

Green–Samoilenko Function and Existence of Integral Sets of Linear Extensions of Differential Equations with Impulses

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We consider the following system of differential equations with impulsive perturbations [7, 9]

$$\frac{d\varphi}{dt} = a(t, \varphi), \quad \frac{dx}{dt} = P(t, \varphi)x + f(t, \varphi), \quad t \neq \tau_i, \quad \Delta x|_{t=\tau_i} = B_i(\varphi)x + I_i(\varphi), \quad (1)$$

where $t \in R$, $x \in R^n$, $\varphi \in \mathfrak{S}^m$, \mathfrak{S}^m is an m -dimensional torus; $a(t, \varphi)$, $f(t, \varphi)$, $P(t, \varphi)$ are continuous (piecewise continuous with first-kind discontinuities at $t = \tau_i$) with respect to t , continuous and 2π -periodic with respect to φ_ν , $\nu = \overline{1, m}$, bounded for all $t \in R$, $\varphi \in \mathfrak{S}^m$ vector and matrix functions, respectively. Functions $B_i(\varphi)$ and $I_i(\varphi)$ are uniformly bounded with respect to $i \in Z$ matrices and vectors, $\det(E + B_i(\varphi)) \neq 0$ for any $\varphi \in \mathfrak{S}^m$. The sequence of the moments of impulsive perturbations $\{\tau_i\}$ is such that $\tau_i \rightarrow -\infty$ for $i \rightarrow -\infty$ and $\tau_i \rightarrow +\infty$ for $i \rightarrow +\infty$. We assume that there exists $\theta > 0$ such that for any $i \in Z$,

$$\tau_{i+1} - \tau_i \geq \theta > 0. \quad (2)$$

Function $a(t, \varphi)$ satisfies the Lipschitz condition with respect to φ and

$$\sup_{t \in R} \|a(t, \varphi_1) - a(t, \varphi_2)\| \leq l \|\varphi_1 - \varphi_2\| \quad (3)$$

holds uniformly with respect to $t \in R$. Additionally assume that functions $f(t, \varphi)$ and $I_i(\varphi)$ satisfy the following condition

$$\sup_{t \in R} \max_{\varphi \in \mathfrak{S}^m} \|f(t, \varphi)\| + \sup_{i \in Z} \max_{\varphi \in \mathfrak{S}^m} \|I_i(\varphi)\| = M < \infty.$$

The problems of the existence of bounded solutions and integral sets for the system of the type (1) were considered in [1, 2]. The problems of the persistence of integral sets under the perturbations of the right-hand side were considered in [3, 6]. In this paper, analogously to [4, 5, 8], we introduce the notion of Green–Samoilenko function of the problem on integral sets of differential equations with impulses and provide sufficient conditions for the existence of integral sets.

Consider the non-autonomous system of differential equations defined on the surface of the torus \mathfrak{S}^m

$$\frac{d\varphi}{dt} = a(t, \varphi) \quad (4)$$

and denote by $\varphi_t(\tau, \varphi)$ a solution of this system satisfying the initial condition $\varphi_\tau(\tau, \varphi) = \varphi$. From the compactness of the phase space of system (4) and the assumptions regarding function $a(t, \varphi)$, for any initial condition $\varphi_\tau(\tau, \varphi) = \varphi$, $\tau \in R$, $\varphi \in \mathfrak{S}^m$ the corresponding solution $\varphi_t(\tau, \varphi)$ exists and can be prolonged to the entire real axis R .

Consider the following non-homogenous system of differential equations with impulsive perturbations

$$\begin{aligned} \frac{dx}{dt} &= P(t, \varphi_t(\tau, \varphi))x + f(t, \varphi_t(\tau, \varphi)), \quad t \neq \tau_i, \\ \Delta x|_{t=\tau_i} &= B_i(\varphi_{\tau_i}(\tau, \varphi))x + I_i(\varphi_{\tau_i}(\tau, \varphi)) \end{aligned} \quad (5)$$

and the corresponding homogeneous system

$$\begin{aligned} \frac{dx}{dt} &= P(t, \varphi_t(\tau, \varphi))x, \quad t \neq \tau_i, \\ \Delta x|_{t=\tau_i} &= B_i(\varphi_{\tau_i}(\tau, \varphi))x, \end{aligned} \tag{6}$$

and denote by $\Omega_s^t(\tau, \varphi)$ the fundamental matrix of (6). Due to continuous dependence of $\varphi_t(\tau, \varphi)$ on parameters $\tau \in R$ and $\varphi \in \mathfrak{S}^m$, the fundamental matrix $\Omega_s^t(\tau, \varphi)$ depends on these parameters also continuously.

