

The Nonlinear Kneser Problem for Singular in Phase Variables Two-Dimensional Differential Systems

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Let $a > 0$, $\mathbb{R}_- =] - \infty, 0]$, $\mathbb{R}_+ = [0, +\infty[$, and $\mathbb{R}_{0+} =]0, +\infty[$. On a positive semi-axis \mathbb{R}_{0+} , we consider the differential system

$$\frac{du_i}{dt} = f_i(t, u_1, u_2) \quad (i = 1, 2) \tag{1}$$

with the boundary condition

$$\varphi(u_1) = c, \tag{2}$$

where c is a positive constant, $f_i : \mathbb{R}_{0+} \times \mathbb{R}_{0+}^2 \rightarrow \mathbb{R}_-$ ($i = 1, 2$) are continuous functions, and $\varphi : C([0, a]; \mathbb{R}_+) \rightarrow \mathbb{R}_+$ is a continuous nondecreasing functional.

A continuously differentiable vector function $(u_1, u_2) : \mathbb{R}_{0+} \rightarrow \mathbb{R}_{0+}^2$, satisfying system (1) in \mathbb{R}_{0+} , is said to be a **positive solution** of that system.

If the component u_i of a positive solution (u_1, u_2) at the point 0 has the right-hand limit

$$u_i(0+) = \lim_{t>0, t \rightarrow 0} u_i(t),$$

then we put $u_i(0) = u_i(0+)$.

A positive solution (u_1, u_2) of system (1) is said to be a **positive solution of problem (1), (2)** if there exists $u_1(0+)$ and equality (2) is satisfied.

A positive solution (u_1, u_2) of system (1) is said to be a **vanishing at infinity positive solution** if

$$\lim_{t \rightarrow +\infty} u_i(t) = 0 \quad (i = 1, 2).$$

If

$$f_1(t, x, y) \equiv -y, \quad f_2(t, x, y) \equiv -f(t, x, -y),$$

then the differential system (1) is equivalent to the differential equation

$$u'' = f(t, u, u'), \tag{3}$$

and condition (2) is equivalent to the condition

$$\varphi(u) = c, \tag{4}$$

respectively. Consequently, problem (1), (2) has a positive solution if and only if problem (3), (4) has a so-called Kneser solution, i.e. a solution satisfying the inequalities

$$u(t) > 0, \quad u'(t) < 0 \quad \text{for } t \in \mathbb{R}_{0+}.$$

Problem (1), (2), as problem (3), (4), is said to be the nonlinear Kneser problem. These problems are investigated in detail in the case where the functions f_i ($i = 1, 2$) and f have no singularities in phase variables (see, e.g., [1–6], and the references therein).

In [7], for the singular in a phase variable equation (3), sufficient conditions for the existence of a Kneser solution satisfying the condition (4) are established. Theorems below are generalizations of the above mentioned results for system (1).

Below everywhere it is assumed that the functions f_i ($i = 1, 2$) on the set $\mathbb{R}_{0+} \times \mathbb{R}_{0+}^2$ admit the estimates

$$\begin{aligned} g_{10}(t) &\leq -x^{\lambda_1} y^{-\mu_1} f_1(t, x, y) \leq g_1(t), \\ g_{20}(t) &\leq -x^{\lambda_2} y^{-\mu_2} f_2(t, x, y) \leq g_2(t), \end{aligned}$$

where λ_i and μ_i ($i = 1, 2$) are nonnegative constants, and $g_{i0} : \mathbb{R}_{0+} \rightarrow \mathbb{R}_{0+}$, $g_i : \mathbb{R}_{0+} \rightarrow \mathbb{R}_{0+}$ ($i = 1, 2$) are continuous functions. If $\lambda_i > 0$ for some $i \in \{1, 2\}$, then

$$\lim_{x \rightarrow 0} f_i(t, x, y) = +\infty \text{ for } t > 0, y > 0.$$

And if $\mu_2 > 0$, then

$$\lim_{y \rightarrow 0} f_2(t, x, y) = +\infty \text{ for } t > 0, x > 0.$$

Consequently, in both cases system (1) has the singularity in at least one phase variable.

We use the following notation and definitions.

$$\nu_0 = \frac{\mu_1}{1 + \mu_2}, \quad \nu = 1 + \lambda_1 + \lambda_2 \nu_0.$$

$C([0, a]; \mathbb{R})$ is the Banach space of continuous functions $u : [0, a] \rightarrow \mathbb{R}$ with the norm

$$\|u\|_C = \max \{|u(t)| : 0 \leq t \leq a\},$$

$C([0, a]; \mathbb{R}_+) = \{u \in C([0, a]; \mathbb{R}) : u(t) \geq 0 \text{ for } 0 \leq t \leq a\}$.

