+^n)$ and constant matrices $\Psi_l \in \mathbb{R}^{n \times n}$ ($l = 1, \dots, m_0$) such that $|P(t, x)| \leq \Phi(t)$ for a.e. $[a, b]$ and $x \in \mathbb{R}^n$;
- (b) $|J_l(x)| \leq \Psi_l$ for $x \in \mathbb{R}^n$ ($l = 1, \dots, m_0$);
- (c) $\det(I_{n \times n} + G_l) \neq 0$ ($l = 1, \dots, m_0$) and the problem

$$\frac{dx}{dt} = A(t)x, \quad x(\tau_l+) - x(\tau_l-) = G_l x(\tau_l) \quad (l = 1, \dots, m_0); \quad |\ell(x)| \leq \ell_0(x) \quad (4)$$

has only the trivial solution for every matrix-function $A \in L([a, b], \mathbb{R}^{n \times n})$ and constant matrices G_1, \dots, G_{m_0} for which there exists a sequence $y_k \in \tilde{C}([a, b], \mathbb{R}^n; m_0)$ ($k = 1, 2, \dots$) such that

$$\lim_{k \rightarrow +\infty} \int_a^t (P(\tau, y_k(\tau)) - A(\tau)) d\tau = 0 \text{ uniformly on } [a, b] \text{ and } \lim_{k \rightarrow +\infty} J_l(y_k(\tau_l)) = G_l \quad (l = 1, \dots, m_0).$$

Theorem 1. *Let the conditions*

$$\|f(t, x) - P(t, x)x\| \leq q(t, \|x\|) \text{ a.e. on } [a, b] \setminus \{\tau_1, \dots, \tau_{m_0}\}, \quad x \in \mathbb{R}^n, \quad (5)$$

$$\|J_l(x) - J_l(x)x\| \leq \beta_l(\|x\|) \text{ for } x \in \mathbb{R}^n \quad (l = 1, \dots, m_0), \quad (6)$$

$$|h(x) - \ell(x)| \leq \ell_0(x) + \ell_1(\|x\|_s) \text{ for } x \in \text{BV}([a, b], \mathbb{R}^n) \quad (7)$$

hold, where $\ell : C_s([a, b], \mathbb{R}^n; m_0) \rightarrow \mathbb{R}^n$ and $\ell_0 : C_s([a, b], \mathbb{R}^n; m_0) \rightarrow \mathbb{R}_+^n$ are, respectively, linear continuous and positive homogeneous continuous operators, the pair $(P, \{J_l\}_{l=1}^{m_0})$ satisfies the Opial condition with respect to the pair (ℓ, ℓ_0) ; $q \in \text{Car}([a, b] \times \mathbb{R}_+, \mathbb{R}_+)$ is a function nondecreasing in the second variable, and $\beta_l \in C(\mathbb{R}_+, \mathbb{R}_+)$ ($l = 1, \dots, m_0$) and $\ell_1 \in C(\mathbb{R}_+, \mathbb{R}_+^n)$ are nondecreasing, respectively, functions and vector-function such that

$$\limsup_{\rho \rightarrow +\infty} \frac{1}{\rho} \left(\|\ell_1(\rho)\| + \int_a^b q(t, \rho) dt + \sum_{l=1}^{m_0} \beta_l(\rho) \right) < 1. \quad (8)$$

Then the problem (1), (2); (3) is solvable.