Lemma. *For any $t, s, \tau, \sigma \in R$ and $\varphi \in \mathfrak{S}^m$ the following relation holds*

$$\Omega_s^t(\tau, \varphi_\tau(\sigma, \varphi)) = \Omega_s^t(\sigma, \varphi).$$

Let $C(t, \varphi)$ be continuous 2π -periodic with respect to each of the component φ_ν , $\nu = \overline{1, m}$, piecewise continuous with respect to $t \in R$, with first-kind discontinuities at the points $\{\tau_i\}$ matrix function. Denote

$$G(t, s, \varphi) = \begin{cases} \Omega_s^t(t, \varphi)C(s, \varphi_s(t, \varphi)), & s \leq t, \\ -\Omega_s^t(t, \varphi)[E - C(s, \varphi_s(t, \varphi))], & s > t \end{cases} \tag{7}$$

and call $G(t, s, \varphi)$ Green–Samoilenko function of the system

$$\begin{aligned} \frac{d\varphi}{dt} &= a(t, \varphi), \quad \frac{dx}{dt} = P(t, \varphi)x, \quad t \neq \tau_i, \\ \Delta x|_{t=\tau_i} &= B_i(\varphi)x, \end{aligned}$$

if there exists $K > 0$ such that for all $t, s \in R$, $\varphi \in \mathfrak{S}^m$

$$\int_{-\infty}^{\infty} \|G(t, s, \varphi)\| ds + \sum_{i=-\infty}^{+\infty} \|G(t, \tau_i + 0, \varphi)\| \leq K. \tag{8}$$

Next, we recall the basic properties of Green–Samoilenko function $G(t, s, \varphi)$. From its definition it follows that Green–Samoilenko function is continuous for all $t, s \in R$, $t \neq s$, $\varphi \in \mathfrak{S}^m$, 2π -periodic with respect to φ_ν , $\nu = \overline{1, m}$, and

$$G(s + 0, s, \varphi) - G(s - 0, s, \varphi) = E.$$

Taking the above lemma into account, we get

$$G(t, s, \varphi_t(\tau, \varphi)) = \begin{cases} \Omega_s^t(t, \varphi)C(s, \varphi_s(\tau, \varphi)), & s \leq t, \\ -\Omega_s^t(t, \varphi)[E - C(s, \varphi_s(\tau, \varphi))], & s > t. \end{cases} \tag{9}$$

For $s = \tau$, we obtain

$$G(t, \tau, \varphi_t(\tau, \varphi)) = \begin{cases} \Omega_\tau^t(t, \varphi)C(\tau, \varphi), & \tau \leq t, \\ -\Omega_\tau^t(t, \varphi)[E - C(\tau, \varphi)], & \tau > t. \end{cases}$$

Matrix $G(t, \tau, \varphi_t(\tau, \varphi))$ consists from solutions to the homogeneous system (6) for $t \geq \tau$ and $t < \tau$, respectively.