A functional $\varphi : C([0, a]; \mathbb{R}_+) \rightarrow \mathbb{R}_+$ is said to be **nondecreasing** if for any $u \in C([0, a]; \mathbb{R}_+)$ and $u_0 \in C([0, a]; \mathbb{R}_+)$ the inequality

$$\varphi(u + u_0) \geq \varphi(u)$$

holds.

Theorem 1. *If*

$$\int_t^{+\infty} g_{20}(s) ds < +\infty, \quad w_0(t) \equiv \int_t^{+\infty} g_{10}(s) \left(\int_s^{+\infty} g_{20}(\tau) d\tau \right)^{\nu_0} ds < +\infty \text{ for } t > 0,$$

and

$$w(t) \equiv \int_t^{+\infty} w_0^{-\frac{\lambda_2}{\nu}}(s) g_2(s) ds < +\infty, \quad \int_t^{+\infty} g_1(s) w^{\nu_0}(s) ds < +\infty \text{ for } t > 0,$$

then system (1) has at least one vanishing at infinity positive solution.

Corollary 1. *Let*

$$\liminf_{t \rightarrow +\infty} (t^{1-\alpha} g_{10}(t)) > 0, \quad \limsup_{t \rightarrow +\infty} (t^{1-\alpha} g_1(t)) < +\infty, \tag{5}$$

$$\liminf_{t \rightarrow +\infty} (t^\beta g_{20}(t)) > 0, \quad \limsup_{t \rightarrow +\infty} (t^\beta g_2(t)) < +\infty, \tag{6}$$

where α and β are nonnegative constants. Then for the existence of at least one vanishing at infinity positive solution of system (1) it is necessary and sufficient that

$$\beta > \frac{1 + \mu_2}{\mu_1} \alpha + 1.$$

If

$$\int_t^{+\infty} g_2(s) ds < +\infty \text{ for } t > 0, \quad \int_0^{+\infty} g_1(s) \left(\int_s^{+\infty} g_2(\tau) d\tau \right) ds < +\infty, \quad (7)$$

then on the set $\mathbb{R}_+ \times \mathbb{R}_{0+}$ we put

$$v_0(t, x) = \left[x^\nu + \nu(1 + \mu_2)^{\nu_0} \int_t^{+\infty} g_{10}(s) \left(\int_s^{+\infty} g_{20}(\tau) d\tau \right)^{\nu_0} ds \right]^{\frac{1}{\nu}},$$

$$v_1(t, x) = \left[x^{1+\lambda_1} + (1 + \lambda_1) \int_t^{+\infty} \nu^{\mu_1}(s, x) g_1(s) ds \right]^{\frac{1}{1+\lambda_1}},$$

where

$$v(t, x) = \left[(1 + \mu_2) \int_t^{+\infty} \nu_0^{-\lambda_2}(s, x) g_2(s) ds \right]^{\frac{1}{1+\mu_2}} \text{ for } t > 0, \quad x > 0.$$

Theorem 2. *Let either*

$$\int_t^{+\infty} g_{10}(s) ds = +\infty \text{ for } t > 0,$$

or

$$\int_t^{+\infty} g_{20}(s) ds < +\infty \text{ for } t > 0, \quad \int_0^{+\infty} g_{10}(s) \left(\int_s^{+\infty} g_{20}(\tau) d\tau \right)^{\nu_0} ds < +\infty$$

and

$$\varphi(v_0(\cdot; 0)) > c.$$

Then problem (1), (2) has no solution.

Theorem 3. *Let along with (7) the conditions*

$$\lim_{x \rightarrow +\infty} \varphi(x) = +\infty$$

and

$$\inf \{ \varphi(v_1(\cdot; x)) : x > 0 \} < c$$

be satisfied. Then problem (1), (2) has at least one positive solution.

Theorems 2 and 3 yield the following propositions.

Corollary 2. *Let*

$$\int_{t_0}^{+\infty} g_{10}(s) ds = +\infty,$$

where $t_0 > 0$. Then for the existence of at least one positive solution of problem (1), (2) for every sufficiently large c , it is necessary and sufficient that

$$\int_t^{+\infty} g_{20}(s) ds < +\infty \text{ for } t > 0, \quad \int_0^{+\infty} g_{10}(s) \left(\int_s^{+\infty} g_{20}(\tau) d\tau \right)^{\nu_0} ds < +\infty.$$

Corollary 3. *Let conditions (5) and (6) hold, where α and β are nonnegative constants. Then for the existence of at least one positive solution of problem (1), (2) for every sufficiently large c , it is necessary and sufficient that*

$$\beta > \frac{1 + \mu_2}{\mu_1} \alpha + 1.$$

Finally we note that the proofs of the above formulated theorems are based on the results of [8].

Acknowledgement

This work was supported by the Shota Rustaveli National Science Foundation (Project # FR/317/5-101/12).

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