Theorem 2. *Let the conditions (5)–(8), $P_1(t) \leq P(t, x) \leq P_2(t)$ for a.a. $t \in [a, b] \setminus \{\tau_1, \dots, \tau_{m_0}\}$ and $x \in \mathbb{R}^n$, and $J_{1l} \leq I_k(x) \leq J_{2l}$ for $x \in \mathbb{R}^n$ ($l = 1, \dots, m_0$) hold, where $P \in \text{Car}^0([a, b] \times \mathbb{R}^n, \mathbb{R}^{n \times n})$, $P_i \in L([a, b], \mathbb{R}^{n \times n})$ ($i = 1, 2$), $J_{il} \in \mathbb{R}^{n \times n}$ ($i = 1, 2; l = 1, \dots, m_0$), $\ell : C_s([a, b], \mathbb{R}^n; m_0) \rightarrow \mathbb{R}^n$ and $\ell_0 : C_s([a, b], \mathbb{R}^n; m_0) \rightarrow \mathbb{R}_+^n$ are, respectively, linear continuous and positive homogeneous continuous operators; $q \in \text{Car}([a, b] \times \mathbb{R}_+, \mathbb{R}_+)$ is a function nondecreasing in the second variable, and $\beta_l \in C([a, b], \mathbb{R}_+)$ ($l = 1, \dots, m_0$) and $\ell_1 \in C(\mathbb{R}_+, \mathbb{R}_+^n)$ are nondecreasing, respectively, functions and vector-function. Let, moreover, the inequalities in (c) of definition hold and the problem (4) have only the trivial solution for every matrix-function $A \in L([a, b], \mathbb{R}^{n \times n})$ and constant matrices $G_l \in \mathbb{R}^{n \times n}$ ($l = 1, \dots, m_0$) such that $P_1(t) \leq A(t) \leq P_2(t)$ for a.a. $t \in [a, b] \setminus \{\tau_1, \dots, \tau_{m_0}\}$ and $x \in \mathbb{R}^n$, and $J_{1l} \leq G_l \leq J_{2l}$ for $x \in \mathbb{R}^n$ ($l = 1, \dots, m_0$). Then the problem (1), (2); (3) is solvable.*

Remark. Theorem 2 is interesting only in the case when $P \notin \text{Car}([a, b] \times \mathbb{R}^n, \mathbb{R}^{n \times n})$, because otherwise it follows from Theorem 1.

Corollary 1. *Let the conditions (5)–(8) hold, where $P(t, x) \equiv P(t)$, $P \in L([a, b], \mathbb{R}^{n \times n})$, $J_l(x) \equiv J_l \in \mathbb{R}^{n \times n}$ ($l = 1, \dots, m_0$) are constant matrices, $\ell_0(x) \equiv 0$, $\ell : C_s([a, b], \mathbb{R}^n; m_0) \rightarrow \mathbb{R}^n$ is a linear continuous operator, $q \in \text{Car}([a, b] \times \mathbb{R}_+, \mathbb{R}_+)$ is a function nondecreasing in the second variable, and $\beta_l \in C([a, b], \mathbb{R}_+)$ ($l = 1, \dots, m_0$) and $\ell_1 \in C(\mathbb{R}_+, \mathbb{R}_+^n)$ are nondecreasing, respectively, functions and vector-function. Let, moreover, $\det(I_{n \times n} + J_l) \neq 0$ ($l = 1, \dots, m_0$) and the homogeneous impulsive problem $dx/dt = P(t)x$, $x(\tau_l+) - x(\tau_l-) = J_l x(\tau_l)$ ($l = 1, \dots, m_0$); $\ell(x) = 0$ have only the trivial solution. Then the problem (1), (2); (3) is solvable.*

We give the effective conditions for the solvability of the problem (1), (2); (3).

For every matrix-function $X \in L([a, b], \mathbb{R}^{n \times n})$ and constant matrices $Y_k \in \mathbb{R}^{n \times n}$ ($k = 1, \dots, m_0$) we introduce the operators $[(X, Y_1, \dots, Y_{m_0})(t)]_0 \equiv I_{n \times n}$, $[(X, Y_1, \dots, Y_{m_0})(t)]_{i+1} \equiv \int_a^t X(\tau) [(X, Y_1, \dots, Y_{m_0})(\tau)]_i d\tau + \sum_{a \leq \tau_i < t} Y_i [(X, Y_1, \dots, Y_{m_0})(\tau)]_i$ ($i = 0, 1, \dots$).

