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**ON NONLINEAR HYPERBOLIC EQUATIONS
WITH GENERAL SOLUTIONS REPRESENTABLE
BY SUPERPOSITION OF ARBITRARY FUNCTIONS**

On a plane of variables x, t we consider a class of quasi-linear non-strictly hyperbolic equations of the second order. It is assumed that differential relations of characteristic directions are both completely integrable and define a pair of smooth invariants $\mu = \mu(x, t)$, $\lambda = \lambda(x, t, u)$. The invariant λ , which depends on an unknown solution $u(x, t)$, has its inverse $u = \Lambda(x, t, \lambda)$. Depending on the right side, a function $h \in C^2(R^3)$ in a number of cases is defined, allowing one to obtain an explicit representation of the general integral $\lambda(x, t, u) = f[h(x, t, g(\mu))]$ of the equation under consideration. Under our assumptions, this results in the explicit general solution

$$u(x, t) = \Lambda\{f[h(x, t, g(\mu))]\} \quad (1)$$

in the form of a complicated superposition of arbitrary functions $f, g \in C^2(R^1)$. As an illustration, we have considered a number of examples, the simplest of which is of the form

$$(1 + u_t)u_{xx} + (1 - u_x + u_t)u_{xt} - u_x u_{tt} = 0 \quad (2)$$

with the characteristic invariants $\lambda = u + y$, $\mu = x - y$ and with the general solution

$$u(x, t) = f[x + g(x - y)] - y \quad (3)$$

for arbitrary functions f, g ; the smoothness of these functions defines that of the solution. As is seen, equation (2) belongs to a class whose general integrals are linear with respect to arbitrary functions of the invariants λ, μ . In the presence of the general solution (1), the D'Alembert method is used for the investigation of nonlinear hyperbolic problems and, as a result, not only solutions, but also the domains of their definition are established.