Consider the relation

$$\int_{-\infty}^{+\infty} G(t, s, \varphi)f(s, \varphi_s(t, \varphi)) ds + \sum_{i=-\infty}^{+\infty} G(t, \tau_i + 0, \varphi)I_i(\varphi_{\tau_i}(t, \varphi)).$$

From (2) and (8) we get

$$\begin{aligned} & \left\| \int_{-\infty}^{+\infty} G(t, s, \varphi) f(s, \varphi_s(t, \varphi)) ds + \sum_{i=-\infty}^{+\infty} G(t, \tau_i + 0, \varphi) I_i(\varphi_{\tau_i}(t, \varphi)) \right\| \\ & \leq \frac{2K}{\gamma} \sup_{t \in R} \max_{\varphi \in \mathfrak{S}_m} \|f(t, \varphi)\| + \frac{2K}{1 - e^{-\gamma\theta}} \sup_{i \in Z} \max_{\varphi \in \mathfrak{S}_m} \|I_i(\varphi)\|. \end{aligned}$$

Finally denote

$$u(t, \varphi) = \int_{-\infty}^{+\infty} G(t, s, \varphi) f(s, \varphi_s(t, \varphi)) ds + \sum_{i=-\infty}^{+\infty} G(t, \tau_i + 0, \varphi) I_i(\varphi_{\tau_i}(t, \varphi)). \quad (10)$$

Theorem 1. *Let functions $a(t, \varphi)$, $f(t, \varphi)$, $P(t, \varphi)$ from system (1) be continuous with respect to t , continuous and 2π -periodic with respect to φ_ν , $\nu = \overline{1, m}$, bounded for all $t \in R$, $\varphi \in \mathfrak{S}^m$ vector and matrix functions, respectively. Let function $a(t, \varphi)$ satisfy condition (3), functions $B_i(\varphi)$ and $I_i(\varphi)$ be uniformly bounded with respect to i matrices and vectors, $\det(E + B_i(\varphi)) \neq 0$ for any $\varphi \in \mathfrak{S}^m$. Let for the sequence of impulsive perturbations $\{\tau_i\}$ estimate (2) hold. Let also there exist Green–Samoilenko function $G(t, s, \varphi)$. Then formula (10) defines an integral set of system (1) and*

$$\sup_{t \in R} \max_{\varphi \in \mathfrak{S}_m} \|u(t, \varphi)\| \leq \frac{2K}{\gamma} \sup_{t \in R} \max_{\varphi \in \mathfrak{S}_m} \|f(t, \varphi)\| + \frac{2K}{1 - e^{-\gamma\theta}} \sup_{i \in Z} \max_{\varphi \in \mathfrak{S}_m} \|I_i(\varphi)\|. \quad (11)$$

Now assume that the fundamental matrix $\Omega_s^t(\tau, \varphi)$ of system (6) satisfies the estimate

$$\|\Omega_s^t(\tau, \varphi)\| \leq K e^{-\gamma(t-s)} \quad (12)$$

for any $t \geq s \in R$, $\tau \in R$, $\varphi \in \mathfrak{S}^m$ and some $K \geq 1$, $\gamma > 0$. In this case there exists Green–Samoilenko function of the following form

$$G(t, s, \varphi) = \begin{cases} \Omega_s^t(t, \varphi), & s < t, \\ 0, & s \geq t. \end{cases} \quad (13)$$

The corresponding integral set of system (1) gets the representation

$$x = u(t, \varphi) = \int_{-\infty}^t G(t, s, \varphi) f(s, \varphi_s(t, \varphi)) ds + \sum_{\tau_i < t} G(t, \tau_i + 0, \varphi) I_i(\varphi_{\tau_i}(t, \varphi)), \quad t \in R, \quad \varphi \in \mathfrak{S}^m. \quad (14)$$

Theorem 2. *Let system (1) satisfy the condition of Theorem 1. Let also the fundamental matrix $\Omega_s^t(\tau, \varphi)$ of system (6) satisfy inequality (12). Then system (1) has an asymptotically stable integral set (14) and this set satisfies the following estimate*

$$\sup_{t \in R} \max_{\varphi \in \mathfrak{S}_m} \|u(t, \varphi)\| \leq K_0 \left[\sup_{t \in R} \max_{\varphi \in \mathfrak{S}_m} \|f(t, \varphi)\| + \sup_{i \in Z} \max_{\varphi \in \mathfrak{S}_m} \|I_i(\varphi)\| \right],$$

where

$$K_0 = \frac{K}{\gamma} + K \sup_{t \in R} \sum_{\tau_i < t} e^{-\gamma(t-\tau_i)}.$$

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