Corollary 2. *Let the matrix-function $P \in L([a, b], \mathbb{R}^{n \times n})$, constant matrices $J_l \in \mathbb{R}^{n \times n}$ ($l = 1, \dots, m_0$), the functions $q \in \text{Car}([a, b] \times \mathbb{R}_+, \mathbb{R}_+)$, $\beta_l \in C(\mathbb{R}_+, \mathbb{R}_+)$ ($l = 1, \dots, m_0$) and $\ell_1 \in C(\mathbb{R}_+, \mathbb{R}_+)$ satisfy the conditions of Corollary 1, where $\ell_0(x) \equiv 0$, and $\ell(x) \equiv \int_a^b d\mathcal{L}(t) \cdot x(t)$, $\mathcal{L} \in L([a, b], \mathbb{R}^{n \times n})$. Let, moreover, there exist natural numbers k and m such that the matrix $M_k = - \sum_{i=0}^{k-1} \int_a^b d\mathcal{L}(t) \cdot [(P, J_1, \dots, J_{m_0})(t)]_i$ is nonsingular and $r(M_{k,m}) < 1$, where $M_{k,m} = [(|P|, |J_1|, \dots, |J_{m_0}|)(b)]_m + \sum_{i=0}^{m-1} [(|P|, |J_1|, \dots, |J_{m_0}|)(b)]_i \int_a^b dV(M_k^{-1}\mathcal{L})(t) \cdot [(|P|, |J_1|, \dots, |J_{m_0}|)(t)]_k$. Then the problem (1), (2); (3) is solvable.*

Corollary 3. *Let the matrix-function $P \in L([a, b], \mathbb{R}^{n \times n})$, constant matrices $J_l \in \mathbb{R}^{n \times n}$ ($l = 1, \dots, m_0$), the functions $q \in \text{Car}([a, b] \times \mathbb{R}_+, \mathbb{R}_+)$, $\beta_l \in C(\mathbb{R}_+, \mathbb{R}_+)$ ($l = 1, \dots, m_0$) and $\ell_1 \in C(\mathbb{R}_+, \mathbb{R}_+)$ satisfy the conditions of Corollary 1, where $\ell_0(x) \equiv 0$, and $\ell(x) \equiv \sum_{j=1}^{n_0} \mathcal{L}_j x(t_j)$, $t_j \in [a, b]$, $\mathcal{L}_j \in \mathbb{R}^{n \times n}$ ($j = 1, \dots, n_0$). Let, moreover, there exist natural numbers k and m such that the matrix $M_k = \sum_{j=1}^{n_0} \sum_{i=0}^{k-1} \mathcal{L}_j [(P_0, J_1, \dots, J_{m_0})(t_j)]_i$ is nonsingular and $r(M_{k,m}) < 1$, where $M_{k,m} = [(|P|, |J_1|, \dots, |J_{m_0}|)(b)]_m + \left(\sum_{i=0}^{m-1} [(|P|, |J_1|, \dots, |J_{m_0}|)(b)]_i \right) \cdot \sum_{j=1}^{n_0} |M_k^{-1} \mathcal{L}_j| [(|P|, |J_1|, \dots, |J_{m_0}|)(t_j)]_k$. Then the problem (1), (2); (3) is solvable.*

Corollary 4. *Let the matrix-function $P \in L([a, b], \mathbb{R}^{n \times n})$, constant matrices $J_l \in \mathbb{R}^{n \times n}$ ($l = 1, \dots, m_0$), the functions $q \in \text{Car}([a, b] \times \mathbb{R}_+, \mathbb{R}_+)$, $\beta_l \in C(\mathbb{R}_+, \mathbb{R}_+)$ ($l = 1, \dots, m_0$) and $\ell_1 \in C(\mathbb{R}_+, \mathbb{R}_+)$ satisfy the conditions of Corollary 1, where $\ell_0(x) \equiv 0$, and $\ell(x) \equiv \sum_{j=1}^{n_0} \mathcal{L}_j x(t_j)$, $t_j \in [a, b]$, $\mathcal{L}_j \in \mathbb{R}^{n \times n}$ ($j = 1, \dots, n_0$). Let, moreover, $\det \left(\sum_{j=1}^{n_0} \mathcal{L}_j \right) \neq 0$ and $r(\mathcal{L}_0 \cdot V(A)(b)) < 1$, where $\mathcal{L}_0 = I_{n \times n} + \left| \left(\sum_{j=1}^{n_0} \mathcal{L}_j \right)^{-1} \right| \cdot \sum_{j=1}^{n_0} |\mathcal{L}_j|$ and $A = \int_a^b |P(t)| dt + \sum_{l=1}^{m_0} |J_l|$. Then the problem (1), (2); (3) is solvable.*

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