

The Boundary Value Problem for One Class of Semilinear Partial Differential Equations

Sergo Kharibegashvili

A. Razmadze Mathematical Institute of I. Javakishvili Tbilisi State University, Tbilisi, Georgia
E-mail: kharibegashvili@yahoo.com

In the Euclidean space \mathbb{R}^{n+1} of the variables $x = (x_1, x_2, \dots, x_n)$ and t we consider the semilinear equation of the type

$$\frac{\partial^{4k} u}{\partial t^{4k}} - \Delta u + f(u) = F, \tag{1}$$

where $f : \mathbb{R} \rightarrow \mathbb{R}$ is a given continuous function, $F = F(x, t)$ is a given, and $u = u(x, t)$ is an unknown real functions, k is a natural number, $\Delta := \sum_{i=1}^n \frac{\partial^2}{\partial x_i^2}$, $n \geq 2$.

For the equation (1) we consider the boundary value problem: find in the cylindrical domain $D_T = \Omega \times (0, T)$, where Ω is an open Lipschitz domain in \mathbb{R}^n , a solution $u(x, t)$ of that equation according to the boundary conditions

$$u|_{\Gamma} = 0, \tag{2}$$

$$\frac{\partial^i u}{\partial t^i} \Big|_{\Omega_0 \cup \Omega_T} = 0, \quad i = 1, \dots, 2k - 1, \tag{3}$$

where $\Gamma := \partial\Omega \times (0, T)$ is the lateral face of the cylinder D_T , $\Omega_0 : x \in \Omega, t = 0$ and $\Omega_T : x \in \Omega, t = T$ are the lower and upper bases of this cylinder, respectively.

Denote by $C^{2,4k}(\overline{D_T}, \partial D_T)$ the space of functions u continuous in $\overline{D_T}$ and having continuous partial derivatives $\frac{\partial u}{\partial x_i}, \frac{\partial^2 u}{\partial x_i \partial x_j}, \frac{\partial^l u}{\partial t^l}$ in $\overline{D_T}$, $i, j = 1, \dots, n; l = 1, \dots, 4k$. Let

$$C_0^{2,4k}(\overline{D_T}, \partial D_T) := \left\{ u \in C^{2,4k}(\overline{D_T}, \partial D_T) : u|_{\Gamma} = 0, \frac{\partial^i u}{\partial t^i} \Big|_{\Omega_0 \cup \Omega_T} = 0 \quad i = 1, \dots, 2k - 1 \right\}.$$

Let $u \in C_0^{2,4k}(\overline{D_T}, \partial D_T)$ be a classical solution of the problem (1), (2), (3). Multiplying both parts of the equation (1) by an arbitrary function $\varphi \in C_0^{2,4k}(\overline{D_T}, \partial D_T)$ and integrating the obtained equation by parts over the domain D_T , we obtain

$$\int_{D_T} \left[\frac{\partial^{2k} u}{\partial t^{2k}} \frac{\partial^{2k} \varphi}{\partial t^{2k}} + \sum_{i=1}^n \frac{\partial u}{\partial x_i} \frac{\partial \varphi}{\partial x_i} \right] dx dt + \int_{D_T} f(u) \varphi dx dt = \int_{D_T} F \varphi dx dt. \tag{4}$$

Introduce the Hilbert space $W_0^{1,2k}(D_T)$ as a completion with respect to the norm

$$\|u\|_{W_0^{1,2k}(D_T)}^2 = \int_{D_T} \left[u^2 + \sum_{i=1}^{2k} \left(\frac{\partial^i u}{\partial t^i} \right)^2 + \sum_{i=1}^n \left(\frac{\partial u}{\partial x_i} \right)^2 \right] dx dt$$

of the classical space $C_0^{2,4k}(\overline{D_T}, \partial D_T)$.

We take the equality (4) as a basis for our definition of the weak generalized solution u of the problem (1), (2), (3): the function $u \in W_0^{1,2k}(D_T)$ is said to be a weak generalized solution of the problem (1), (2), (3) if for any function $\varphi \in W_0^{1,2k}(D_T)$ the integral equality (4) is valid.

It is not difficult to verify that if the weak generalized solution of the problem (1), (2), (3) belongs to the class $C_0^{2,4k}(\overline{D_T}, \partial D_T)$, then it will also be a classical solution of this problem.

Below, on the function $f = f(u)$ we impose the following requirements

$$f \in C(\mathbb{R}), \quad |f(u)| \leq M_1 + M_2|u|^\alpha, \quad u \in \mathbb{R}, \quad (5)$$

where

$$0 \leq \alpha = \text{const} < \frac{n+1}{n-1}, \quad (6)$$

and

$$uf(u) \geq 0 \quad \forall u \in \mathbb{R}. \quad (7)$$

Theorem. *Let the conditions (5)–(7) be fulfilled. Then for any $F \in L_2(D)$ the problem (1), (2), (3) has at least one weak generalized solution $u \in W_0^{1,2k}(D_T)$.*

Remark. Let us note that if along with the conditions (5)–(7) imposed on function f to demand that it is monotonous, then the solution $u \in W_0^{1,2k}(D_T)$ of the problem (1), (2), (3), the existence of which is stated in the theorem, is unique. As show the examples, when the conditions imposed on nonlinear function f are violated, then the problem (1), (2), (3) may not have a solution.

Acknowledgement

The work was supported by the Shota Rustaveli Natural Science Foundation, Grant # FR/86/5–109/14.